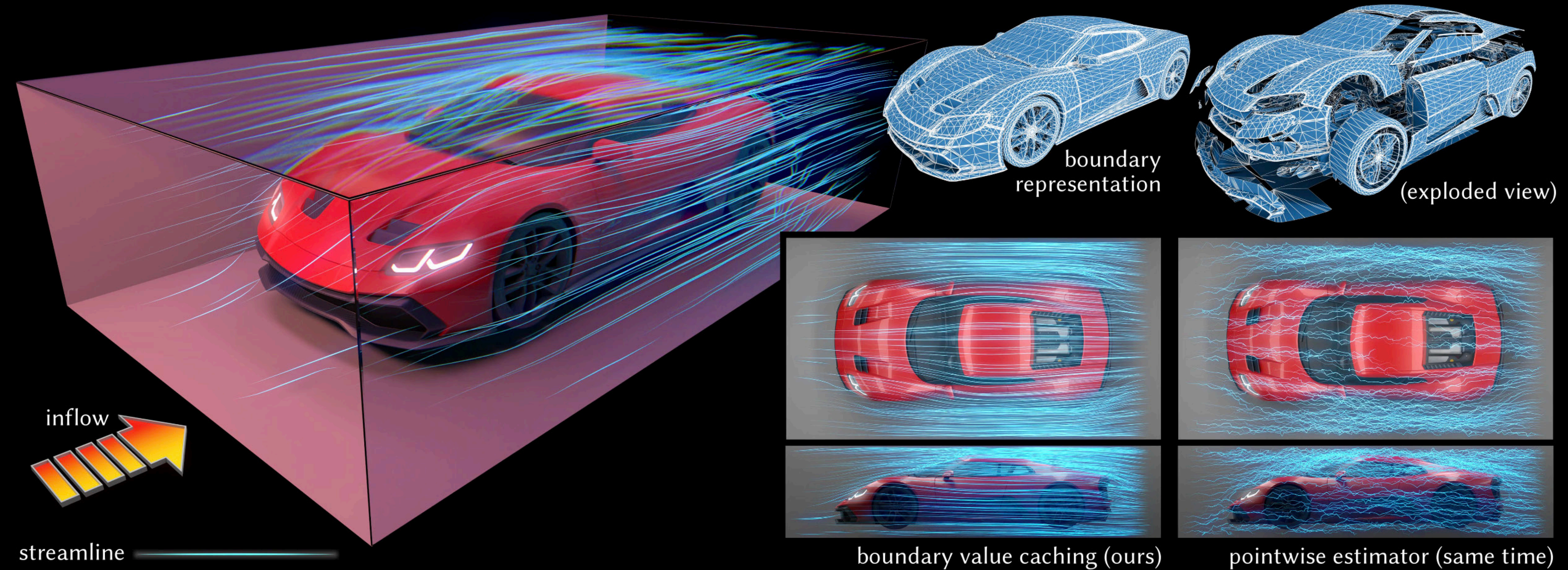


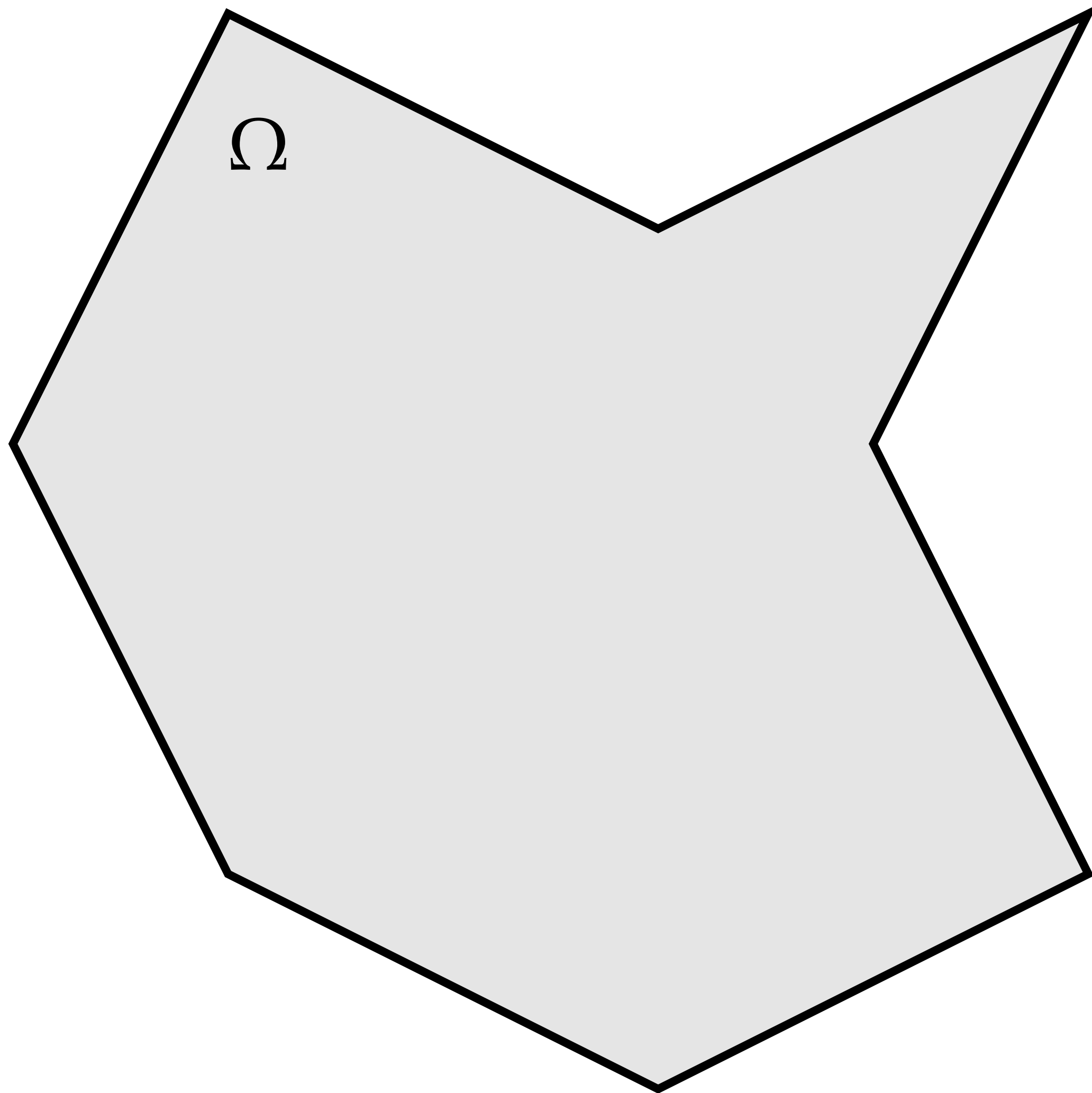
# Boundary Value Caching for Walk on Spheres



Bailey Miller\*, Rohan Sawhney\*, Keenan Cranet†, and Ioannis Gkioulekast†

# Grid-Free Monte Carlo PDE Solvers

Walk on Spheres avoids **meshing** or **global solves**!



**Poisson equation**

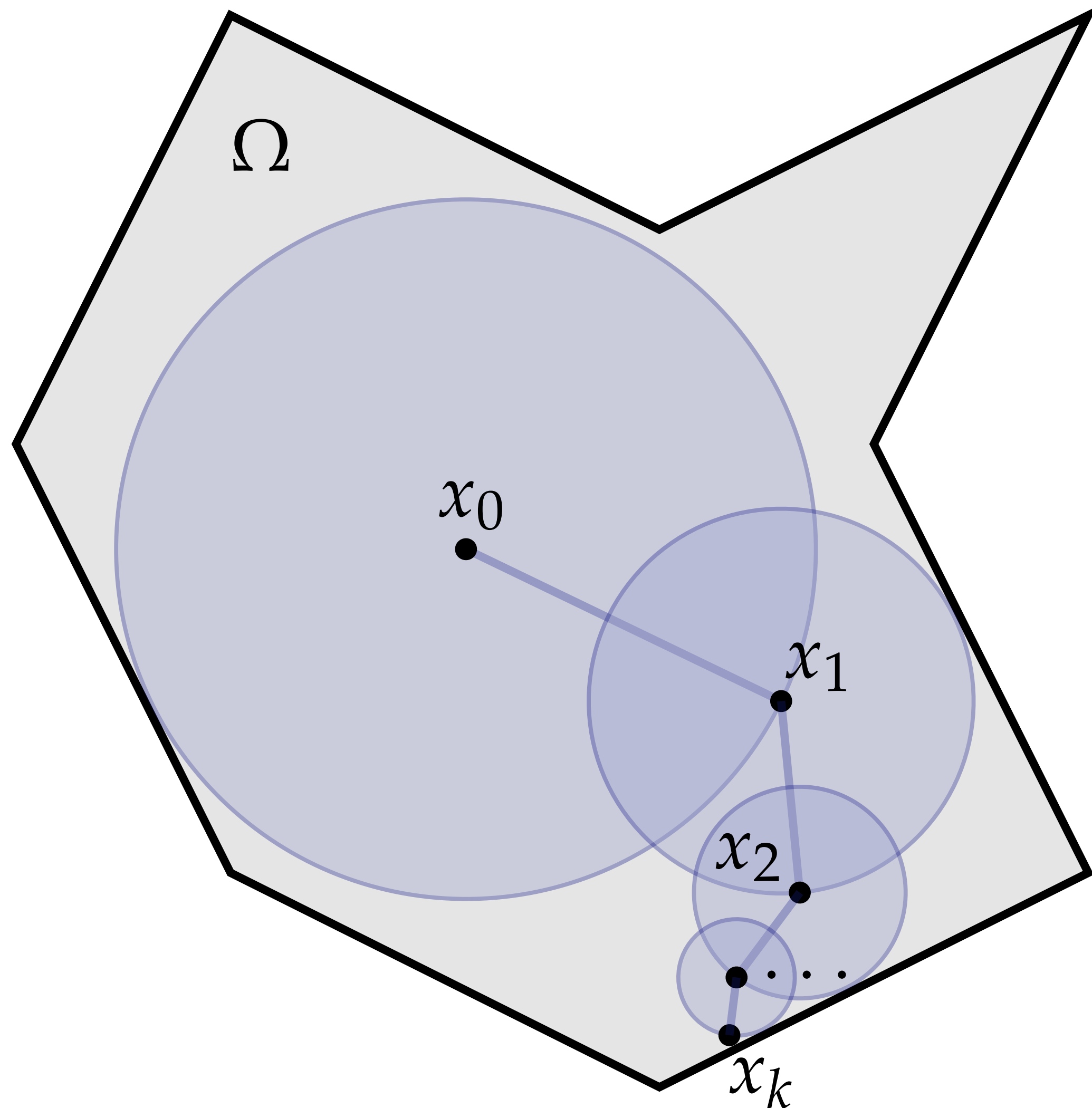
$$\Delta u = f \quad \text{on } \Omega$$

$$u = g \quad \text{on } \partial\Omega_D$$

$$\frac{\partial u}{\partial n} = h \quad \text{on } \partial\Omega_N$$

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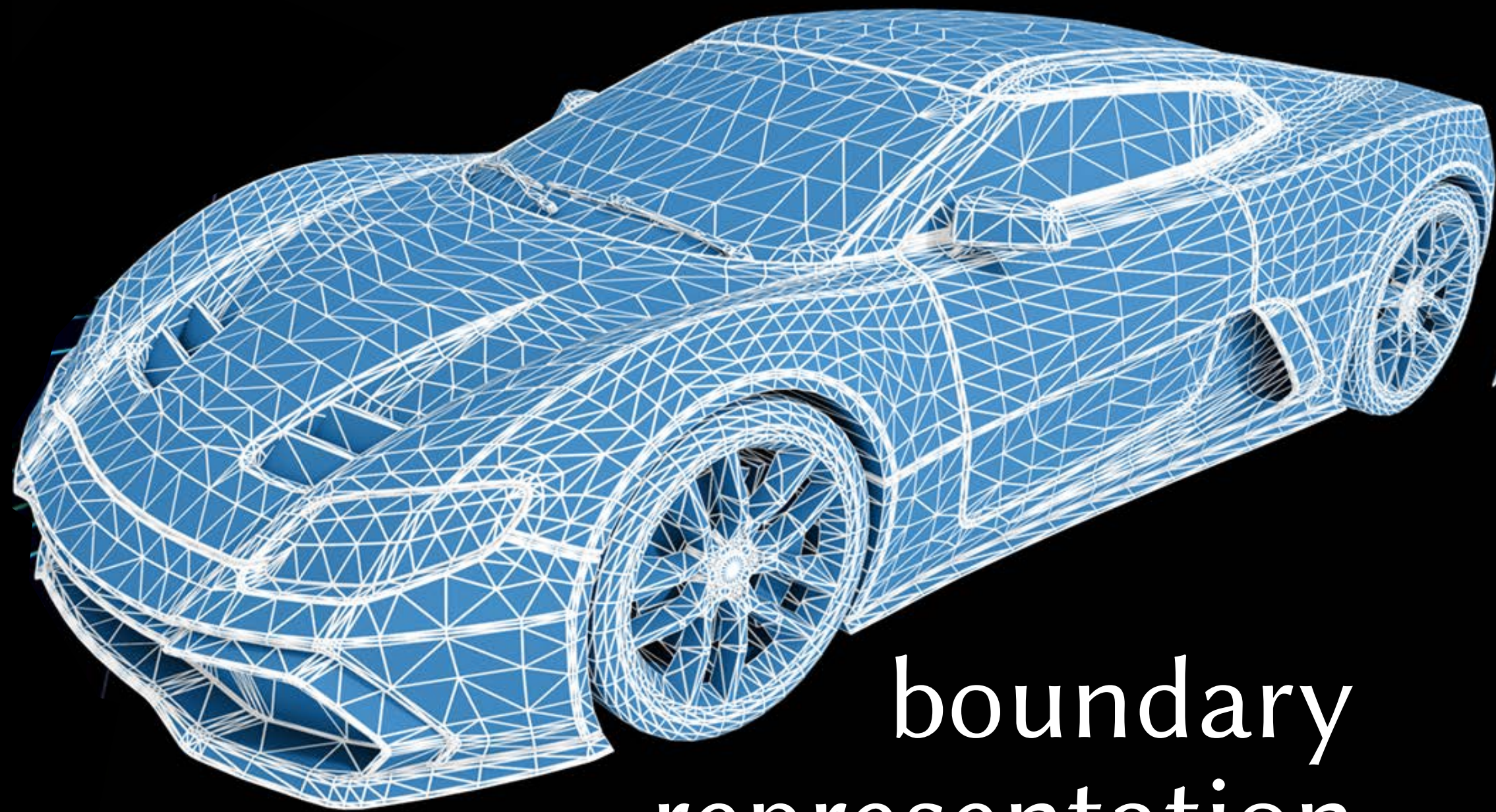
**Poisson equation**

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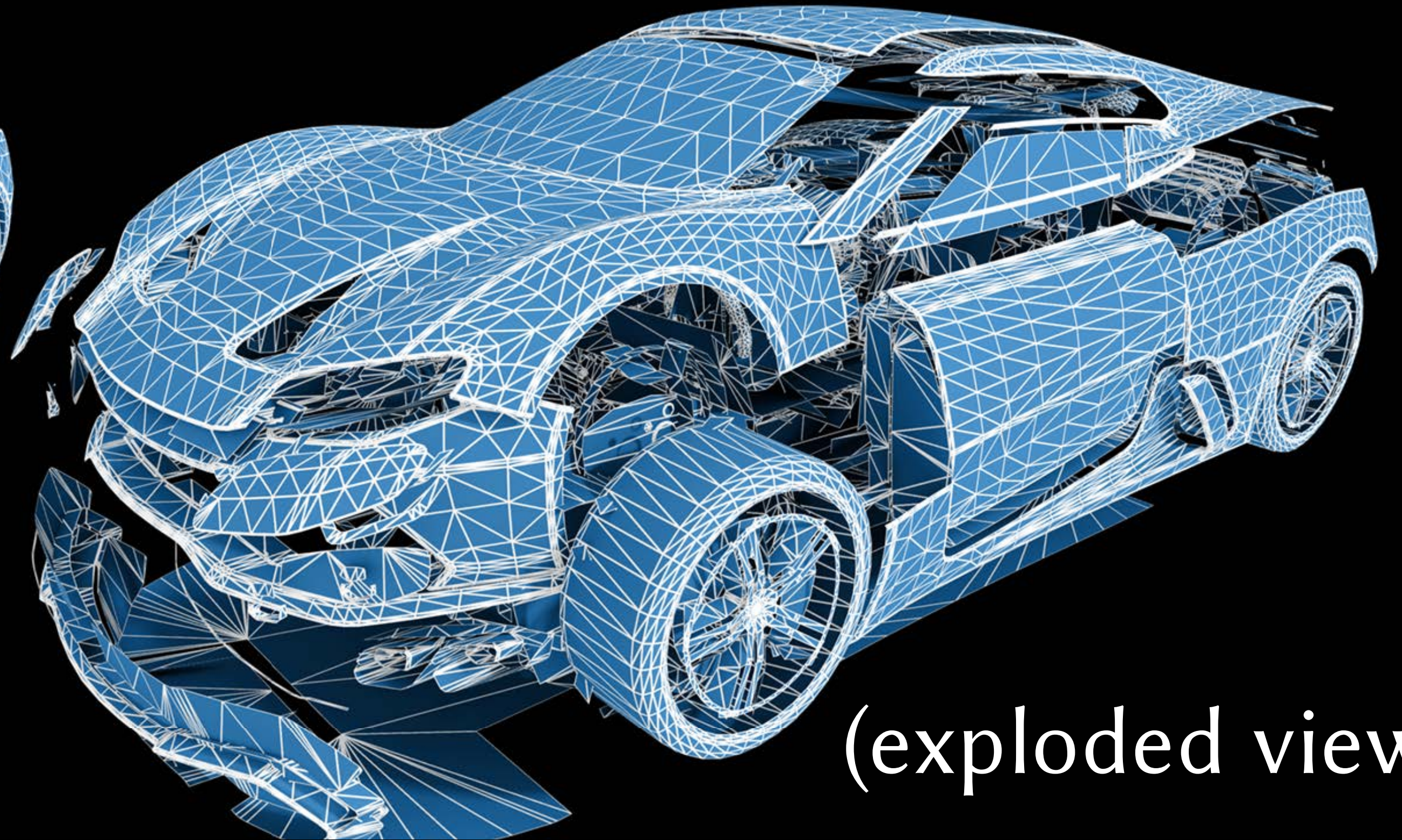
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# Robustly handle meshes intended for visualization

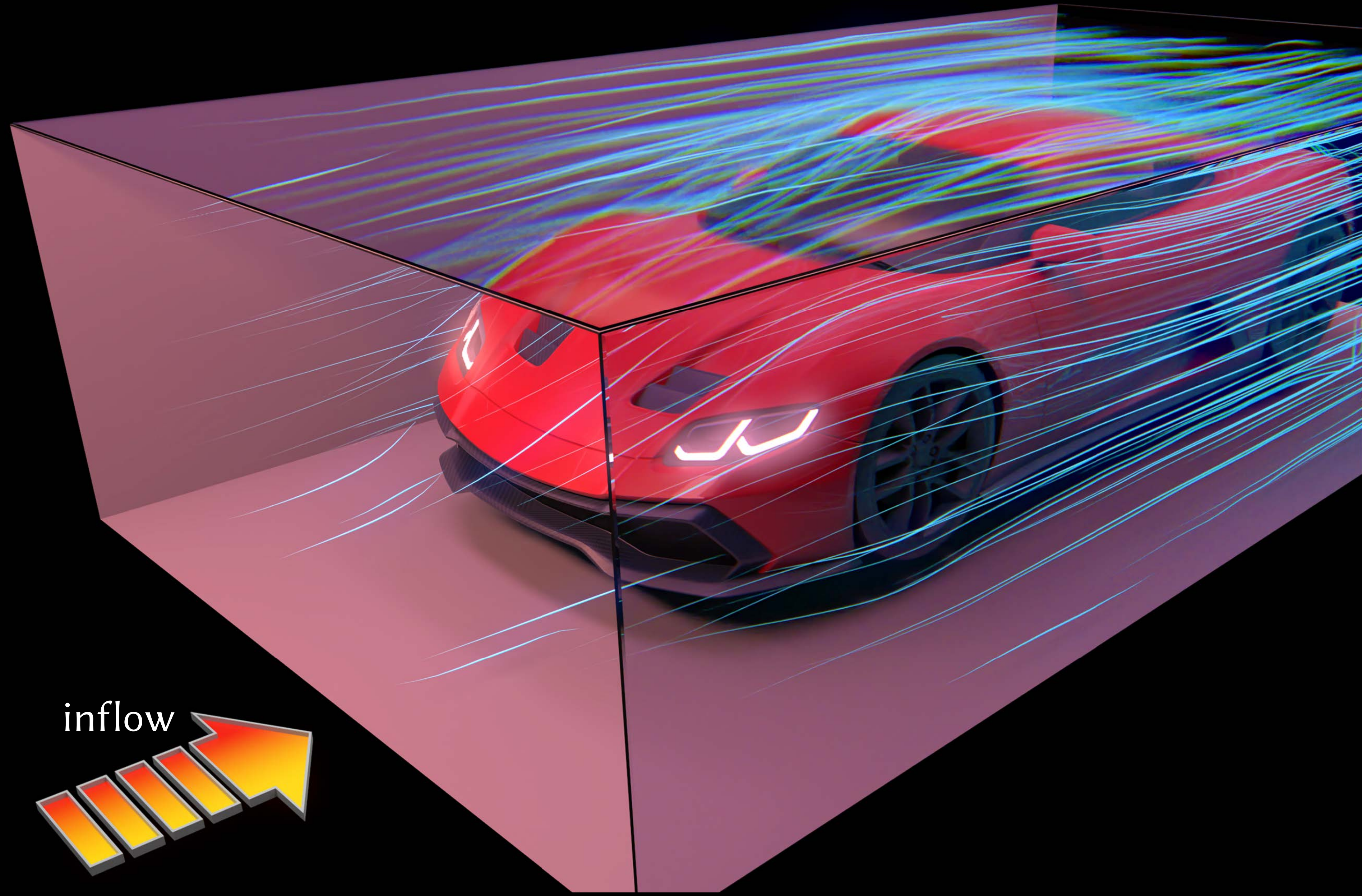


boundary  
representation

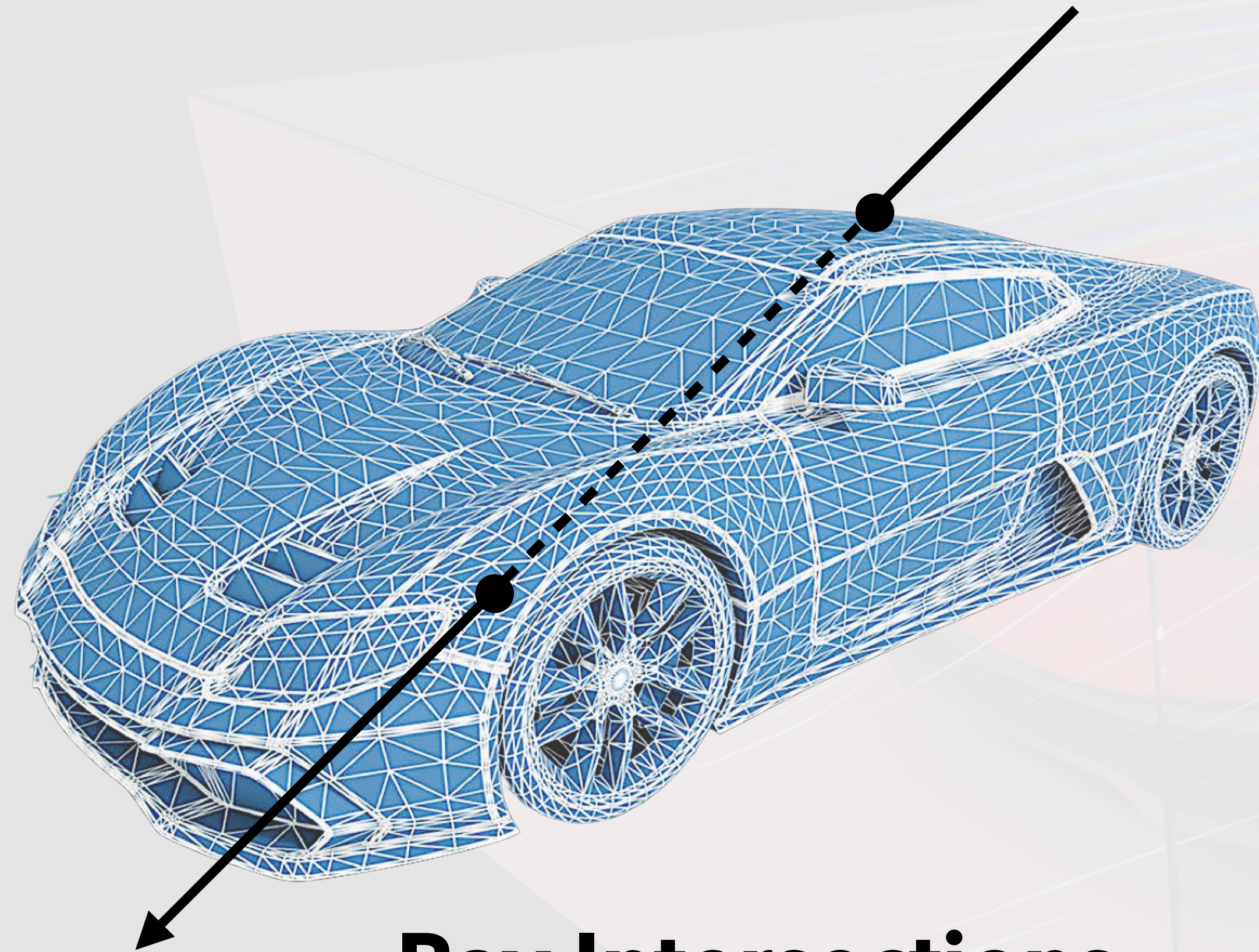


(exploded view)

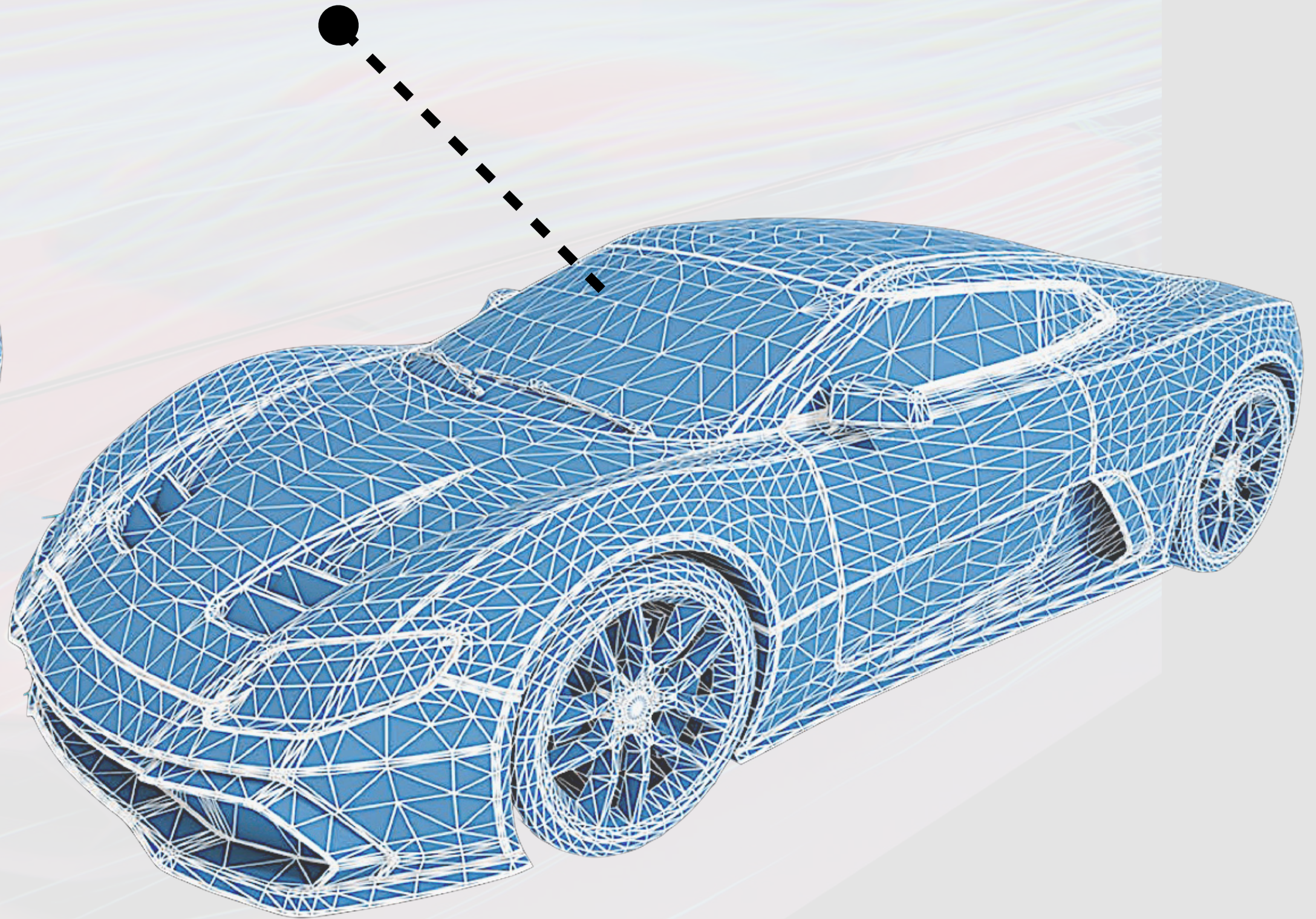
# Potential Flow Simulation



# Potential Flow Simulation

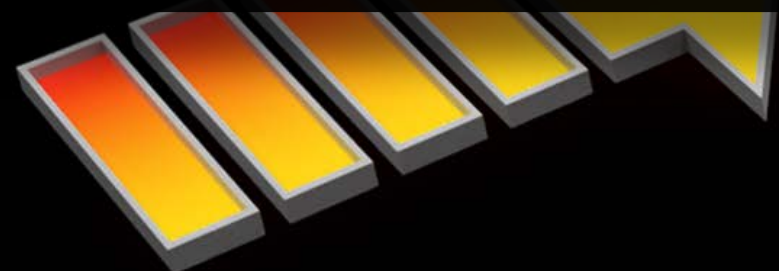


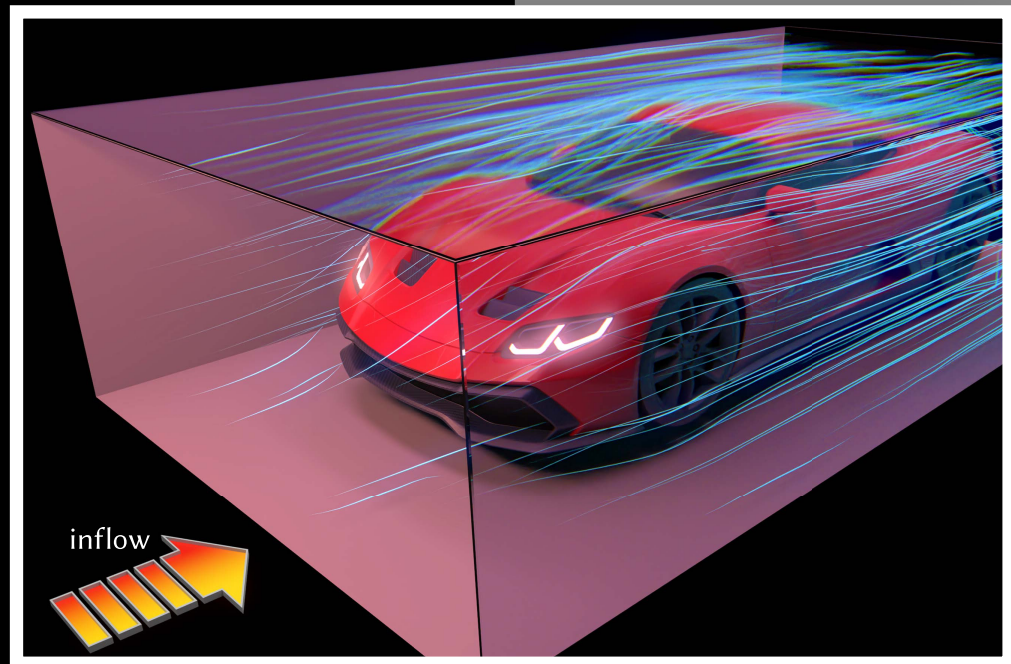
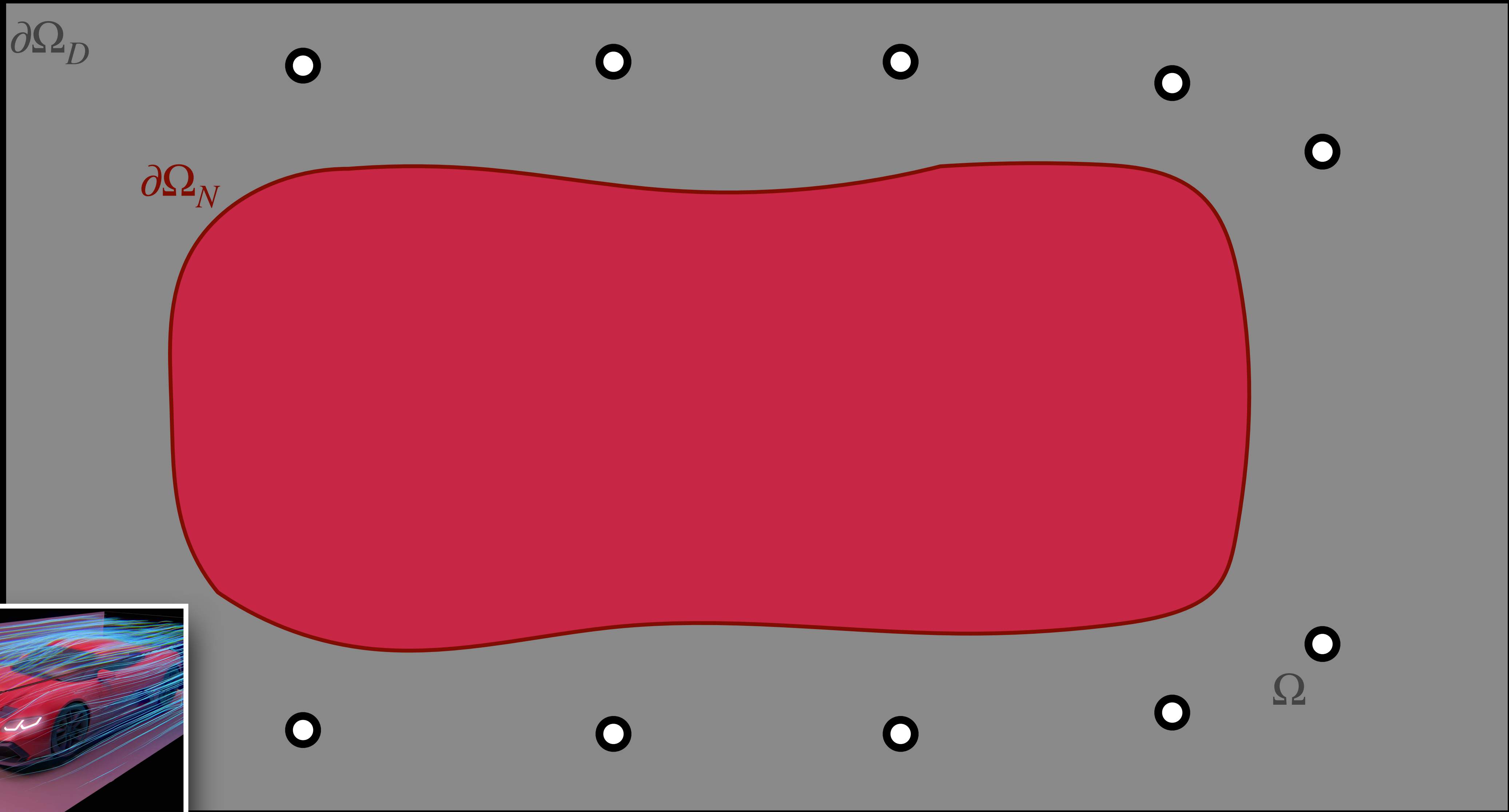
**Ray Intersections**



**Closest Point Queries**

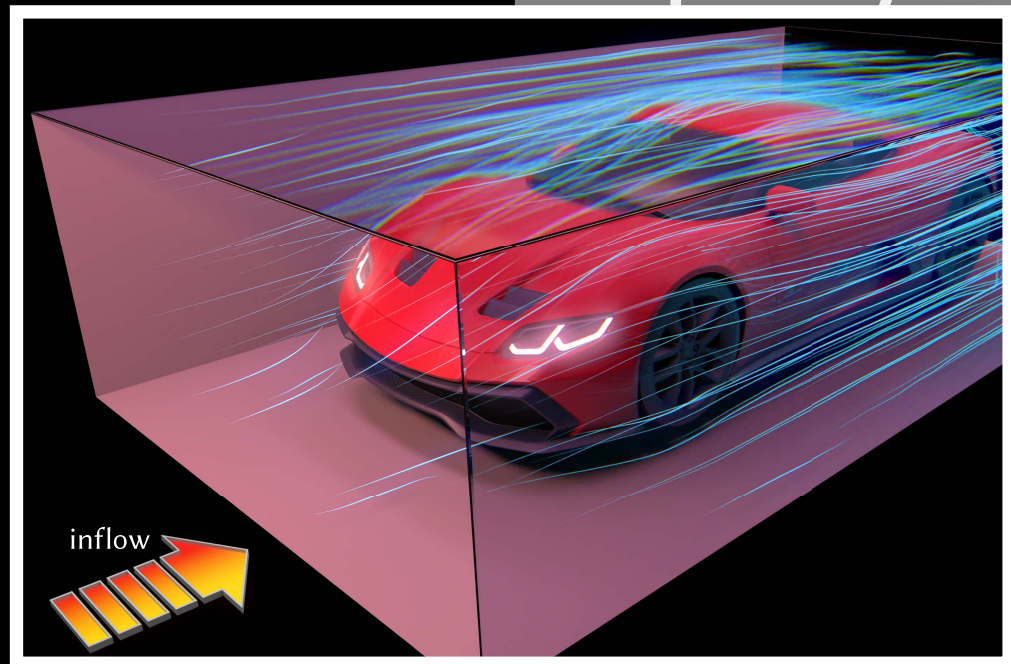
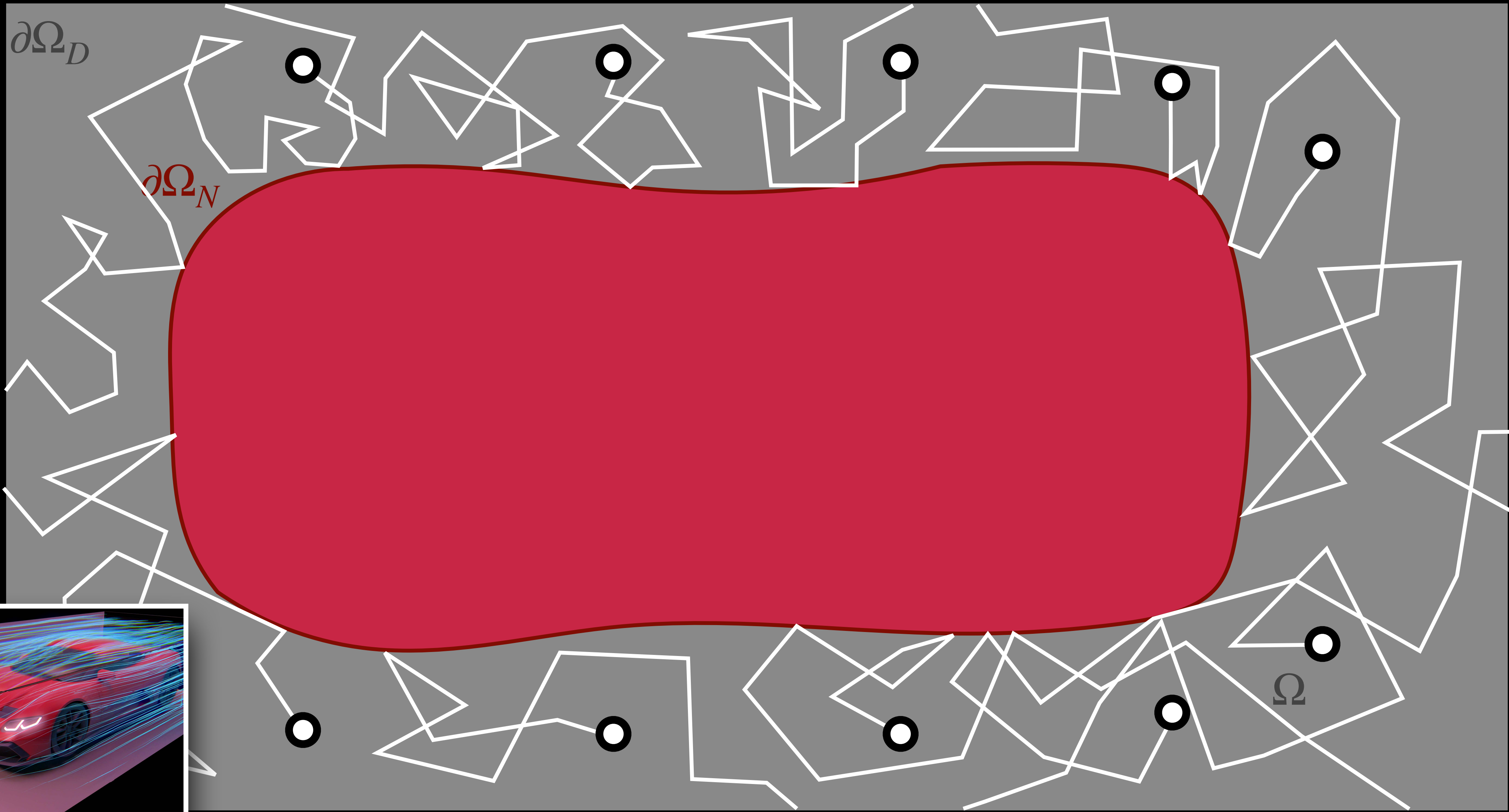
inflow





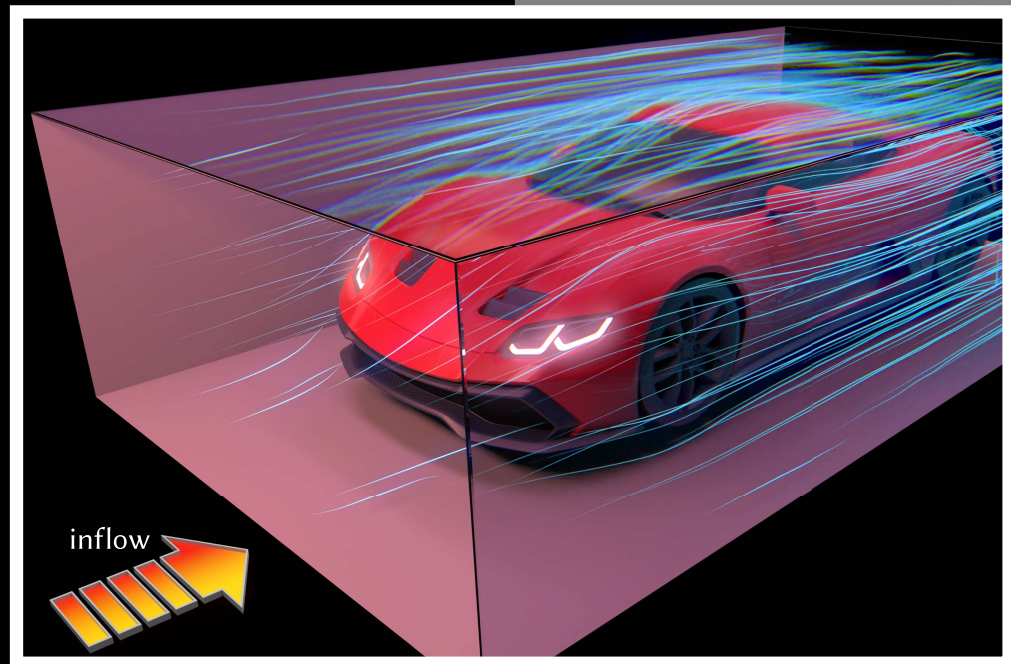
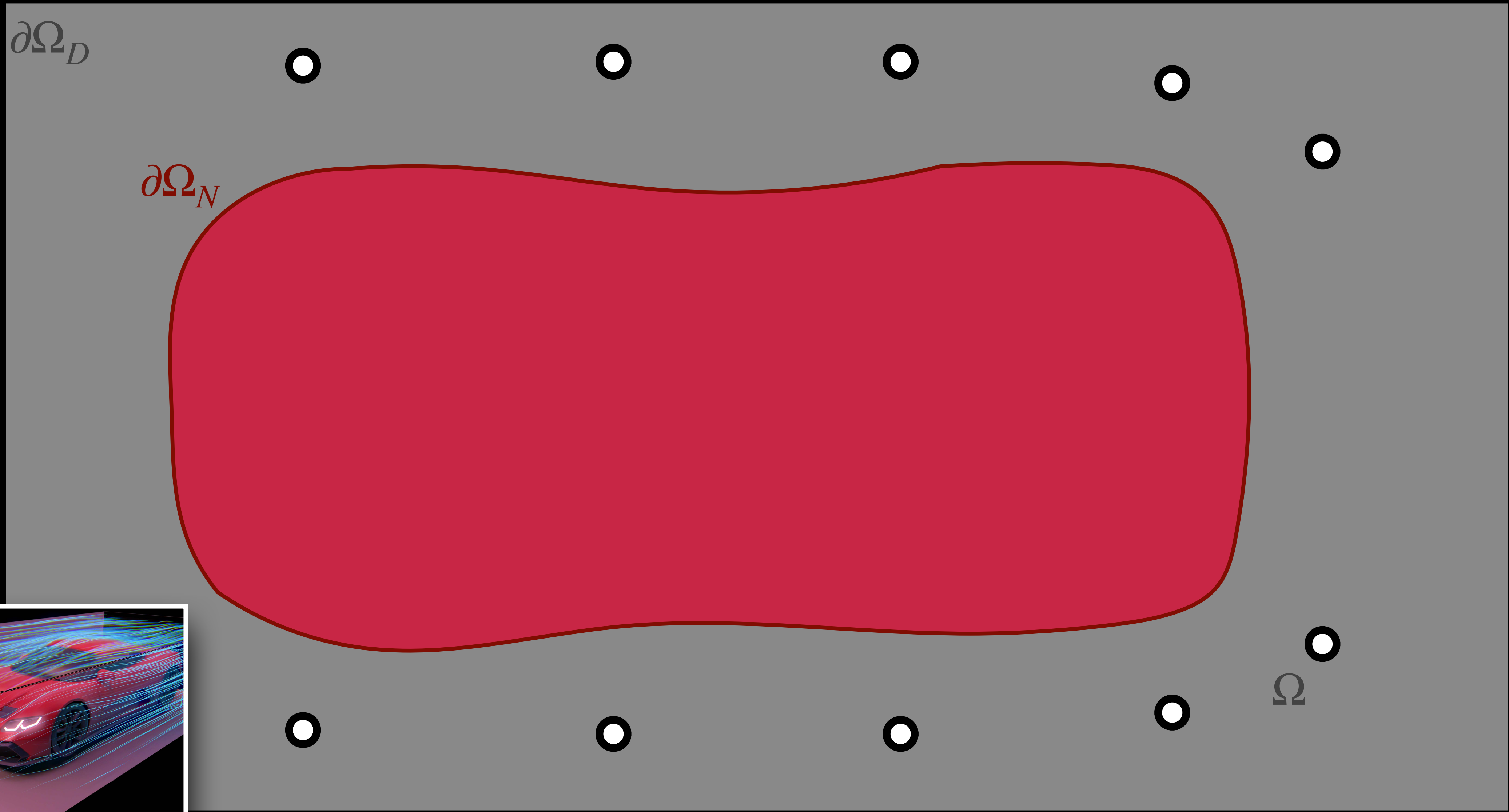
wind tunnel

pointwise estimator



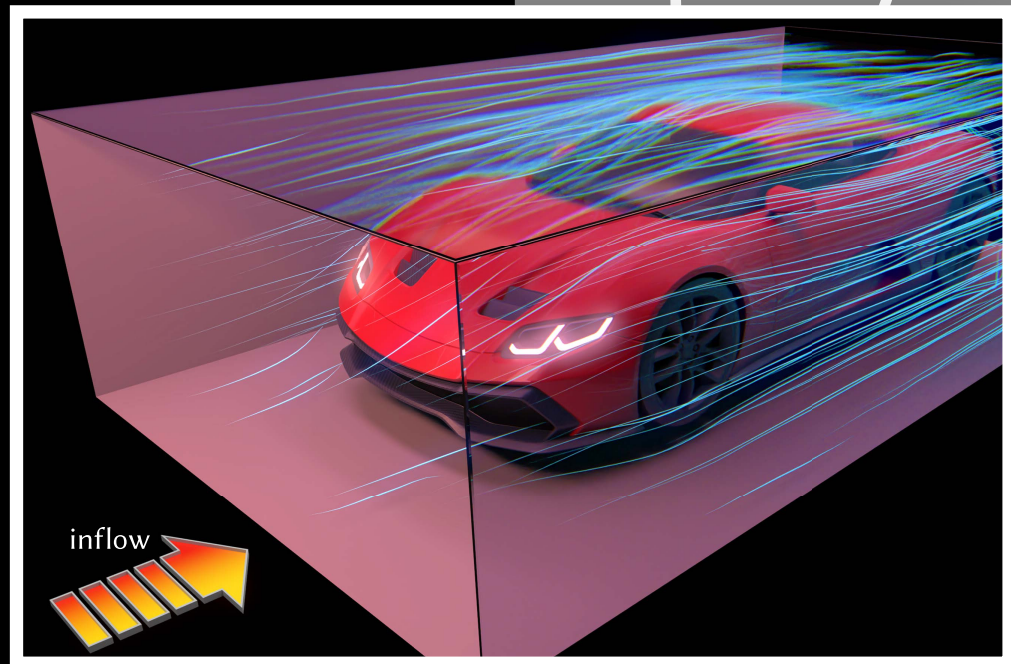
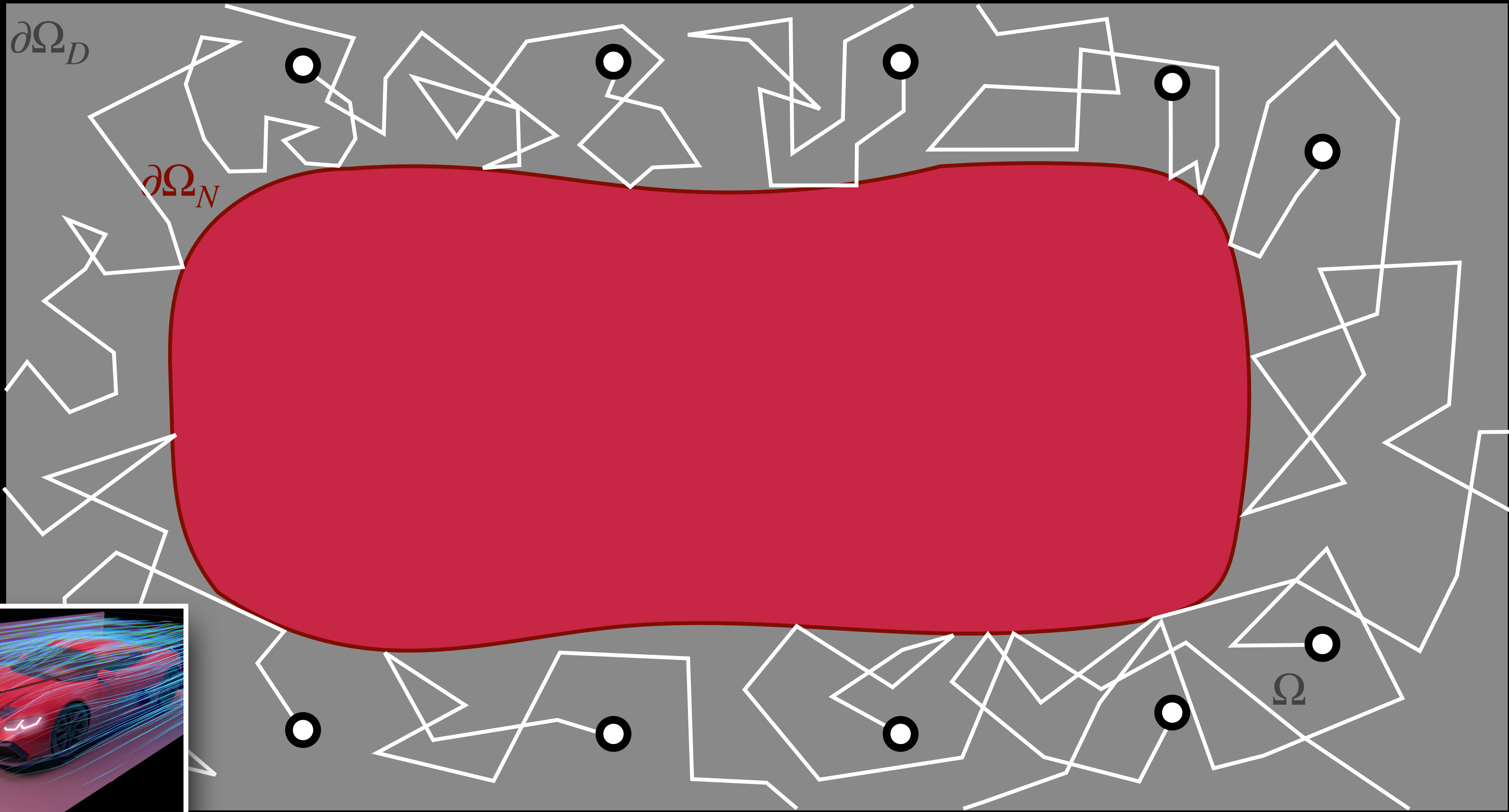
pointwise estimator





wind tunnel

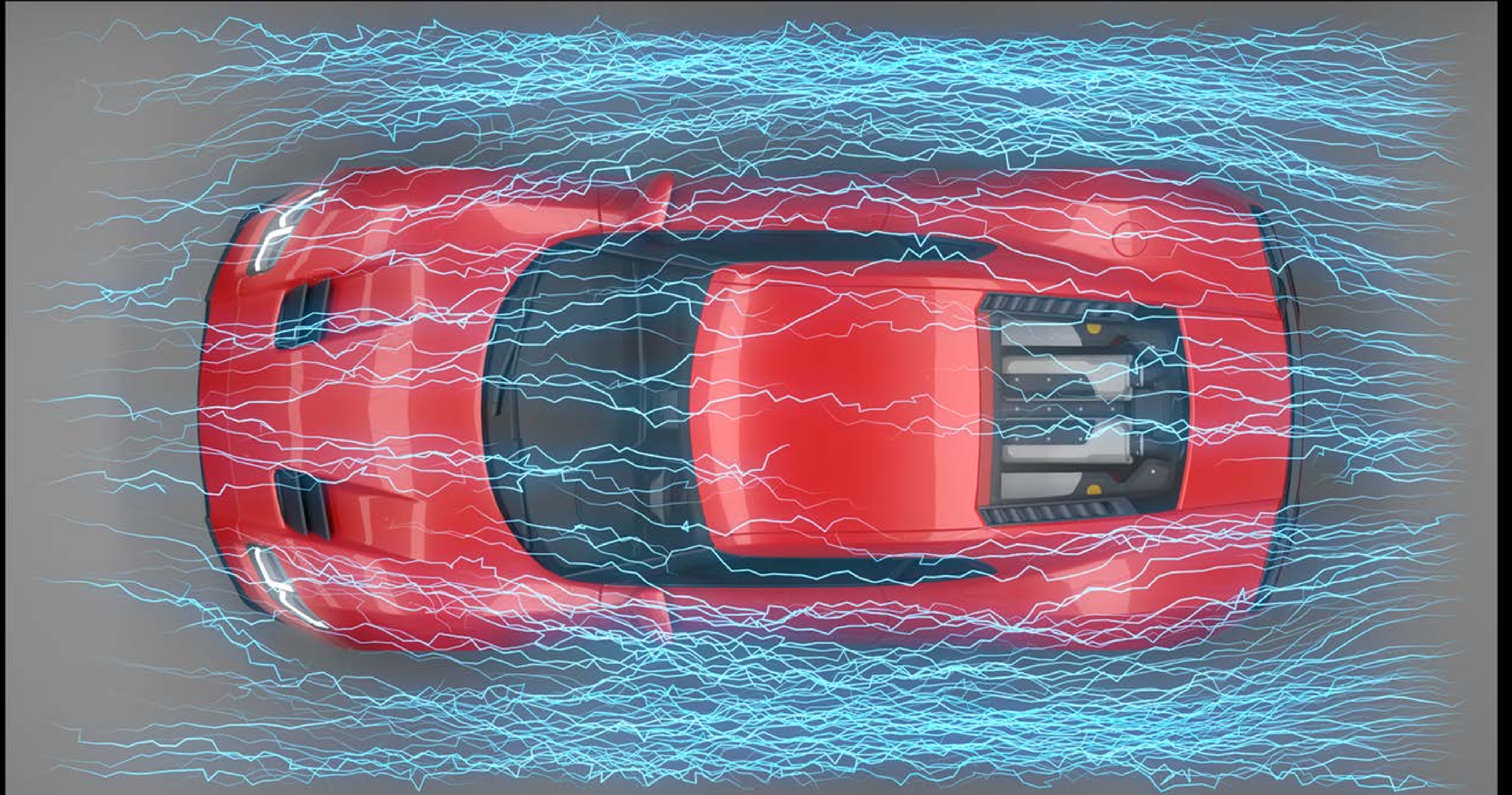
pointwise estimator



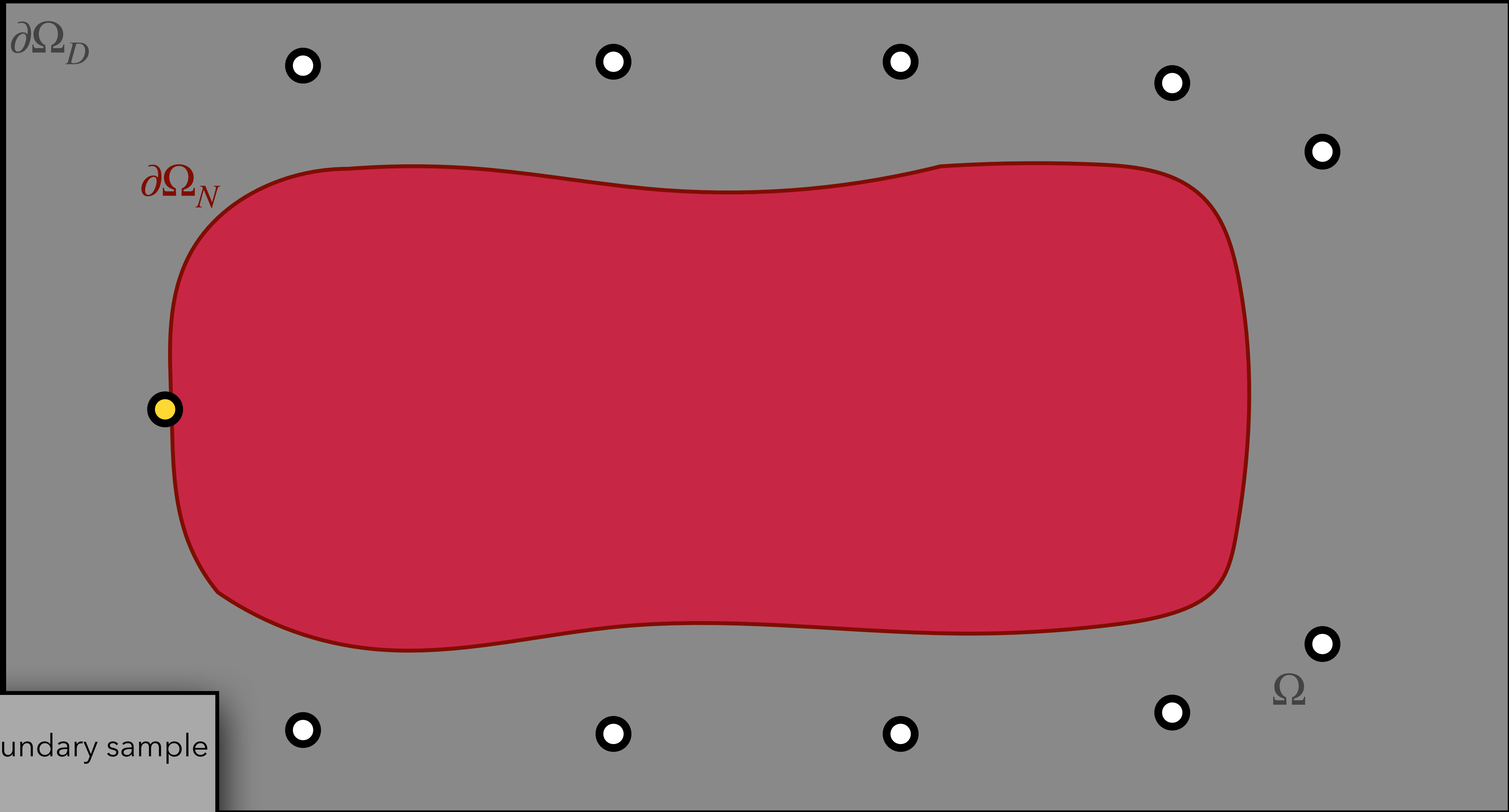
wind tunnel

pointwise estimator

Noisy streamlines!

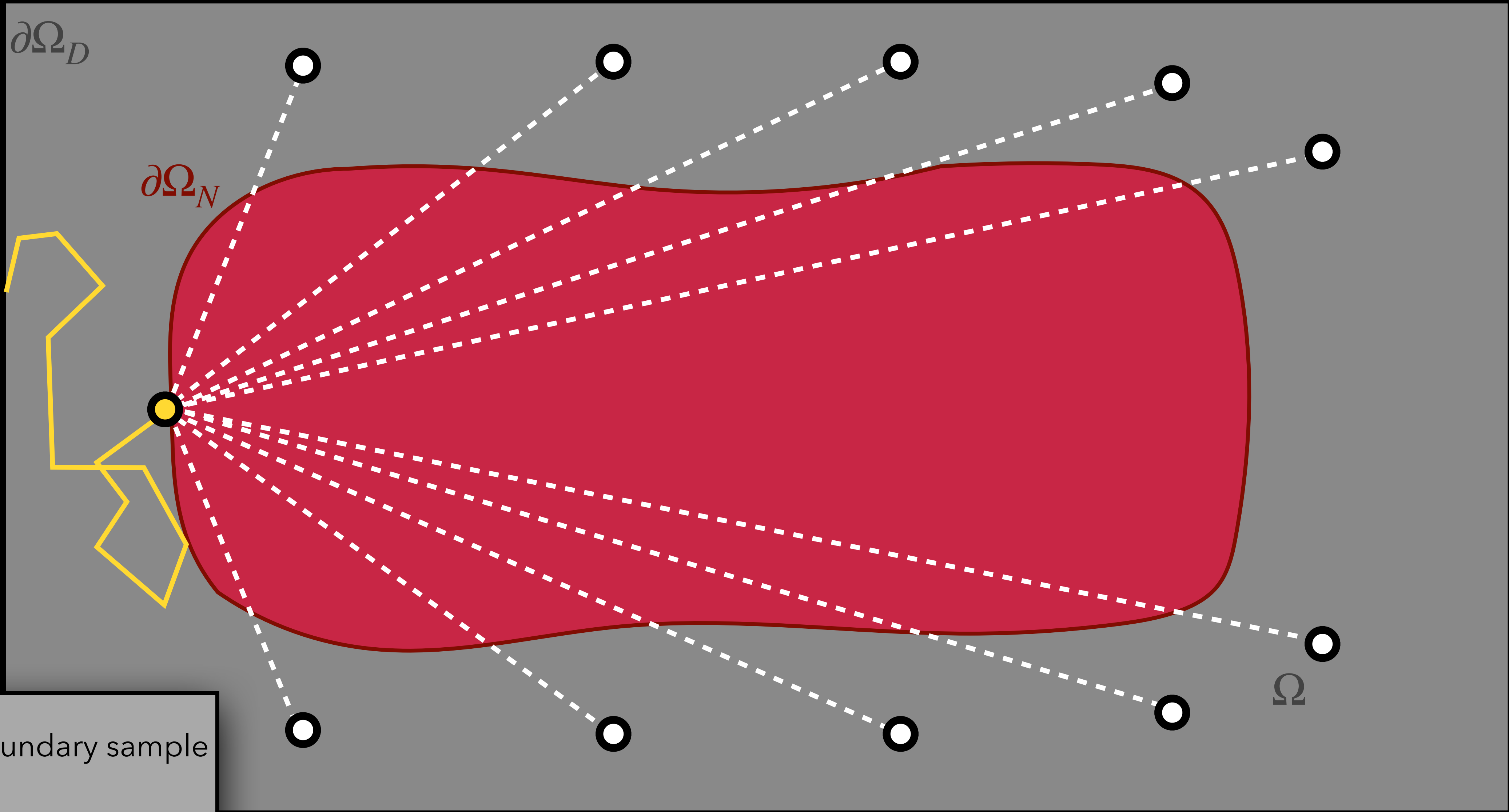


pointwise estimator



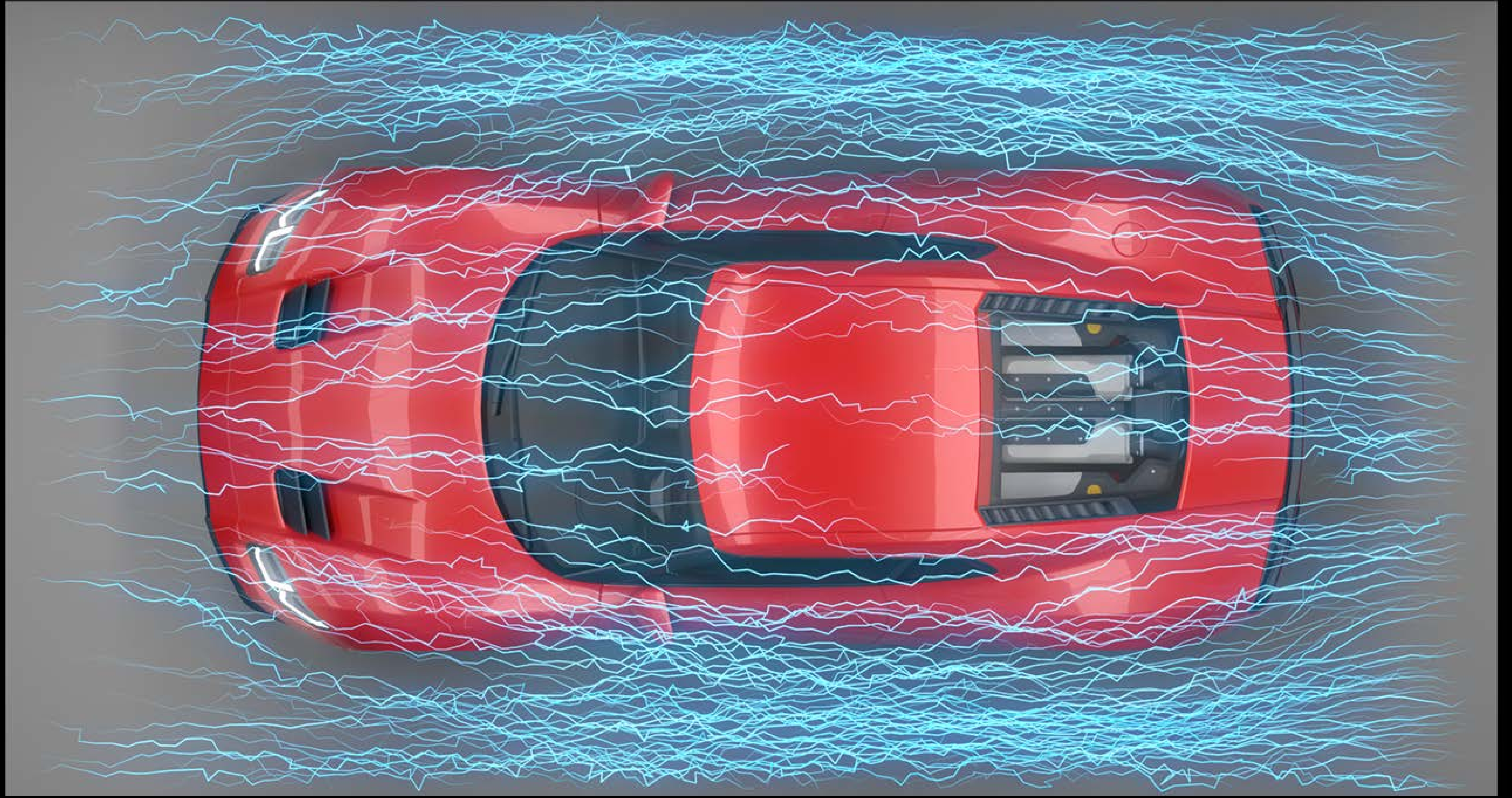
● boundary sample  
— shared walk

boundary value caching

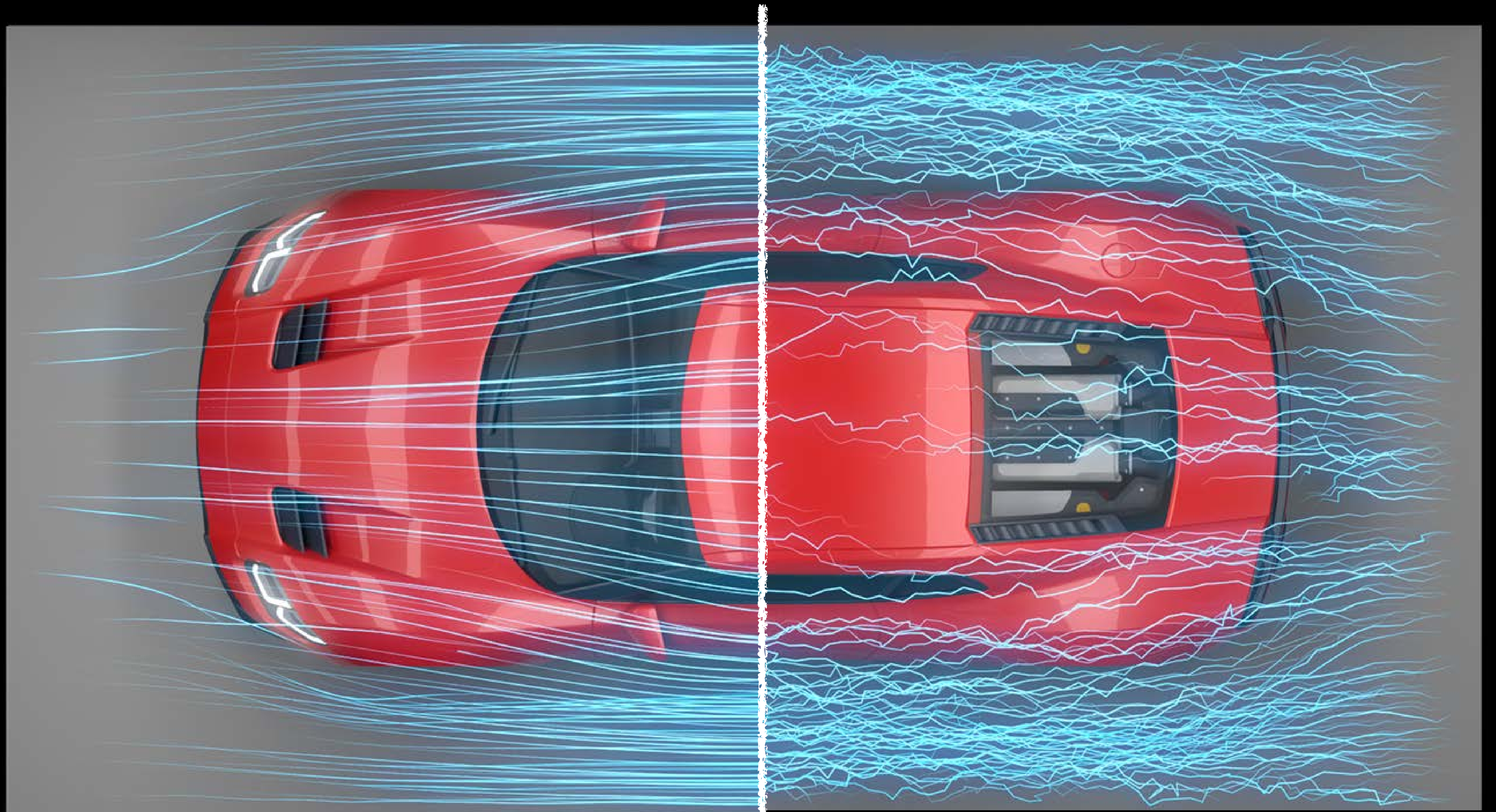


- boundary sample
- shared walk

boundary value caching



pointwise estimator



boundary value caching

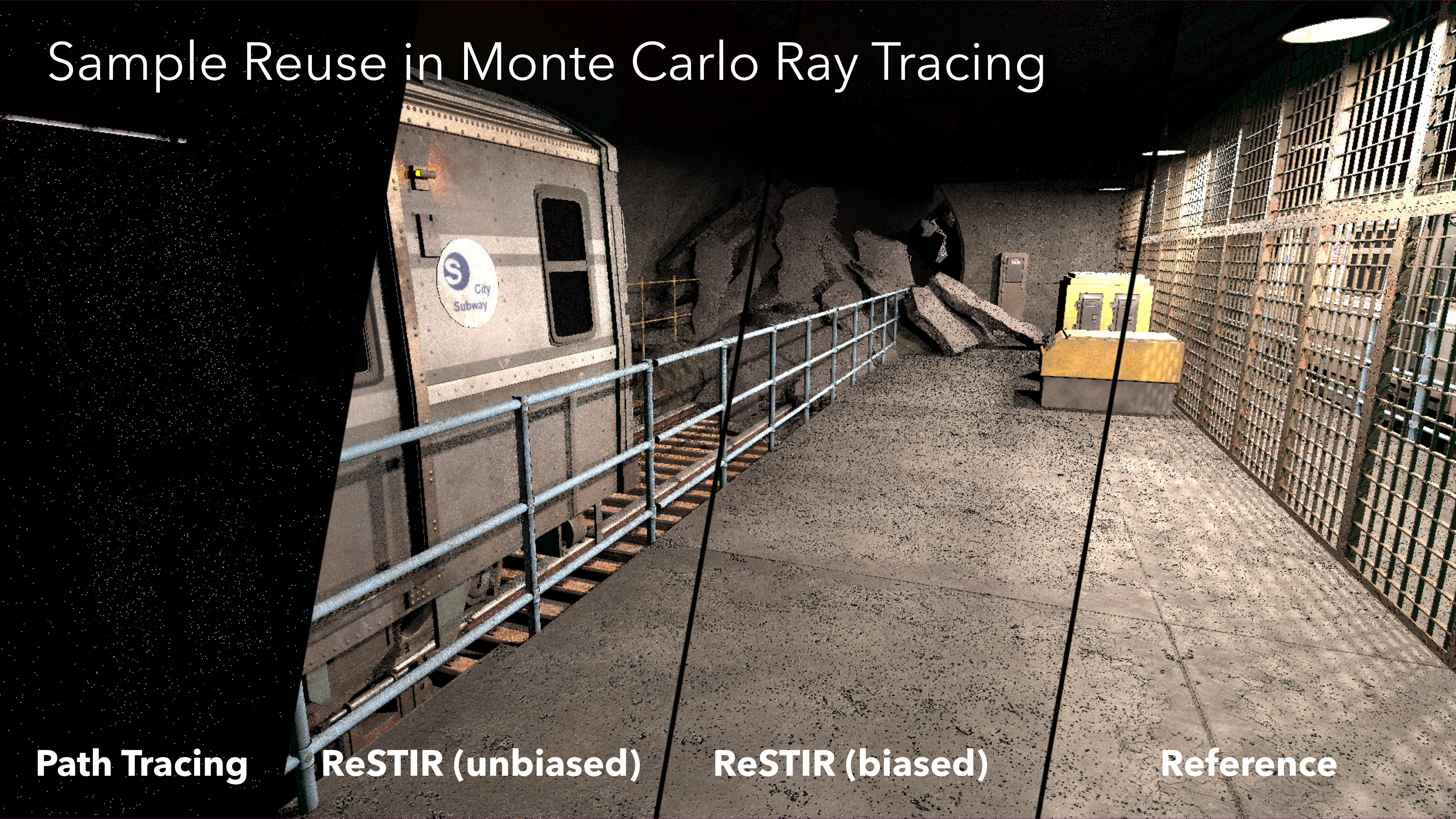
pointwise estimator





BACKGROUND

# Sample Reuse in Monte Carlo Ray Tracing



**Path Tracing**

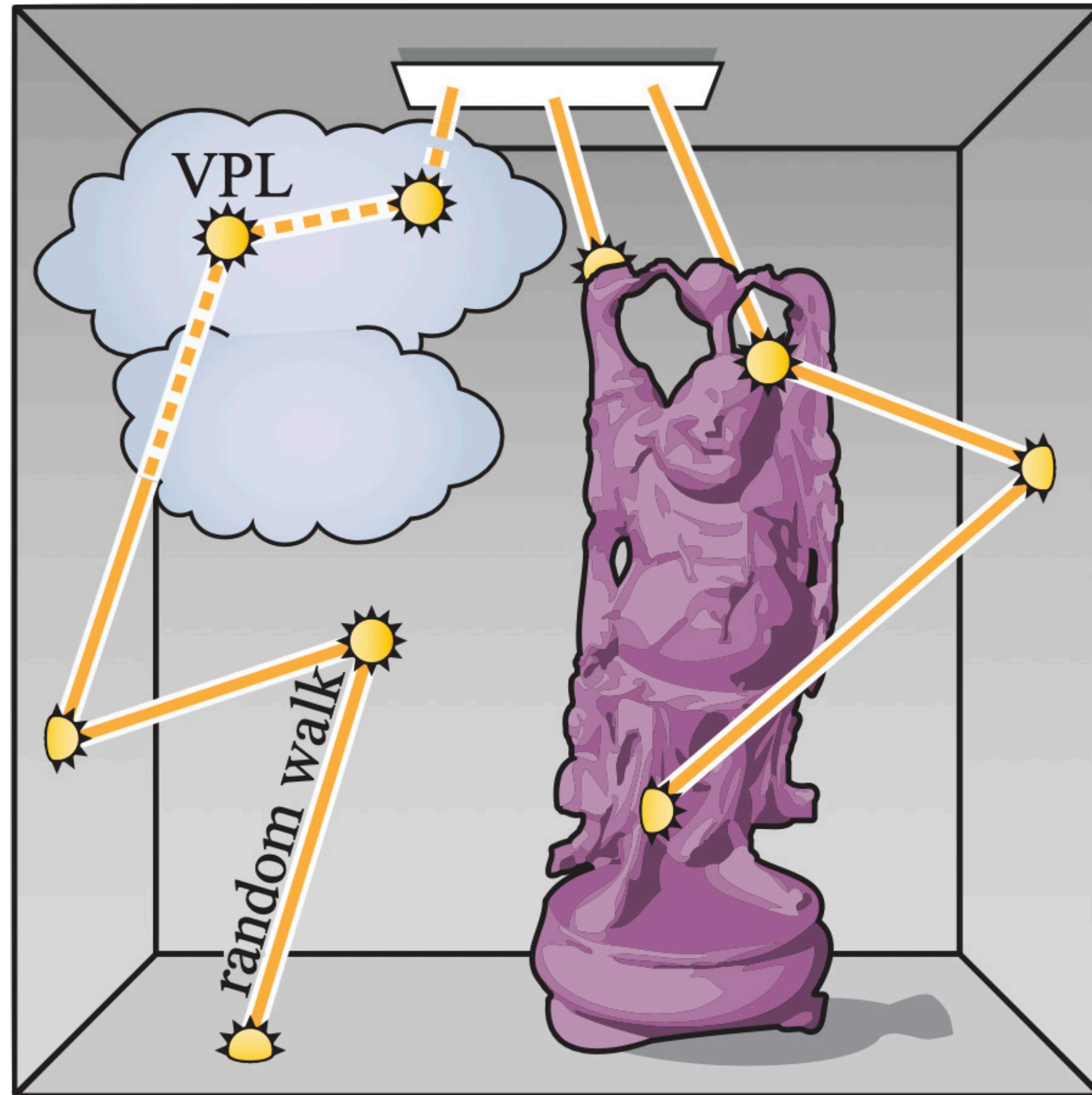
**ReSTIR (unbiased)**

**ReSTIR (biased)**

**Reference**

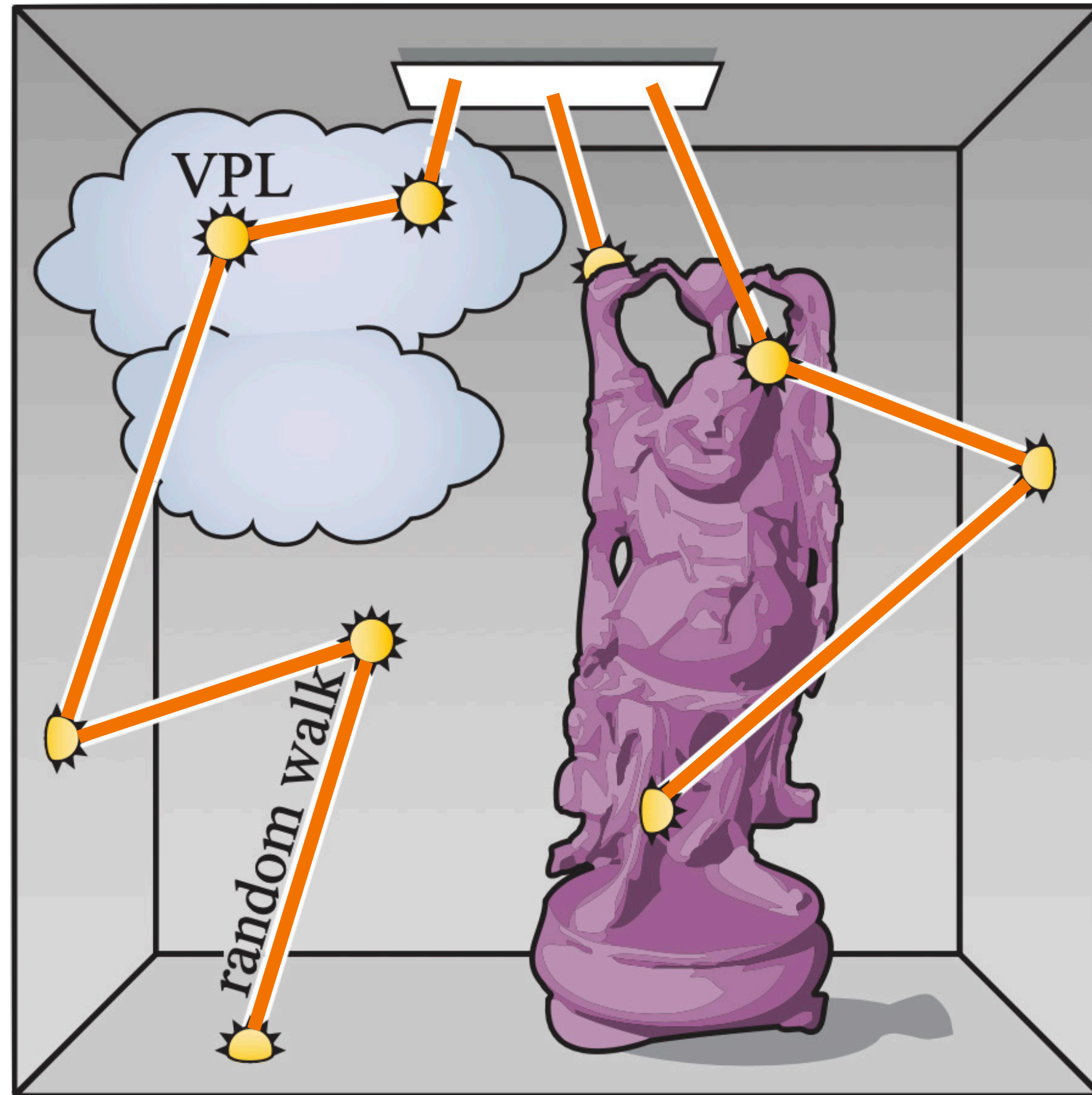
# Sample Reuse in Monte Carlo Ray Tracing

## Virtual Point Light Methods (VPLs)



# Sample Reuse in Monte Carlo Ray Tracing

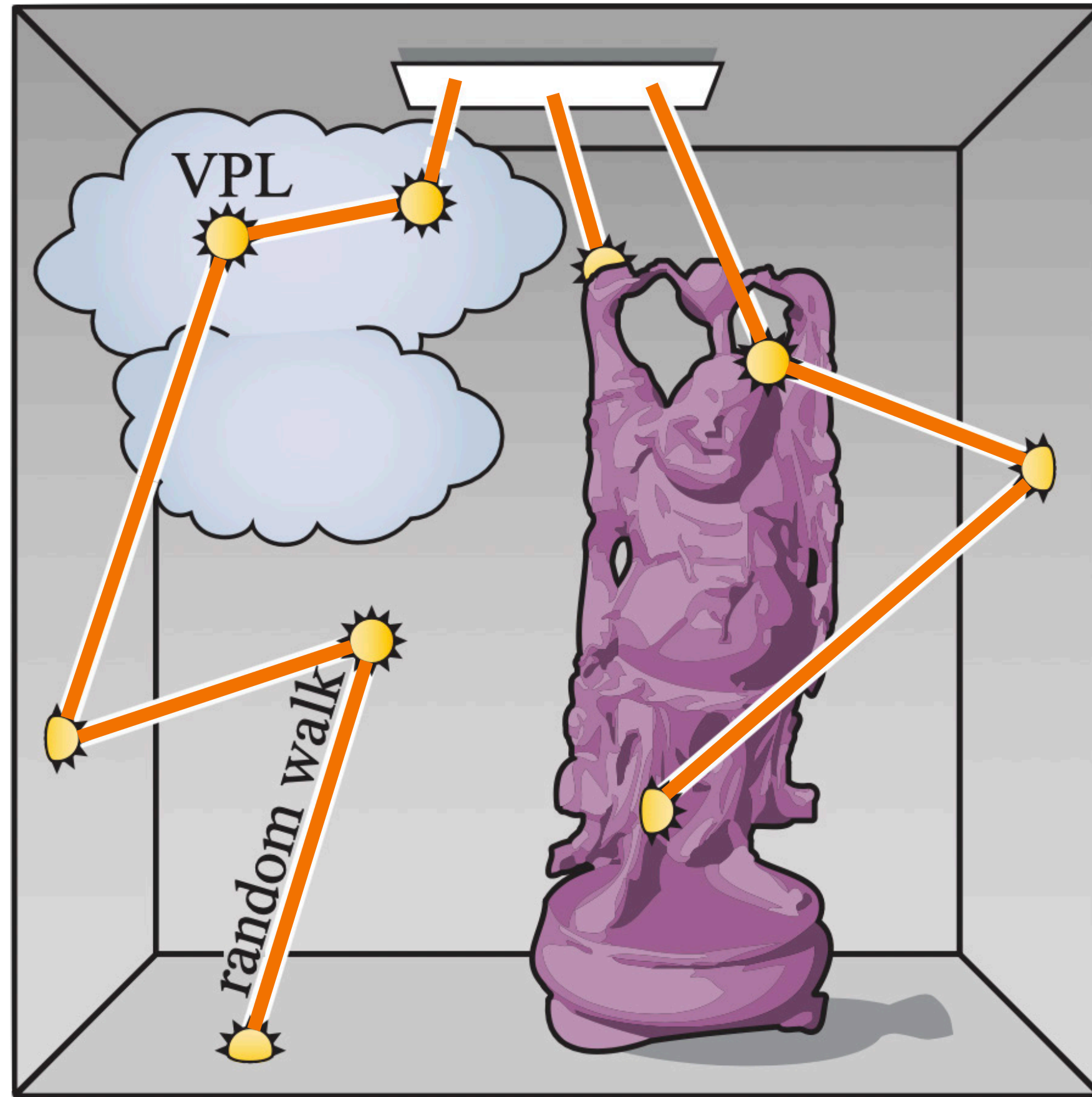
## Virtual Point Light Methods (VPLs)



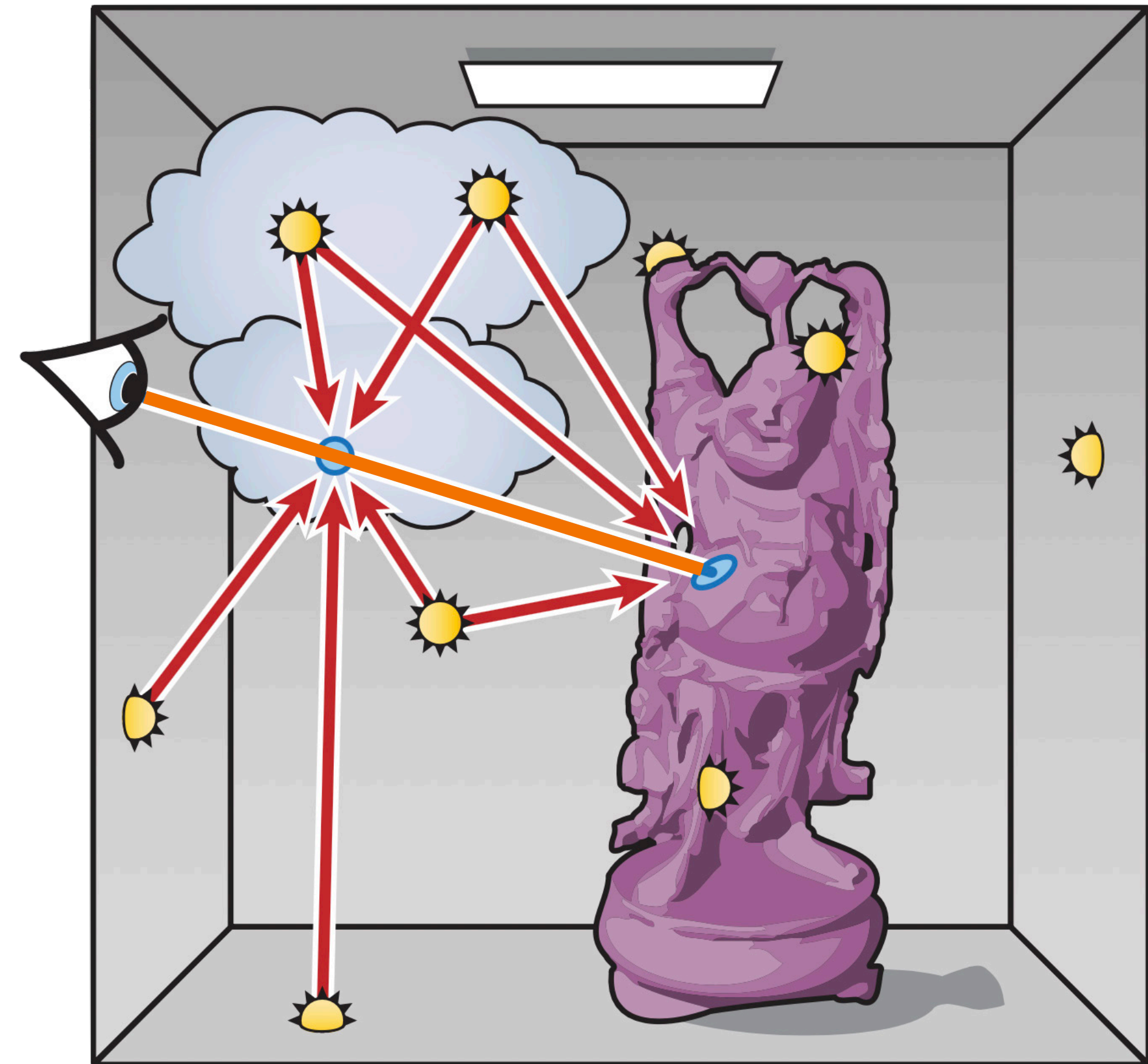
**Step 1:** Deposit radiance estimates

# Sample Reuse in Monte Carlo Ray Tracing

## Virtual Point Light Methods (VPLs)



**Step 1:** Deposit radiance estimates



**Step 2:** Reuse cached radiance estimates

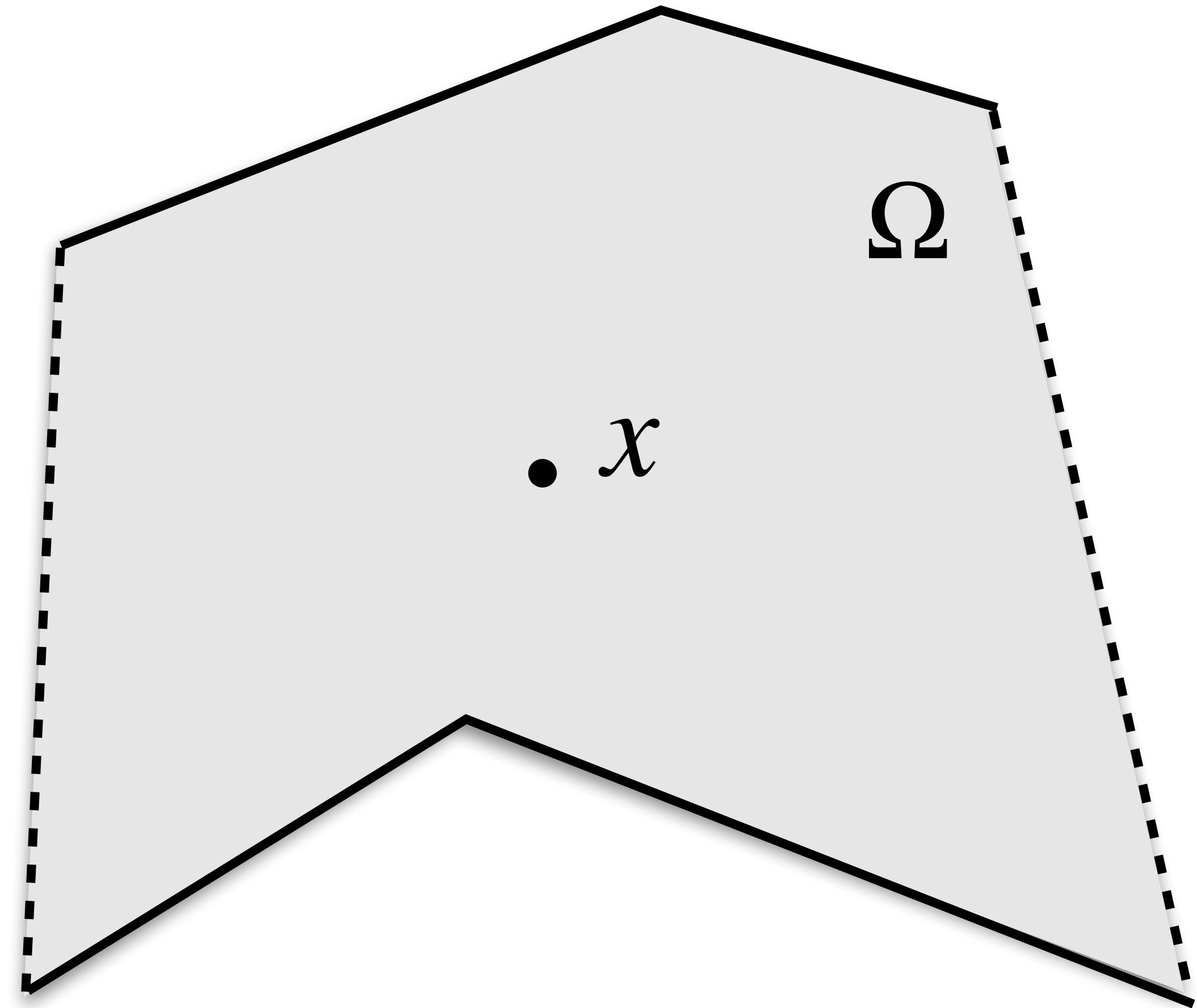
# Boundary Integral Equation (BIE)

**Laplace equation**

$$\Delta u = 0 \quad \text{on } \Omega$$

$$u = g \quad \text{on } \partial\Omega_D$$

$$\frac{\partial u}{\partial n} = h \quad \text{on } \partial\Omega_N$$



Dirichlet



Neumann

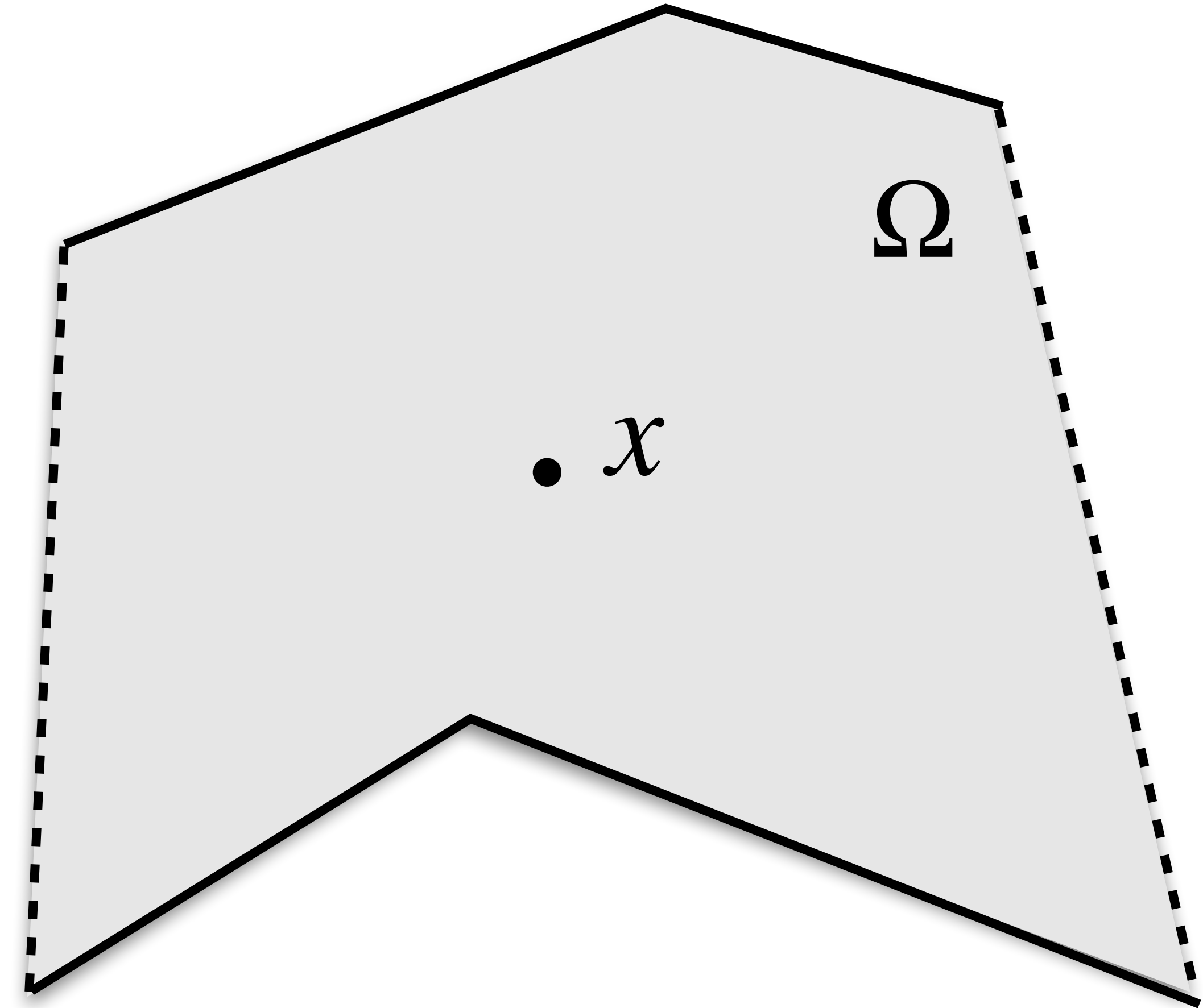
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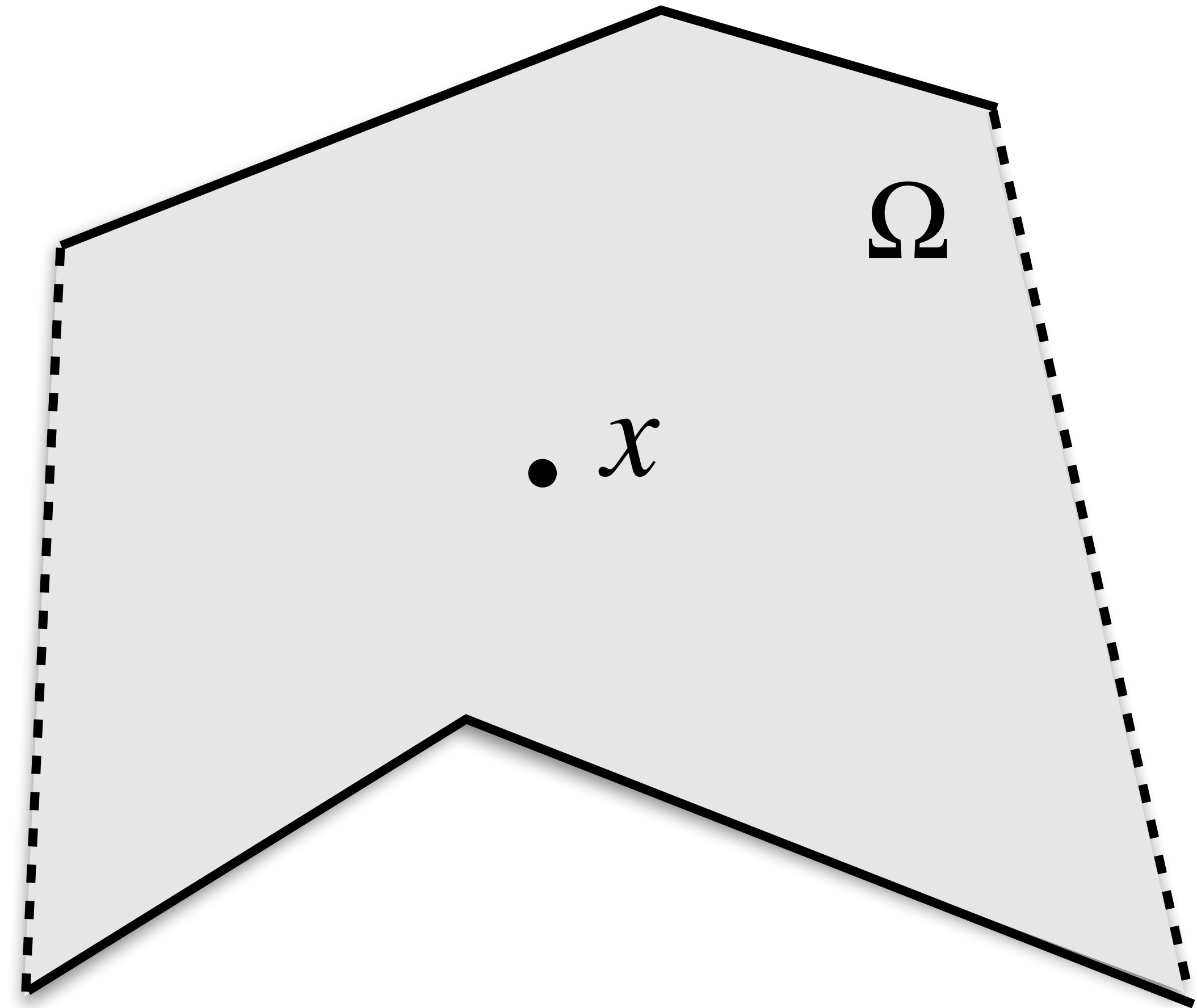
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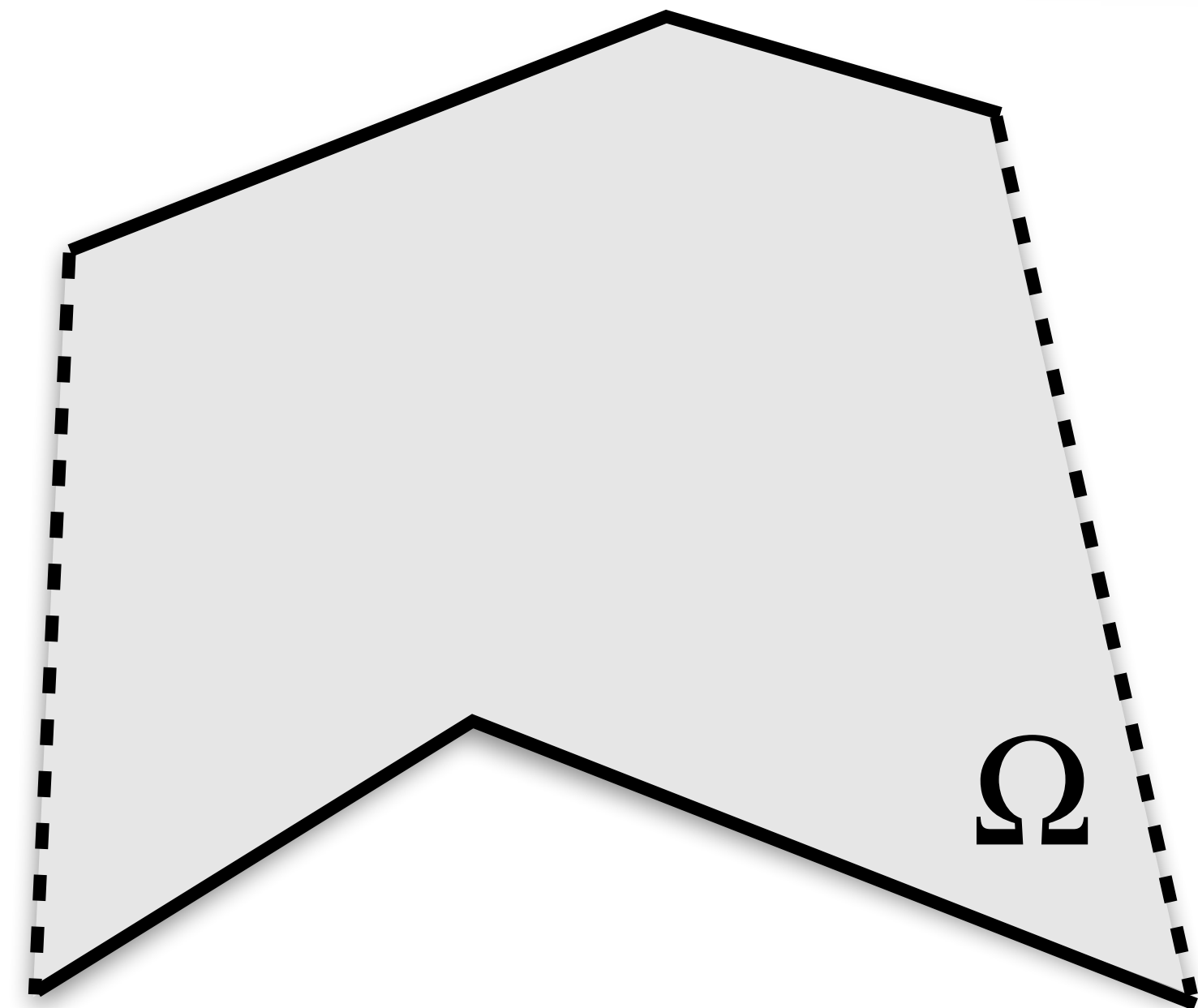
# Boundary Integral Equation (BIE)

$$u(x) = \int_{\partial\Omega} \frac{\partial G(x, y)}{\partial n} u(y) - G(x, y) \frac{\partial u(y)}{\partial n} dy$$

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# Boundary Integral Equation (BIE)

Dirichlet Data

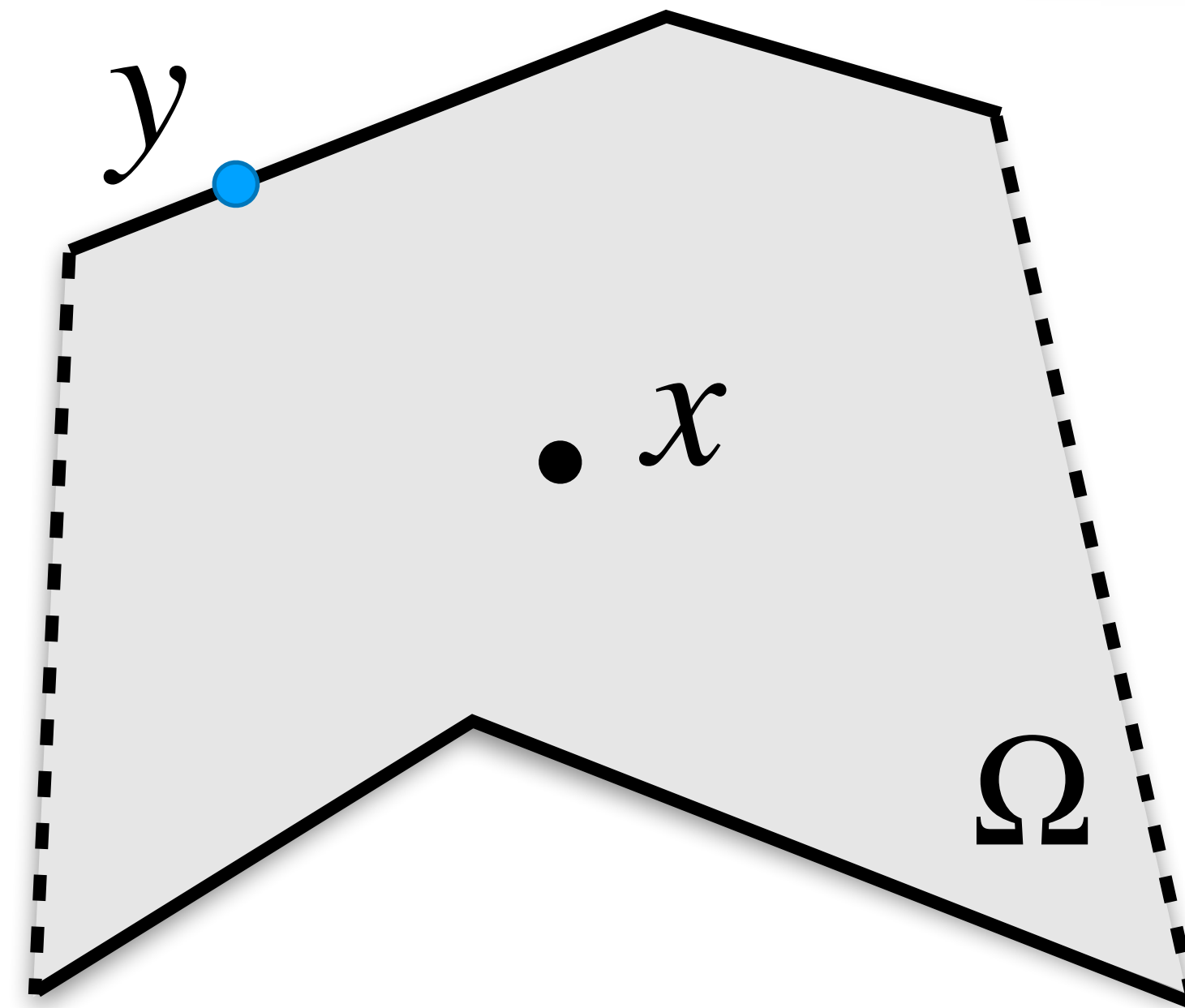
Neumann Data

$$u(x) = \int_{\partial\Omega} \frac{\partial G(x, y)}{\partial n} u(y) - G(x, y) \frac{\partial u(y)}{\partial n} dy$$

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$$\frac{\partial u}{\partial n} = h \quad \text{on } \partial\Omega_N$$



# Boundary Integral Equation (BIE)

free-space Poisson kernel

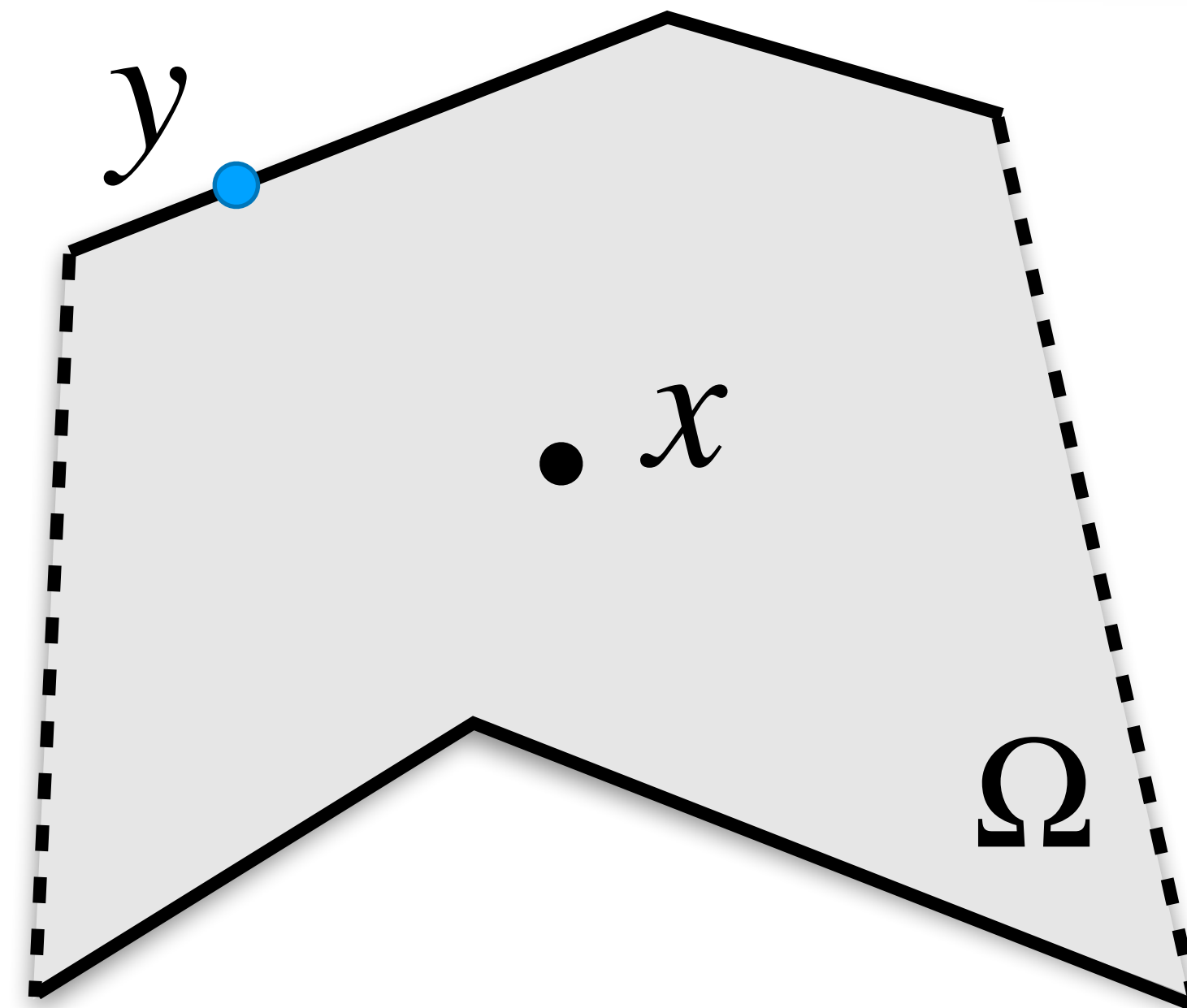
free-space Green kernel

$$u(x) = \int_{\partial\Omega} \frac{\partial G(x, y)}{\partial n} u(y) - G(x, y) \frac{\partial u(y)}{\partial n} dy$$

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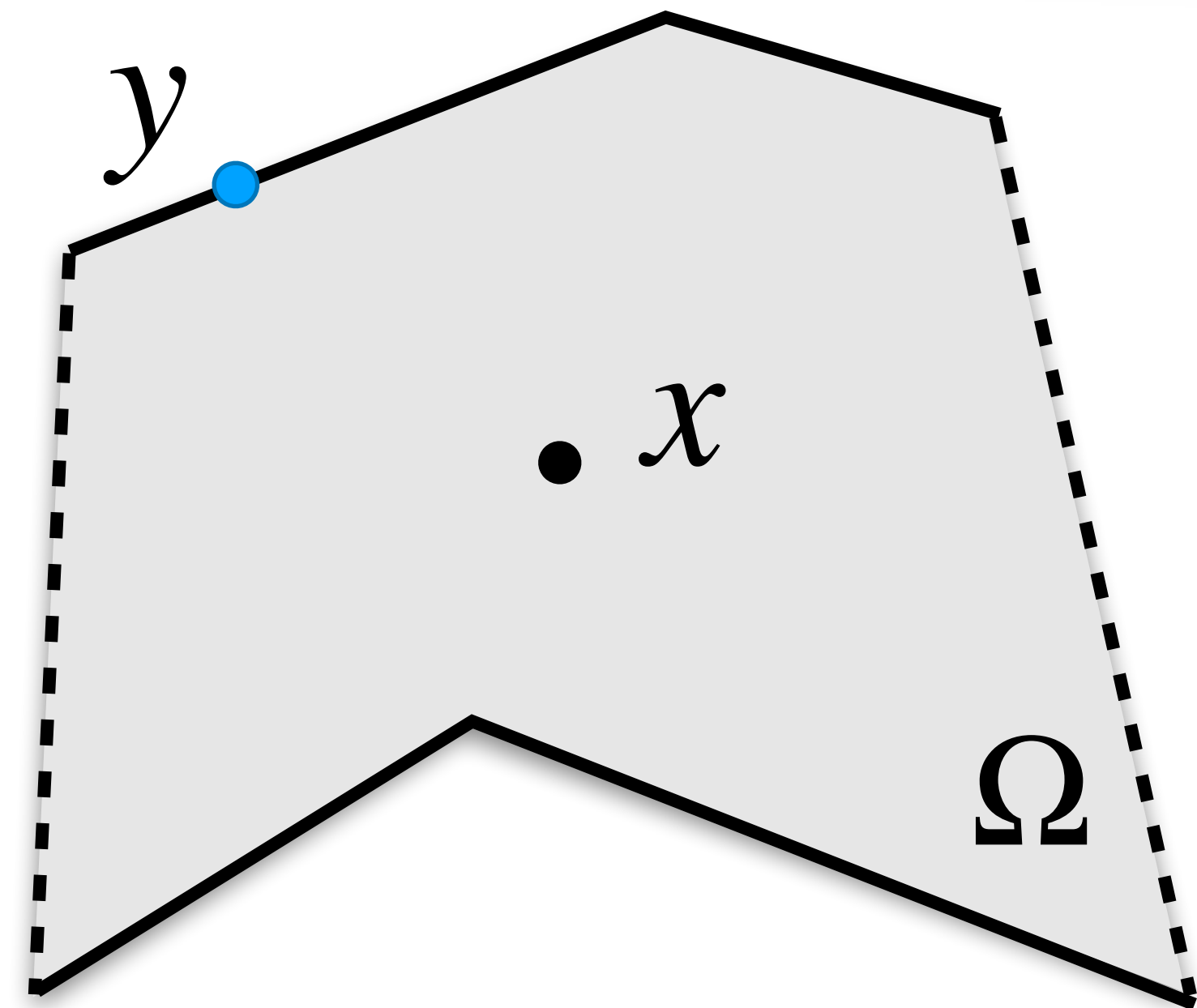
# Monte Carlo Estimate of BIE

$$\hat{u}(x) = \frac{|\partial\Omega|}{N} \sum_{i=1}^N \frac{\partial G(x, y_i)}{\partial n} u(y_i) - G(x, y_i) \frac{\partial u(y_i)}{\partial n}$$

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$$u = g \quad \text{on } \partial\Omega_D$$

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# Monte Carlo Estimate of BIE

known

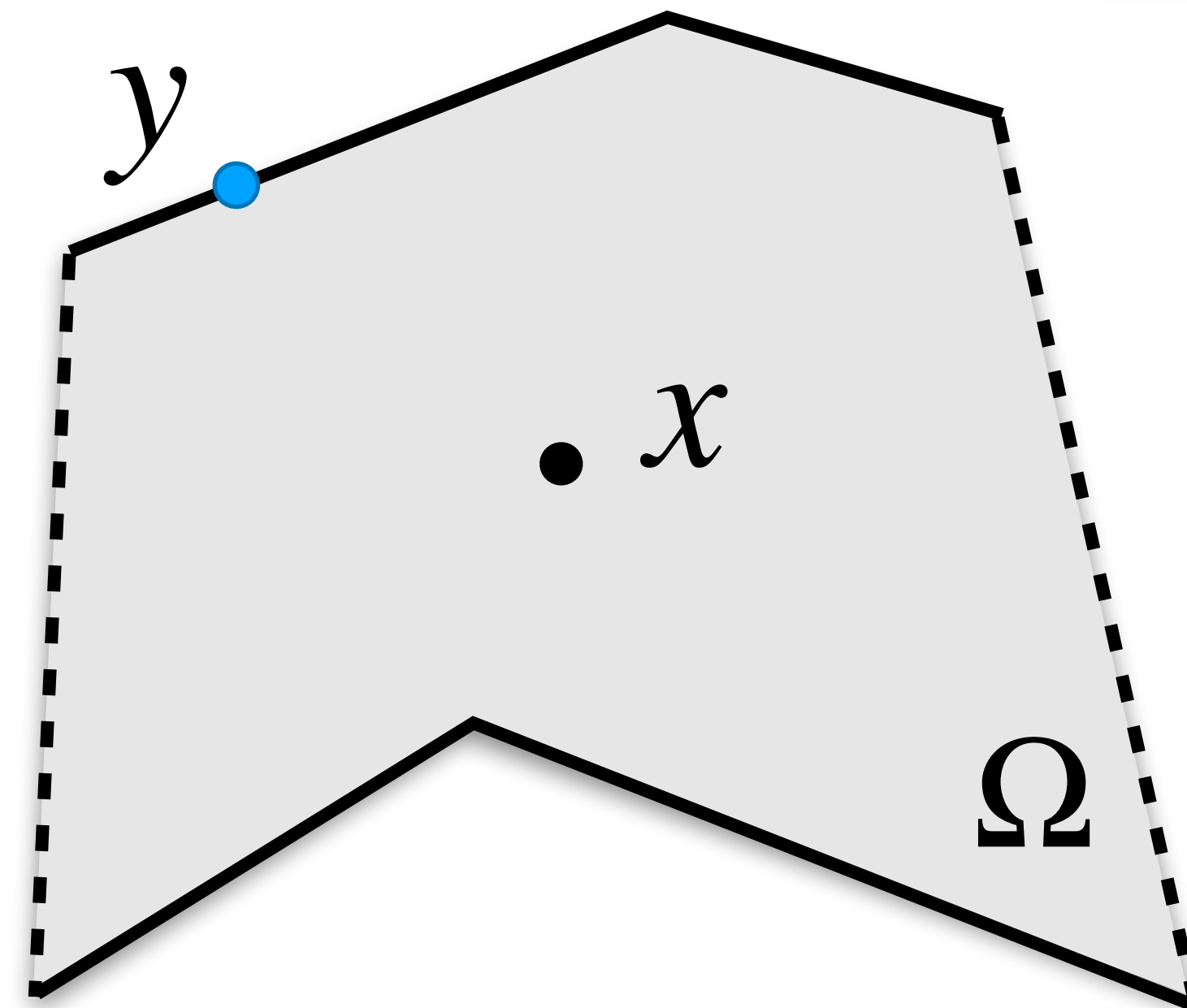
requires estimate

$$\hat{u}(x) = \frac{|\partial\Omega|}{N} \sum_{i=1}^N \frac{\partial G(x, y_i)}{\partial n} g(y_i) - G(x, y_i) \frac{\widehat{\partial u(y_i)}}{\partial n}$$

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$$\frac{\partial u}{\partial n} = h \quad \text{on } \partial\Omega_N$$



# Monte Carlo Estimate of BIE

requires estimate

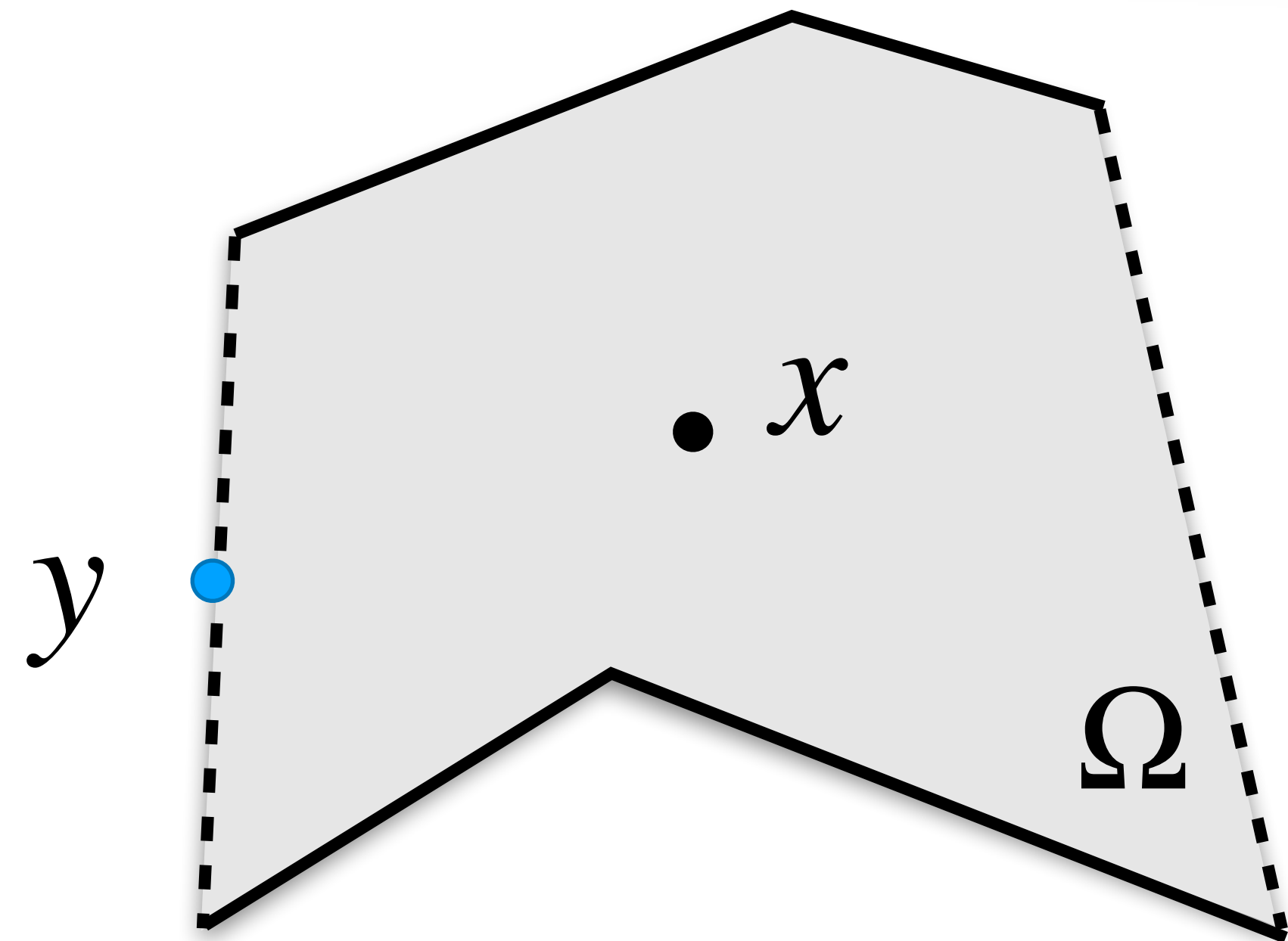
known

$$\hat{u}(x) = \frac{|\partial\Omega|}{N} \sum_{i=1}^N \frac{\partial G(x, y_i)}{\partial n} \hat{u}(y_i) - G(x, y_i) h(y_i)$$

$$\Delta u = 0 \quad \text{on } \Omega$$

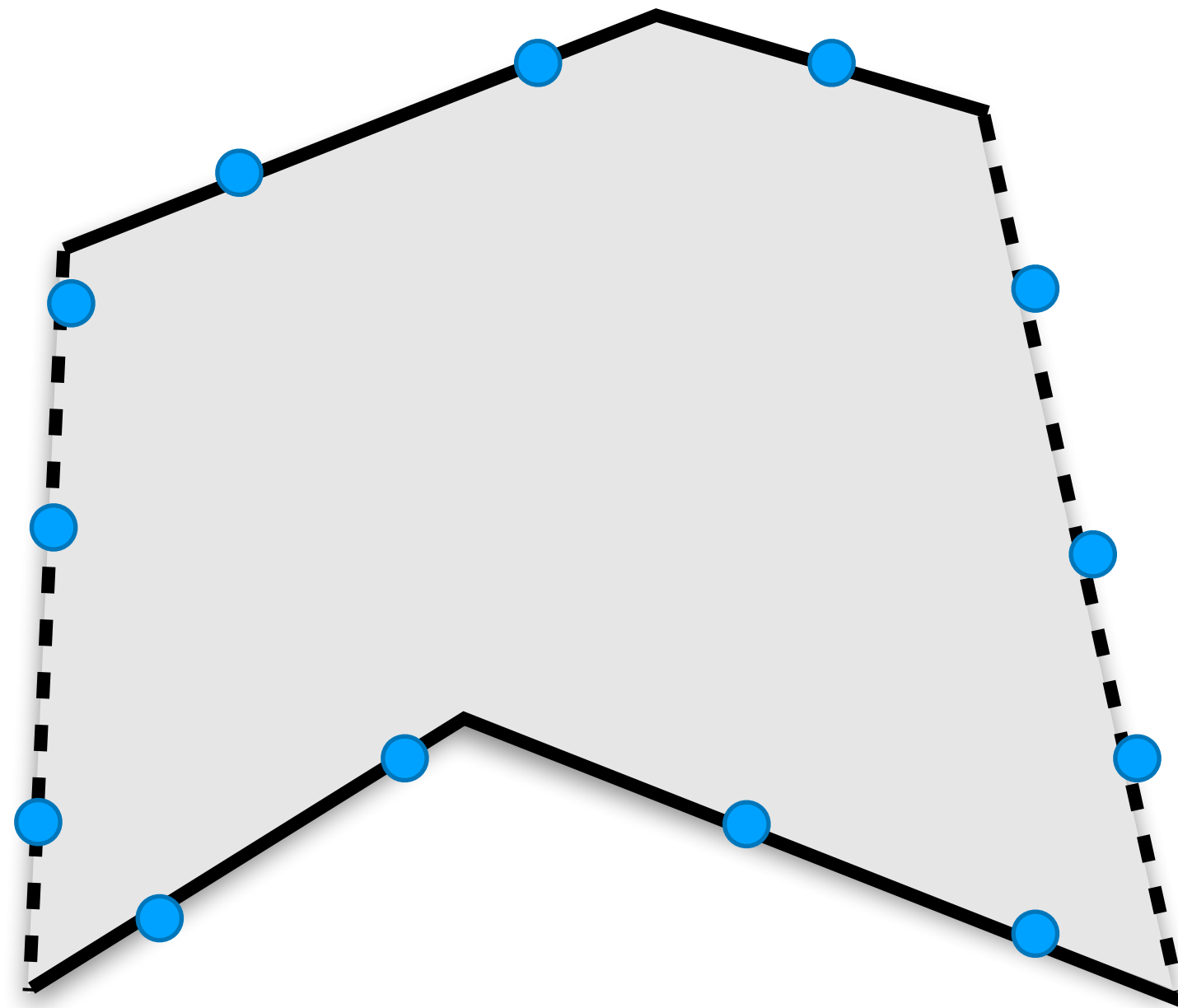
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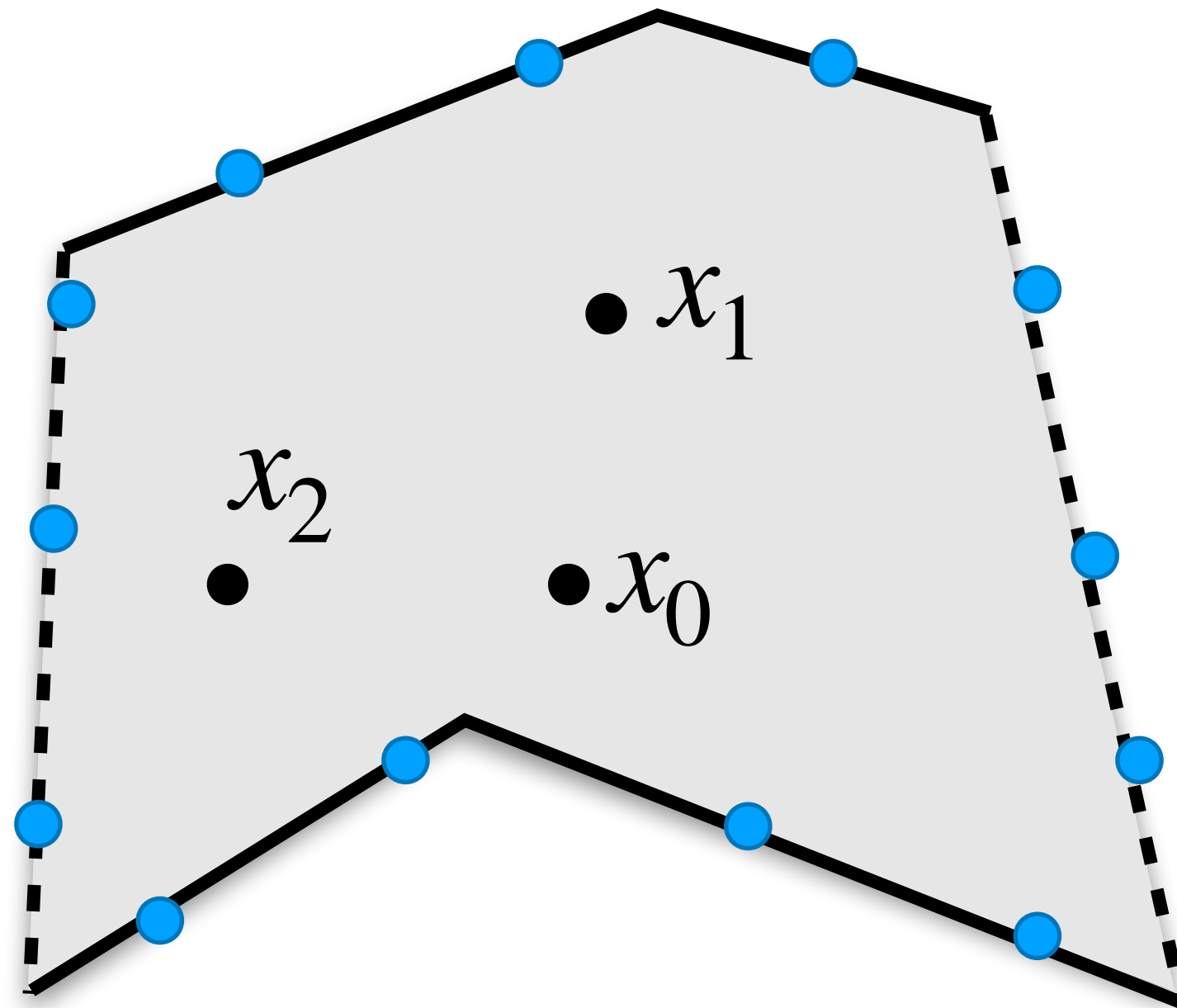
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# Monte Carlo Estimate of BIE

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we can reuse  
boundary value  
estimates!

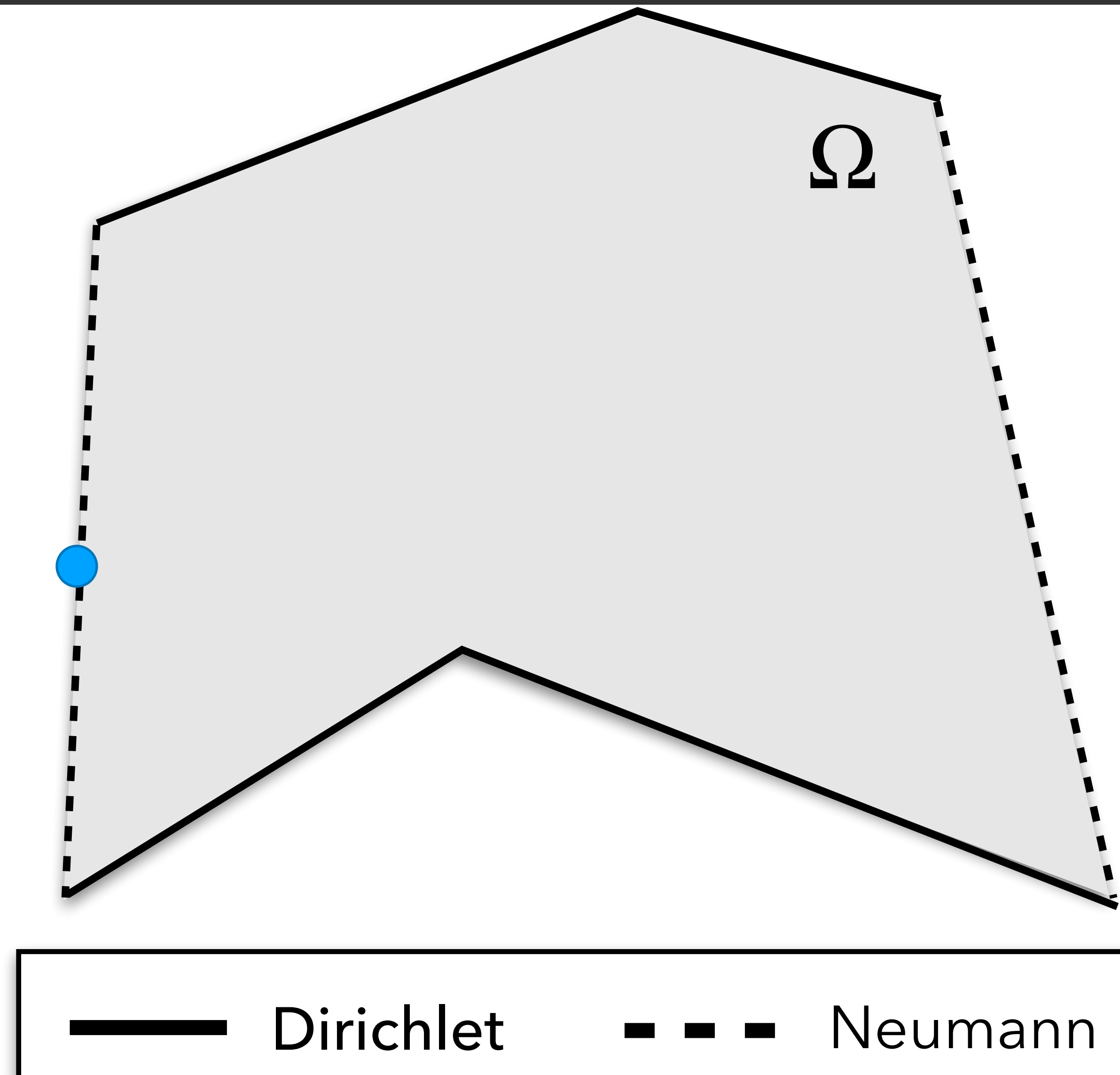
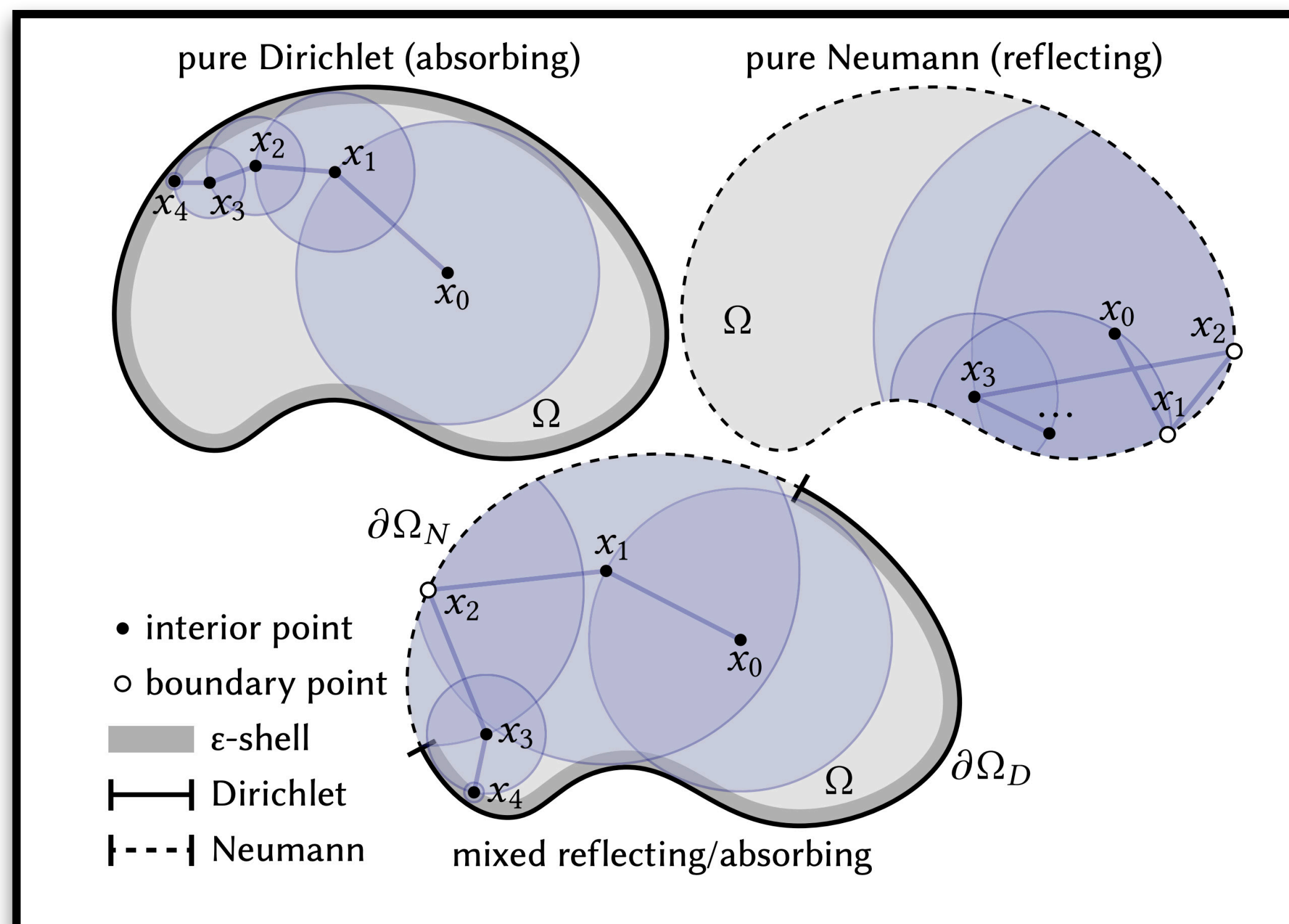




# METHOD

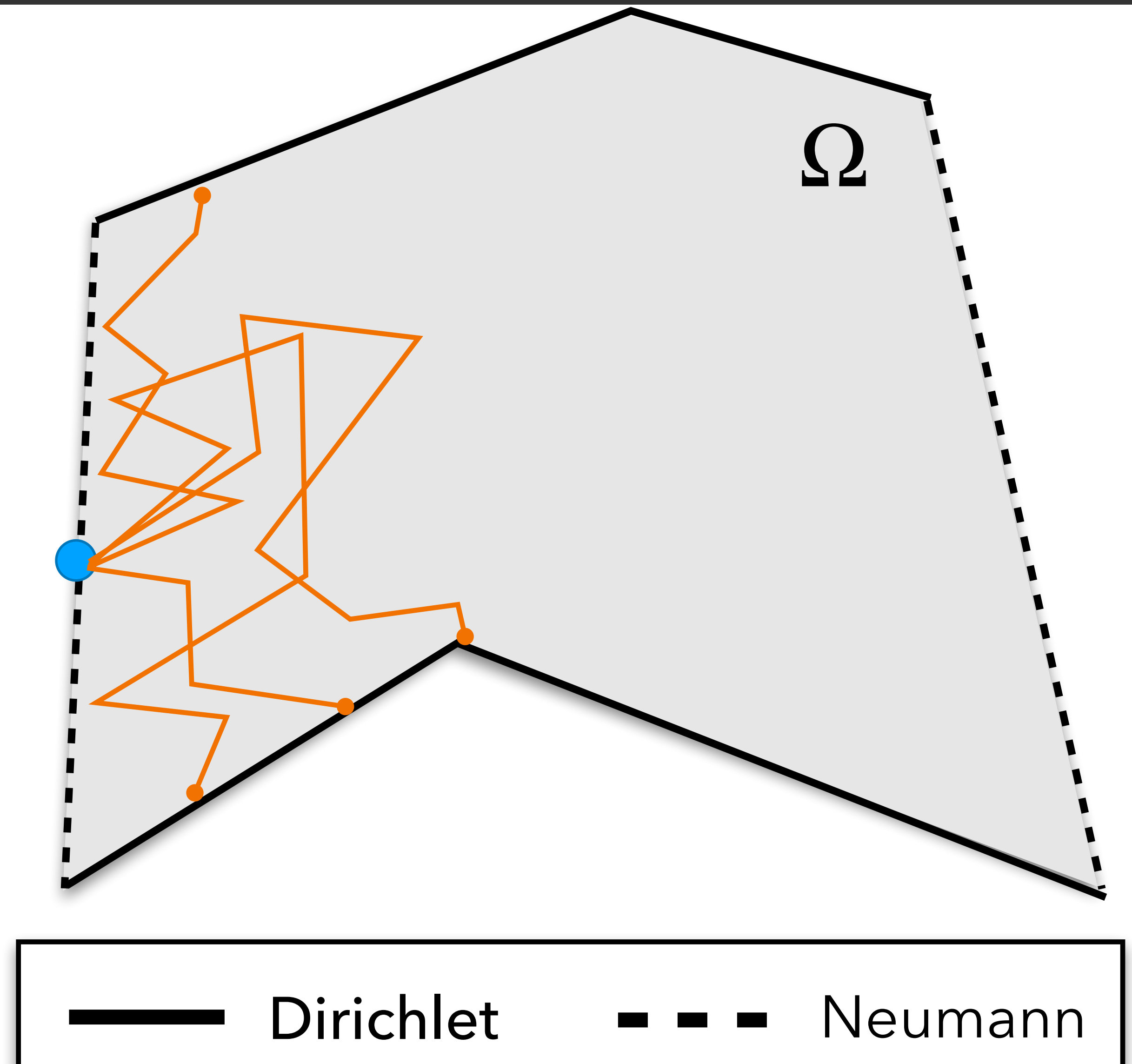
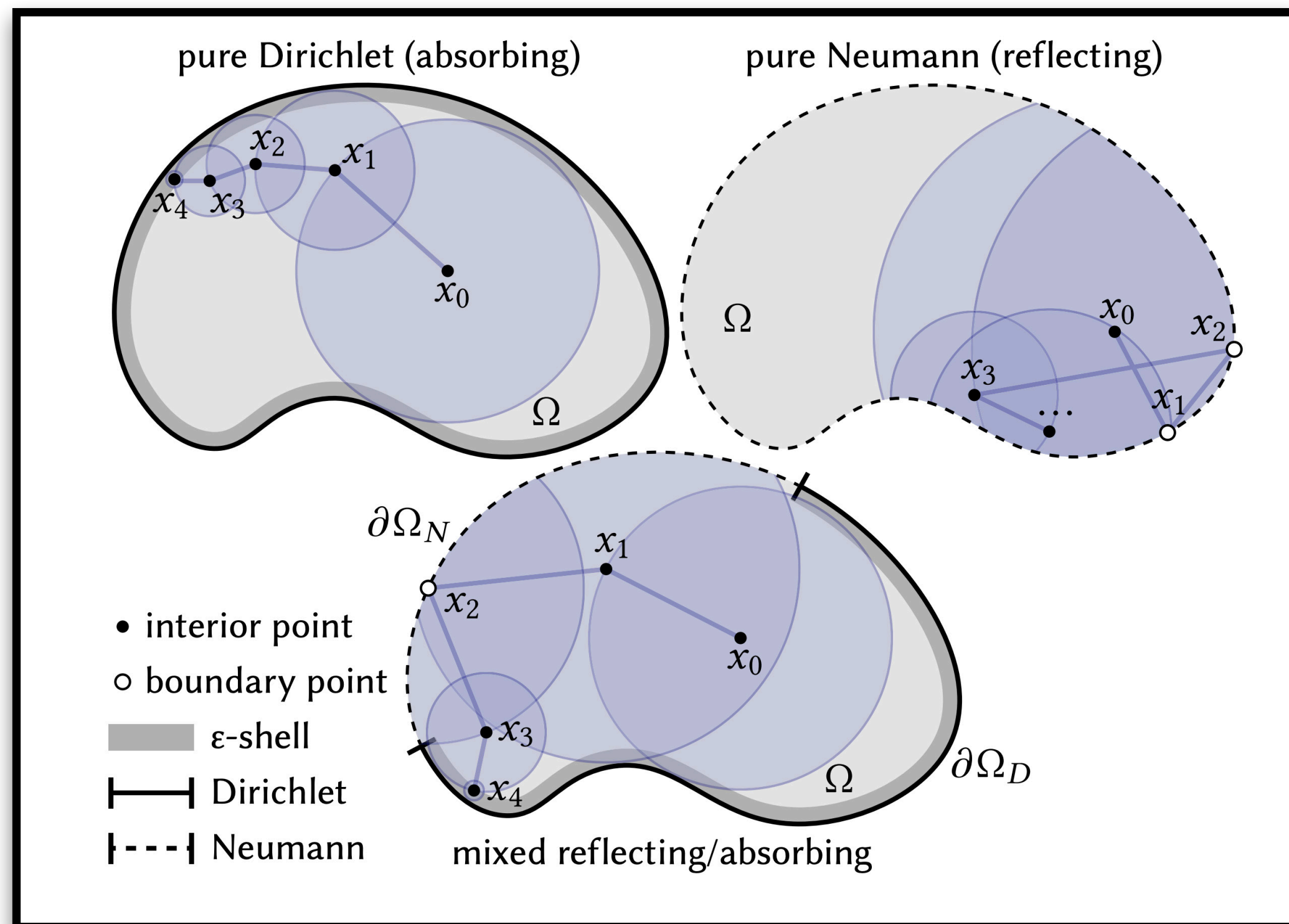
# Estimating Dirichlet Boundary Values $\hat{u}$

**Walk on Stars** [Sawhney et al. 2023]:



# Estimating Dirichlet Boundary Values $\hat{u}$

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# Estimating Neumann Boundary Values $d\hat{u}/dn$

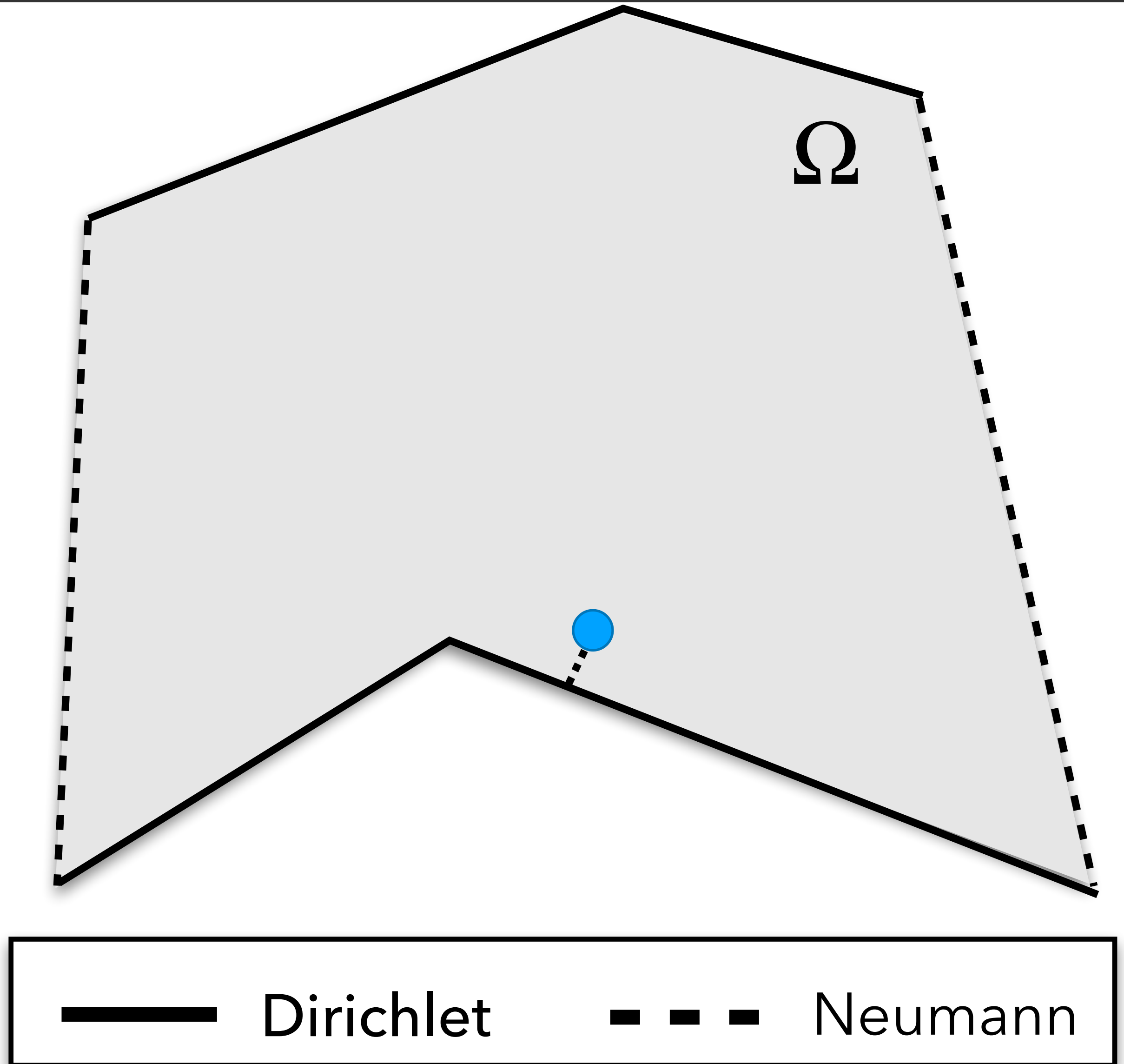
Spatial derivative **inside a ball**

[Sawhney & Crane 2020]:

$$\nabla_x u(x) = \frac{1}{|B|} \int_{\partial B} u(y) v(y) dy$$

Normal derivative **on the boundary**:

$$\frac{du(x)}{dn_x} = n_x \cdot \nabla_x u(x)$$



# Estimating Neumann Boundary Values $d\hat{u}/dn$

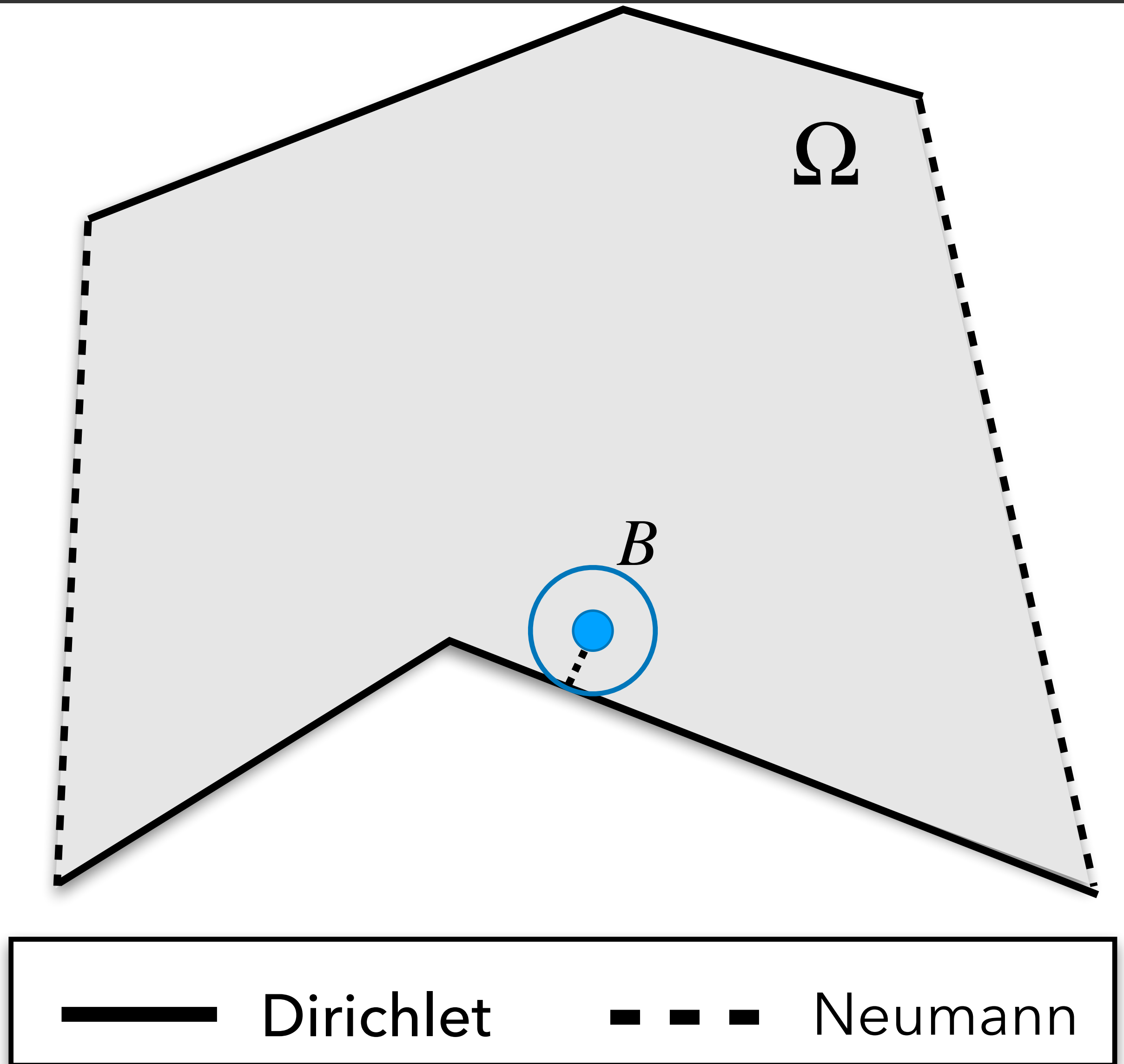
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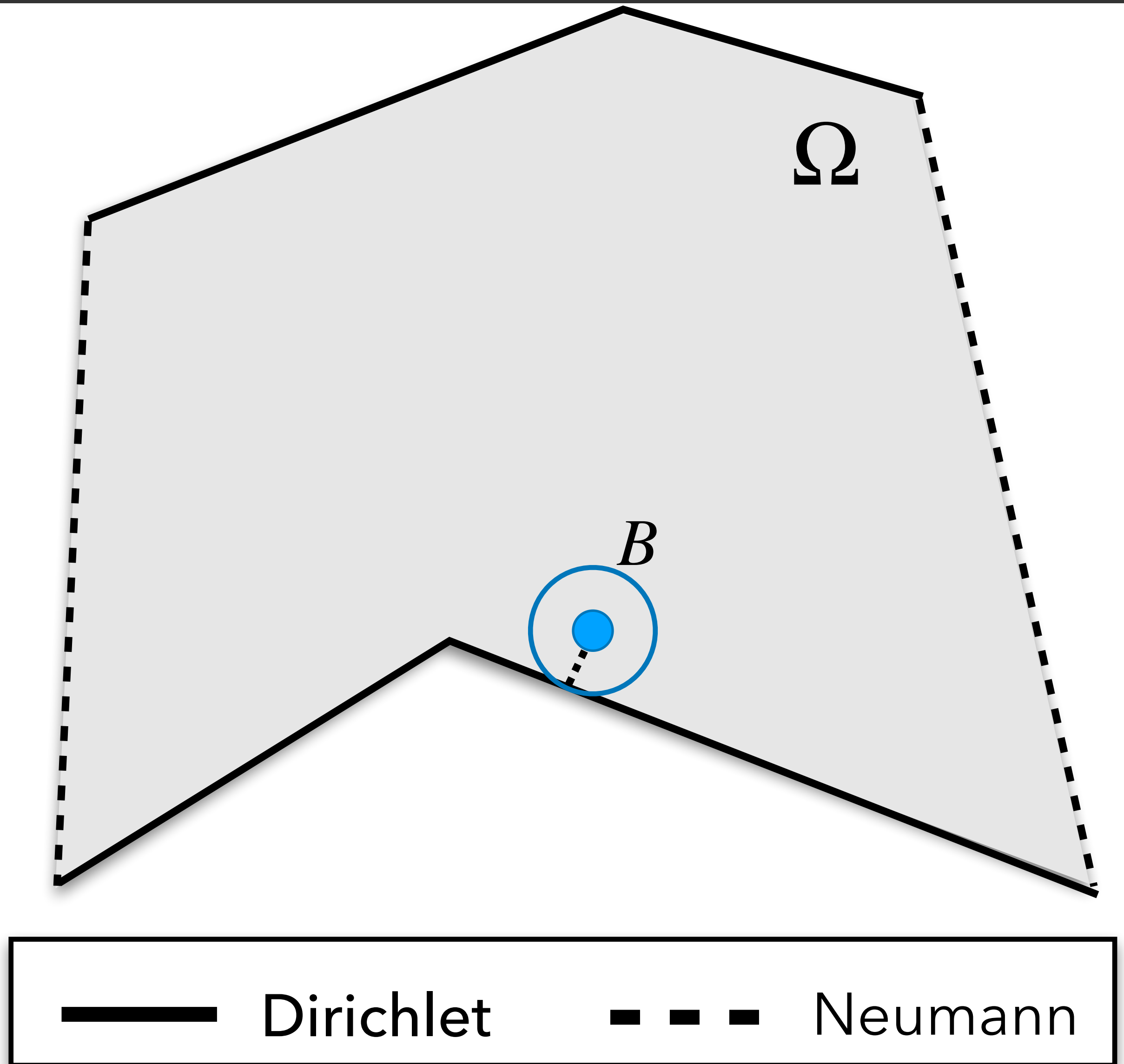
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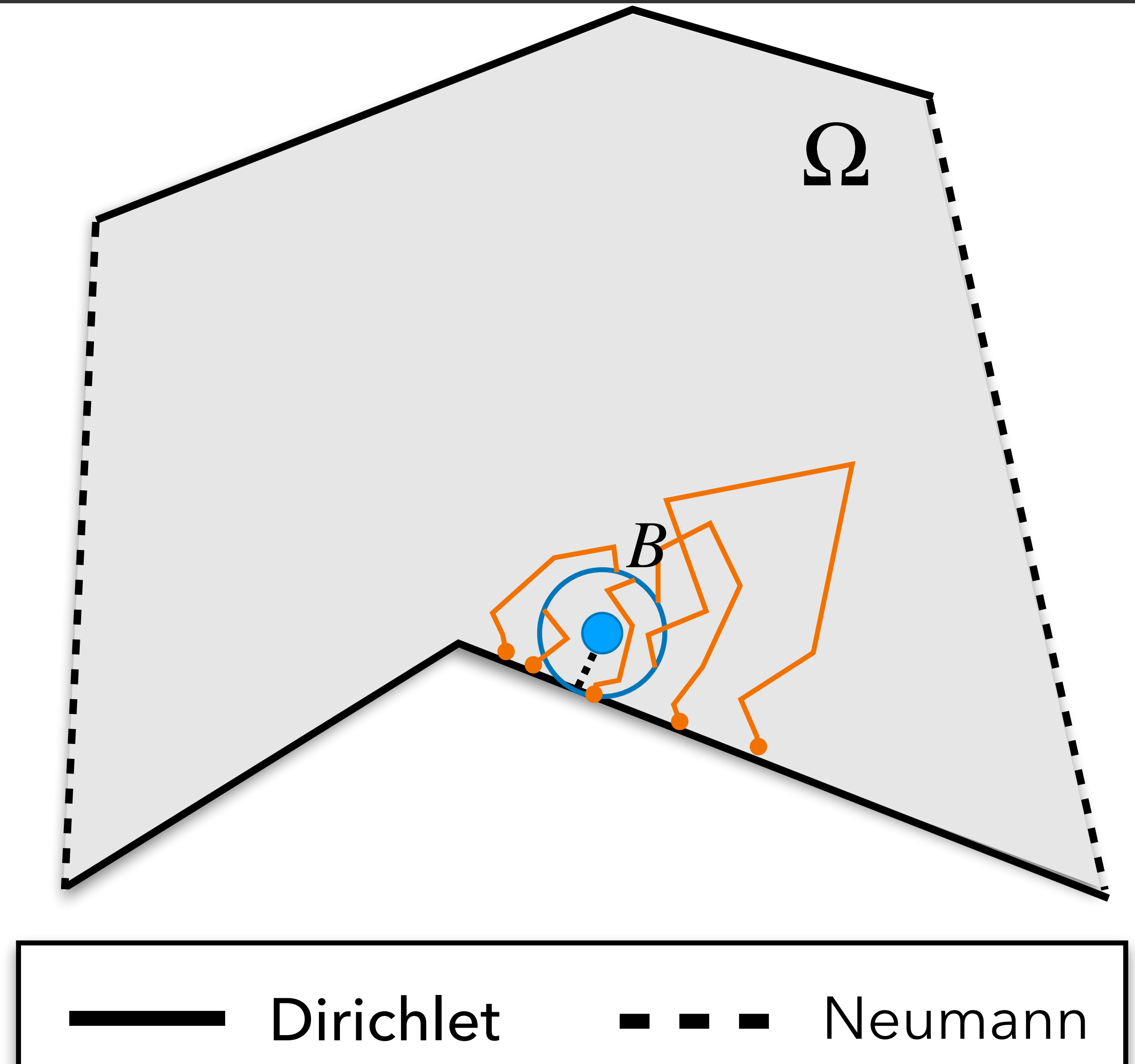
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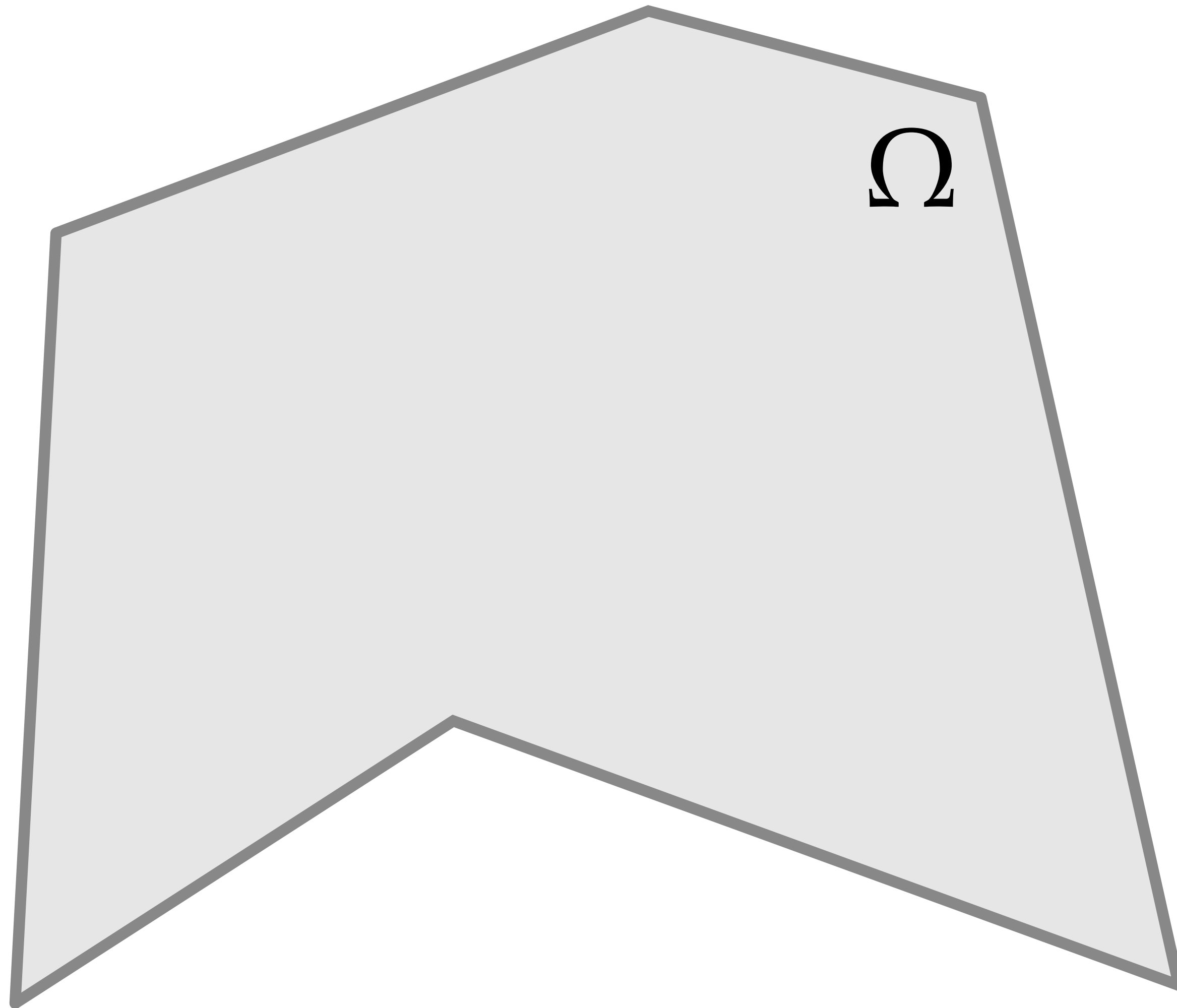
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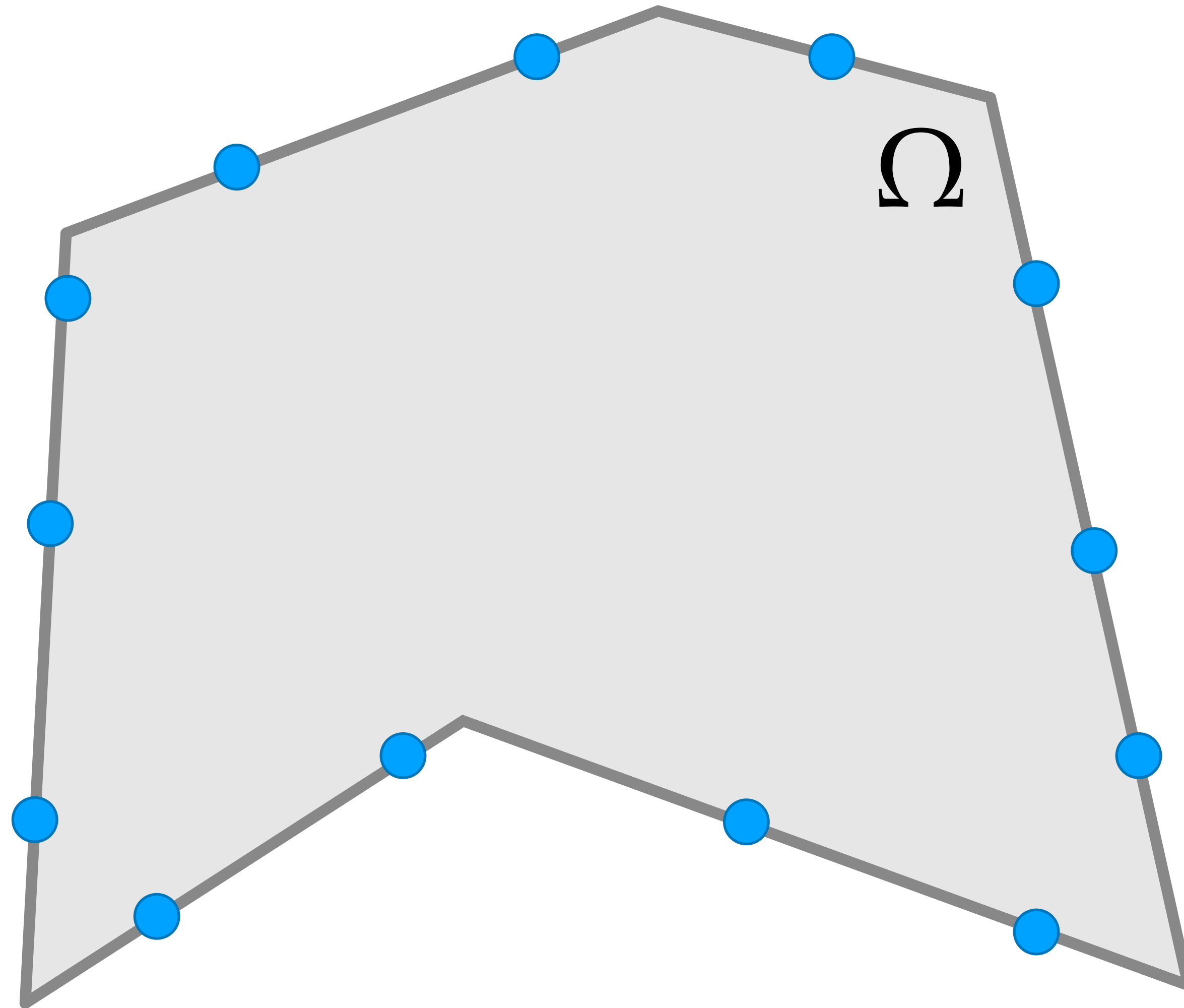




# Boundary Value Caching (BVC)

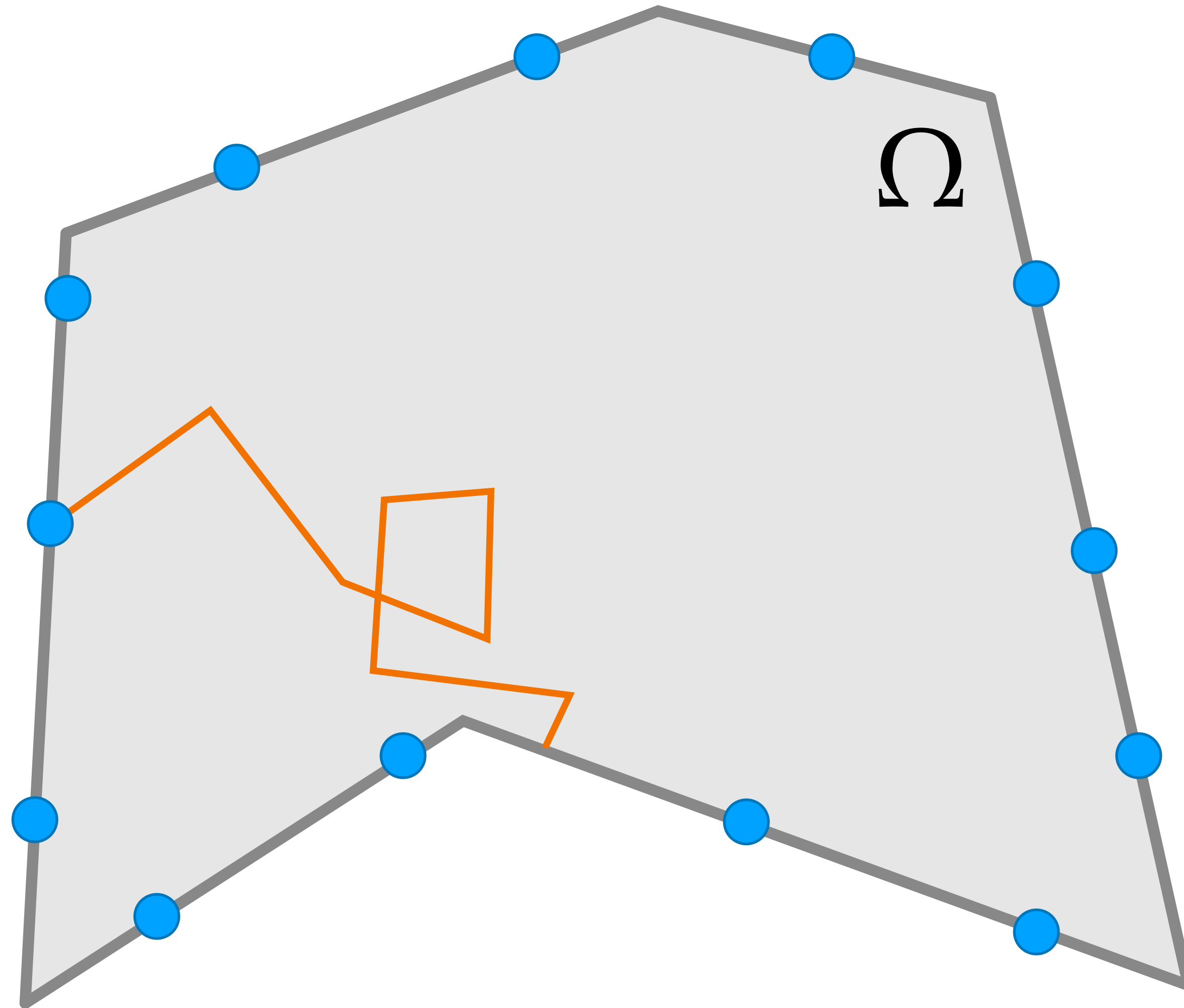


# Boundary Value Caching (BVC)



generate samples  
on boundary  $\partial\Omega$

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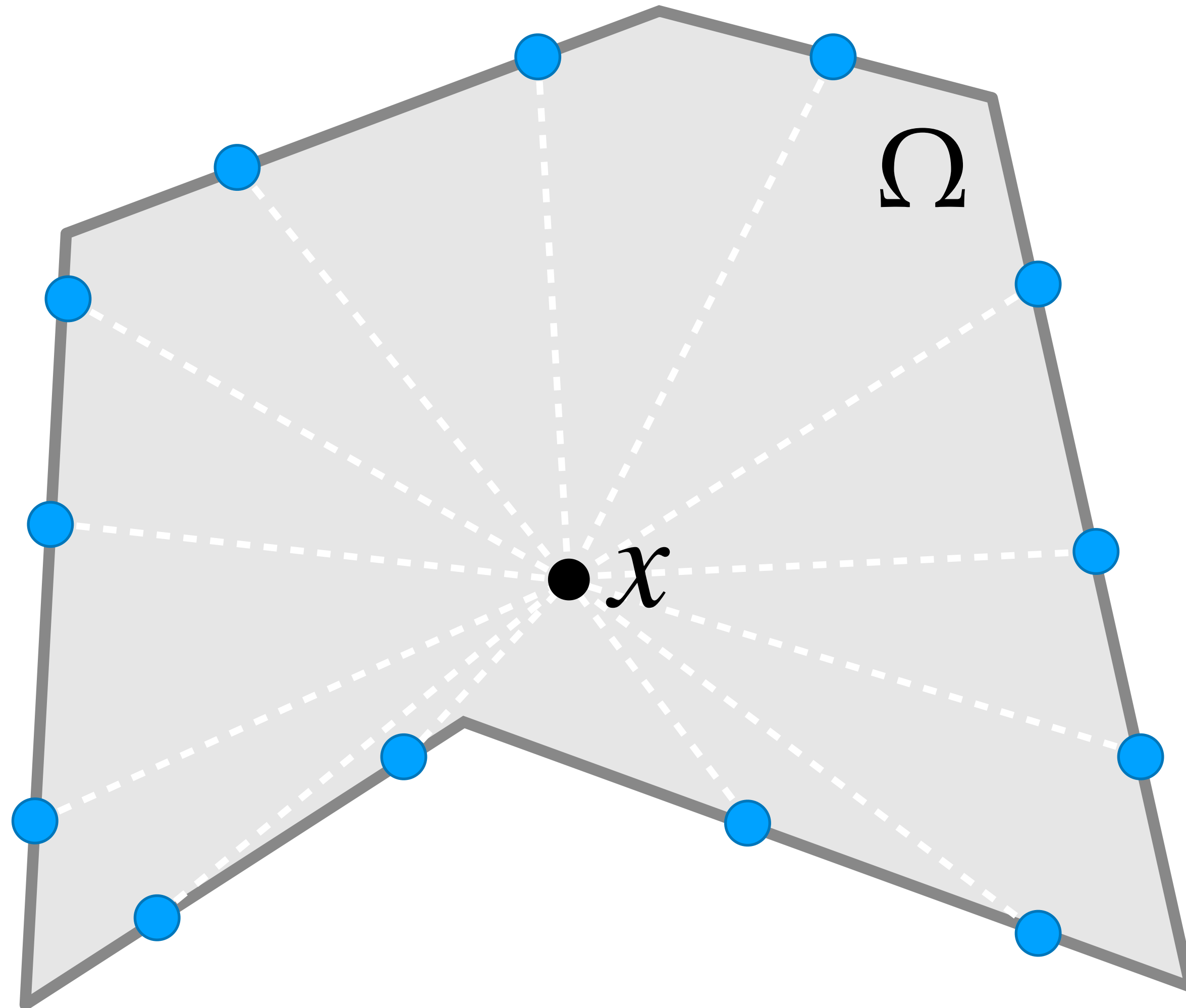


generate samples  
on boundary  $\partial\Omega$



use WoSt to  
estimate  $u$  &  $\frac{du}{dn}$

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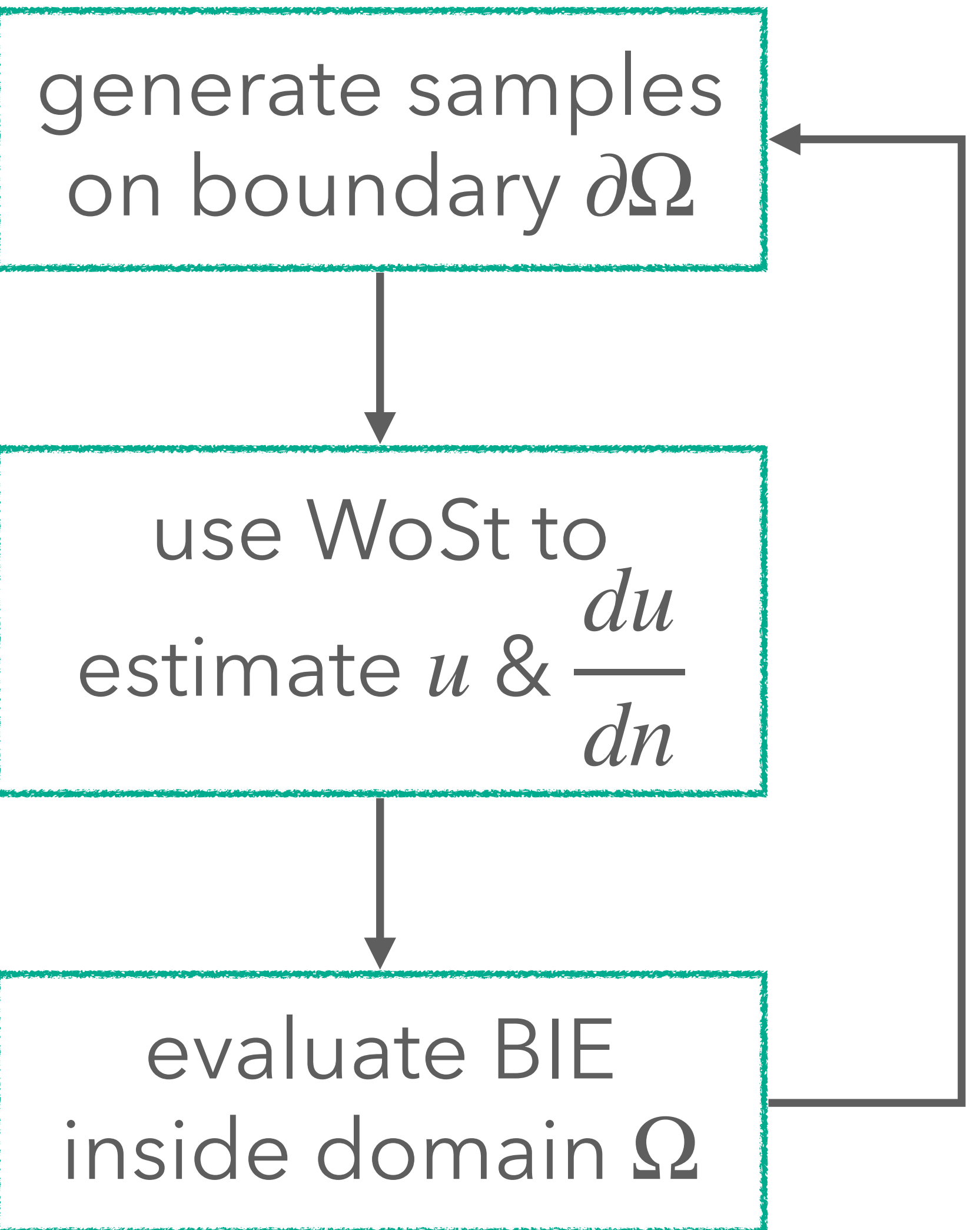
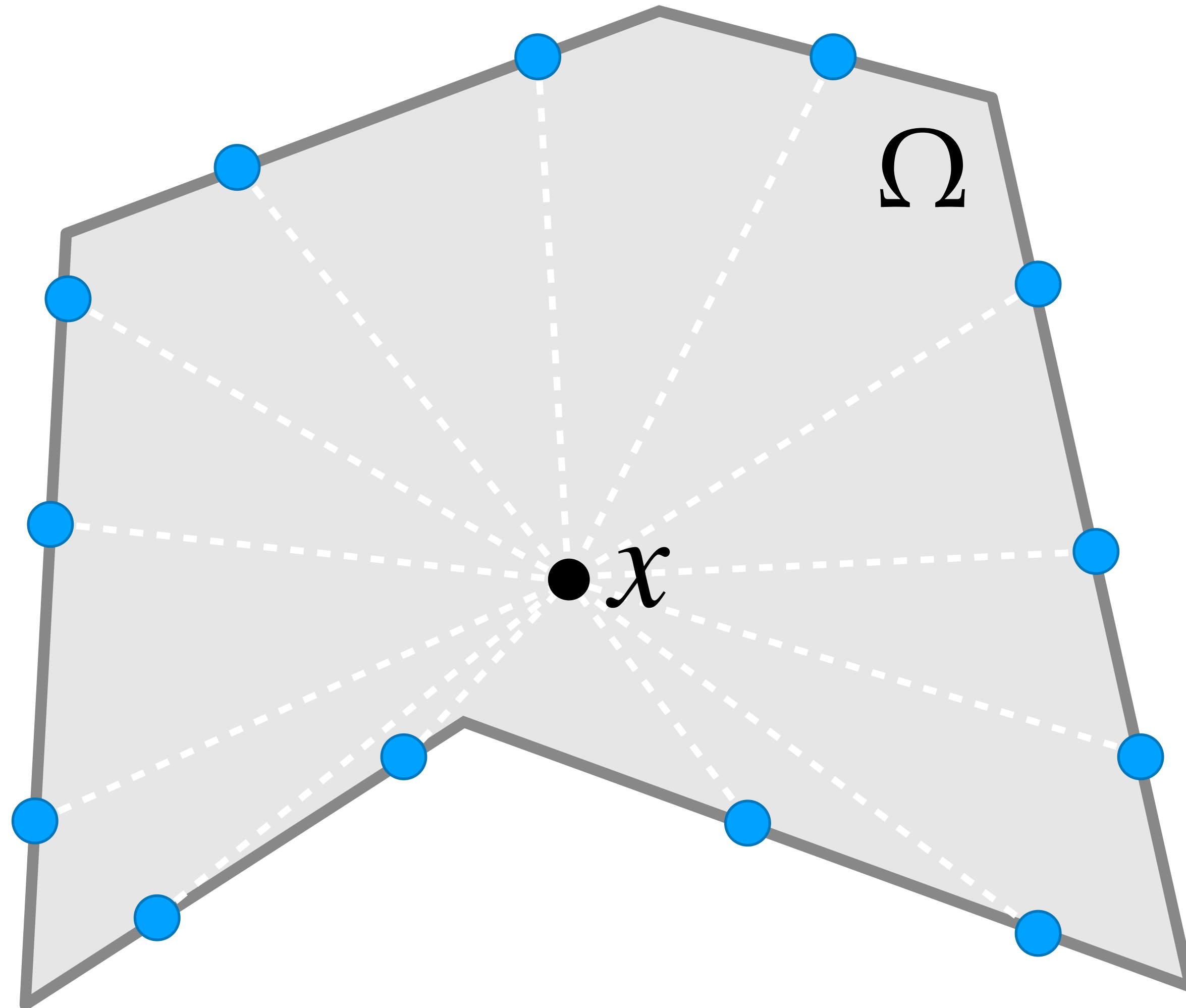


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on boundary  $\partial\Omega$

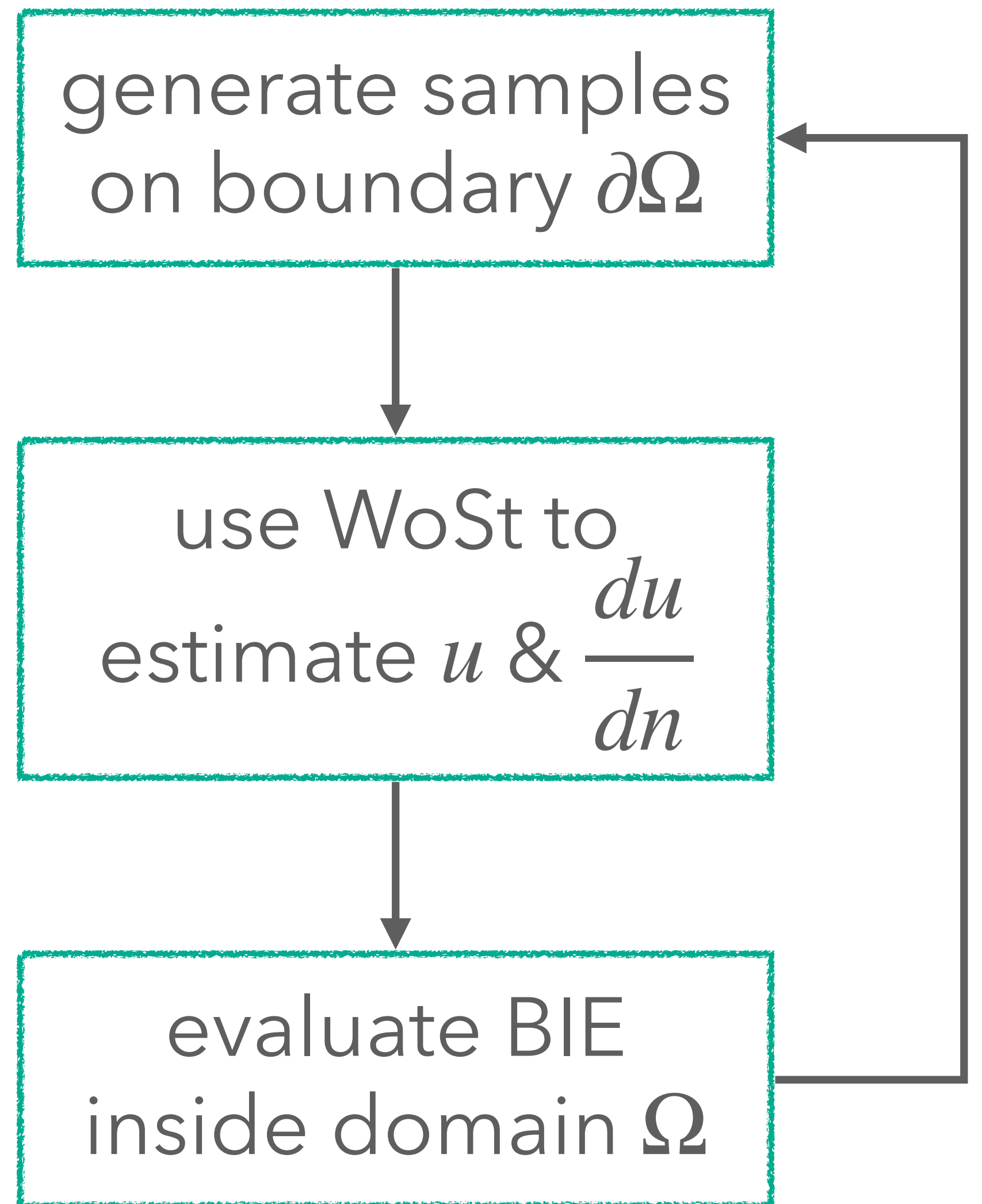
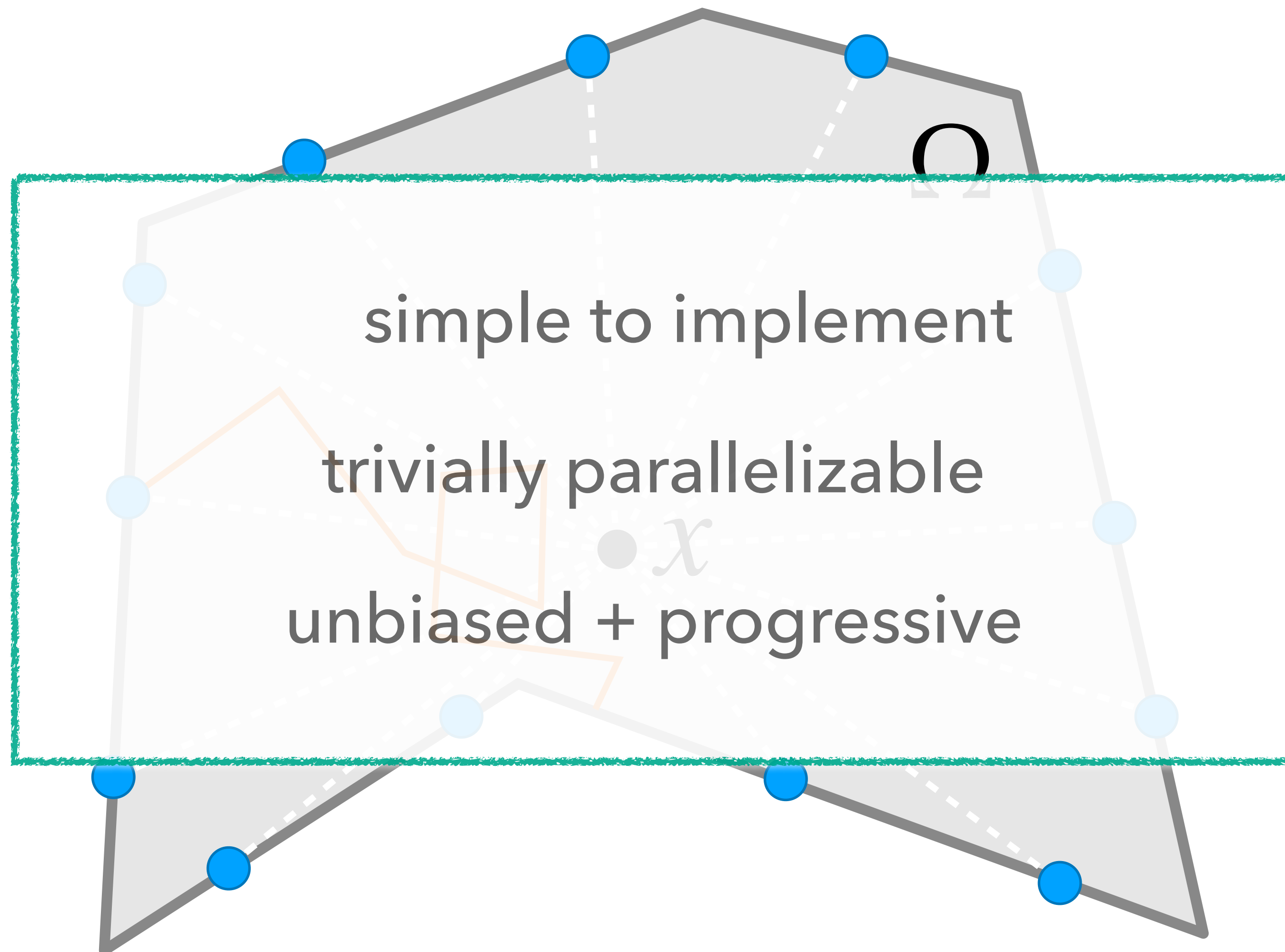
use WoSt to  
estimate  $u$  &  $\frac{du}{dn}$

evaluate BIE  
inside domain  $\Omega$

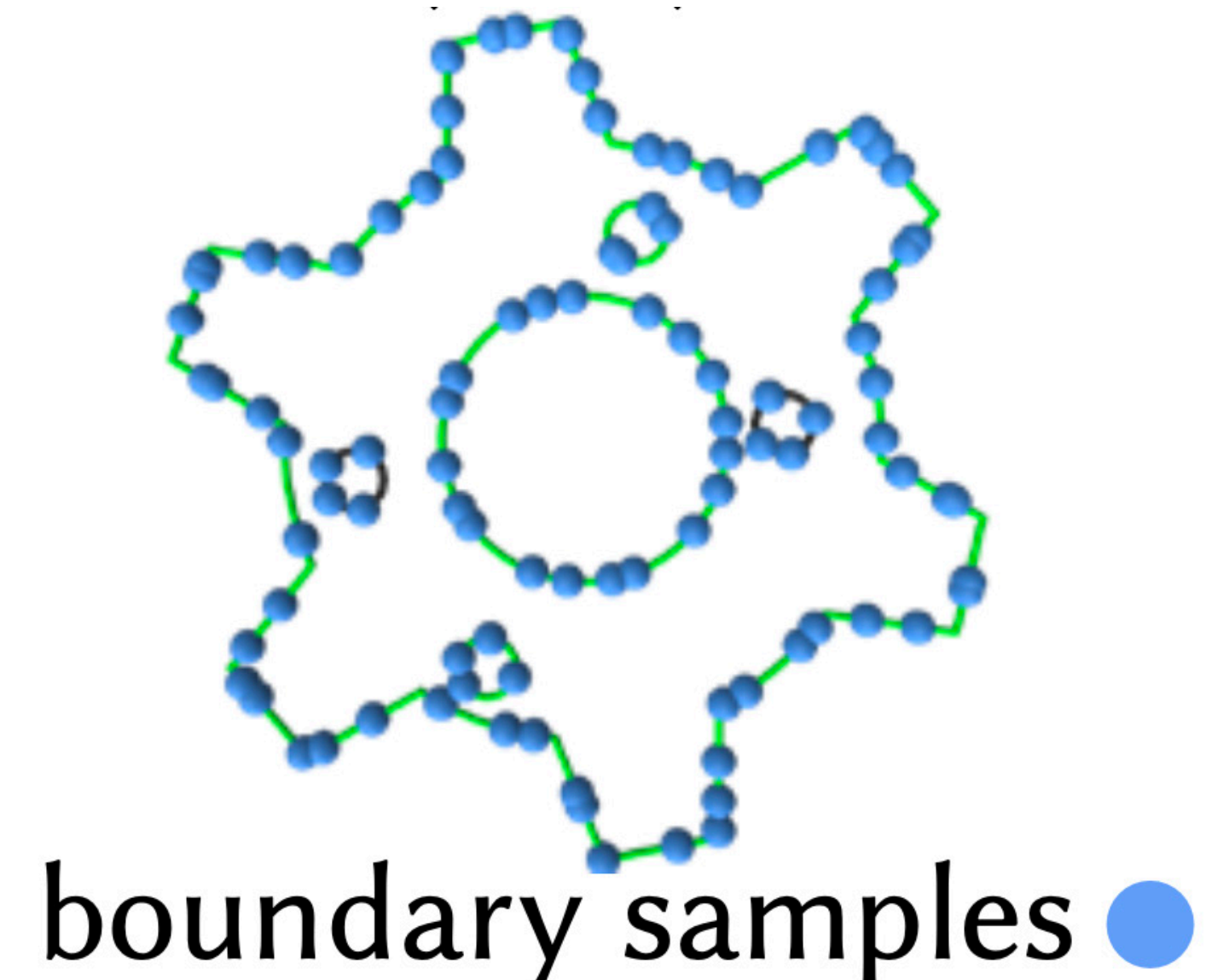
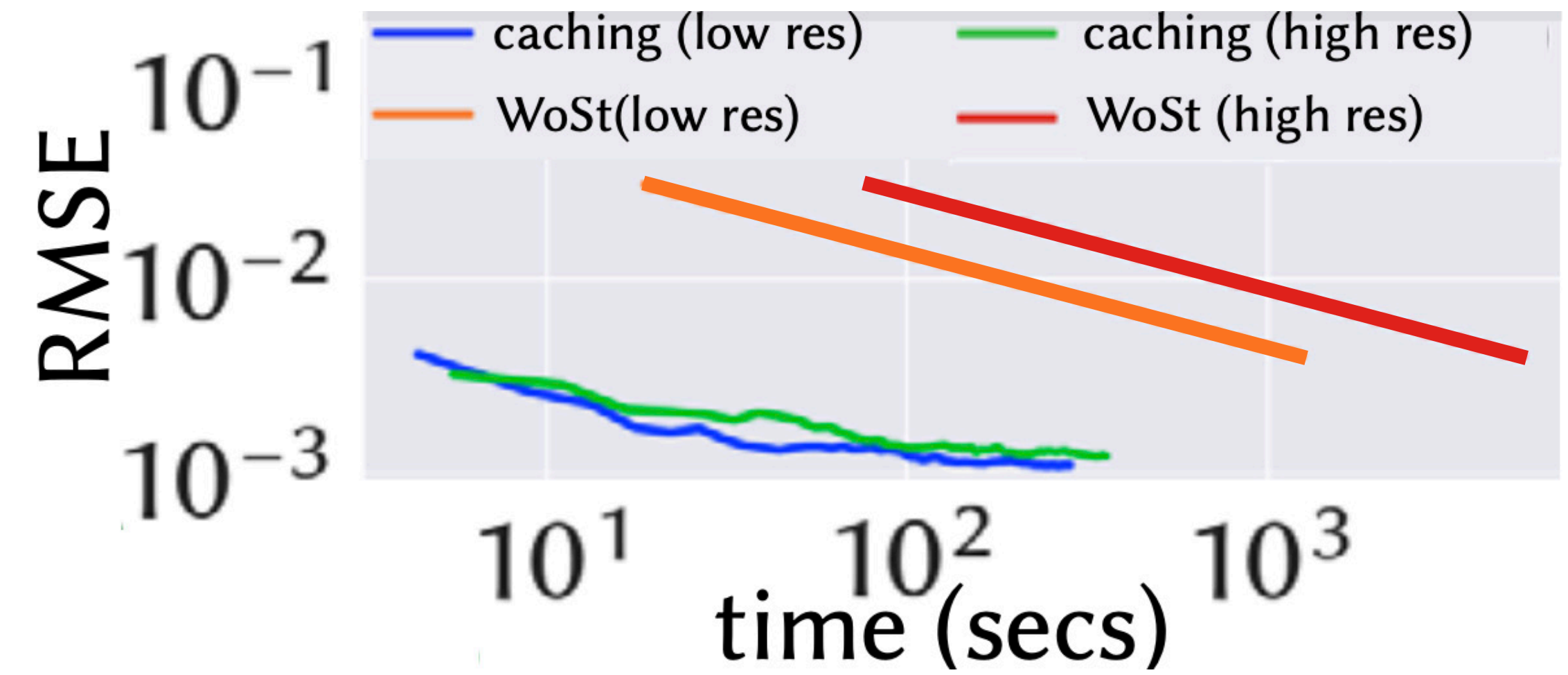
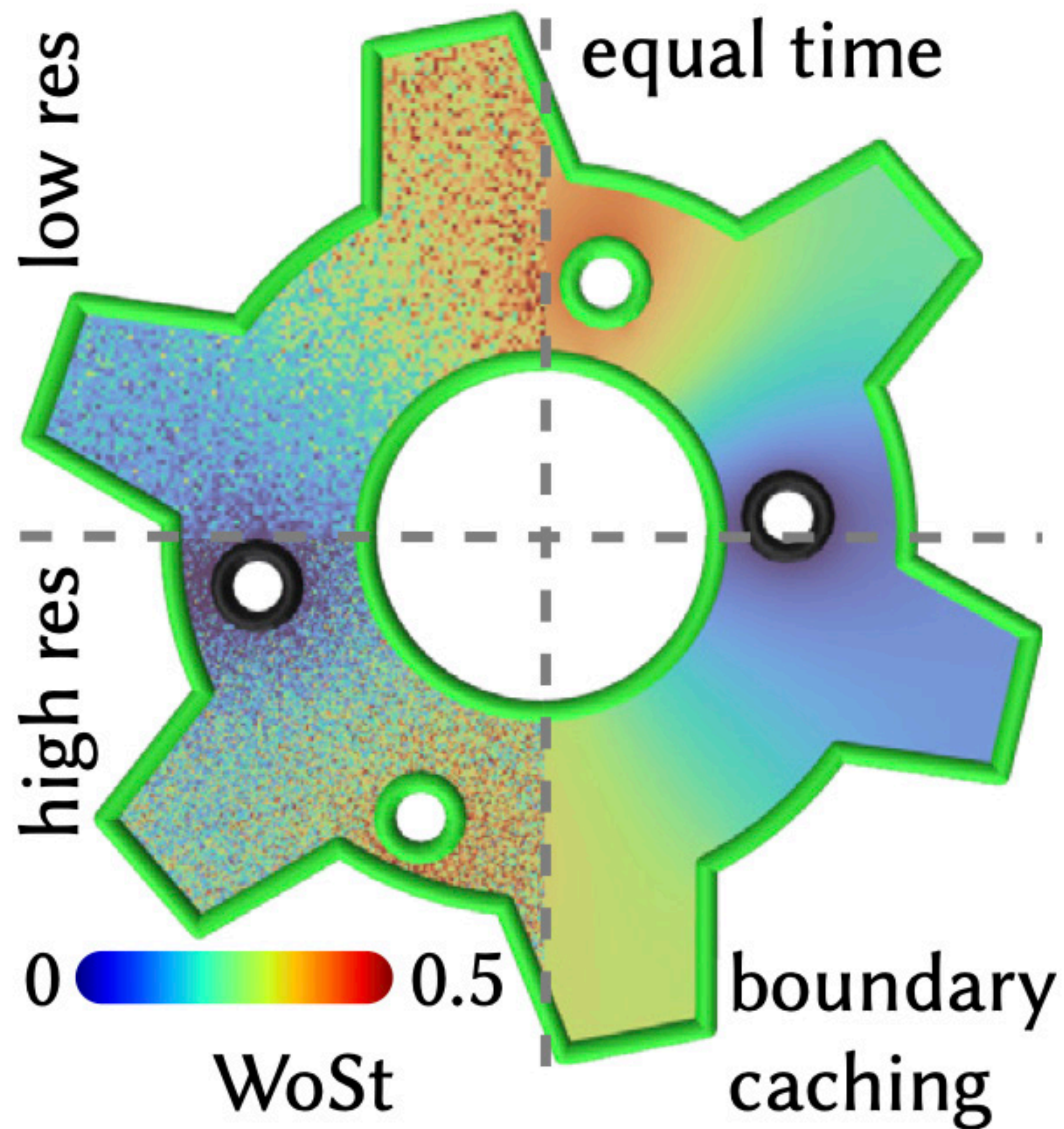
# Boundary Value Caching (BVC)



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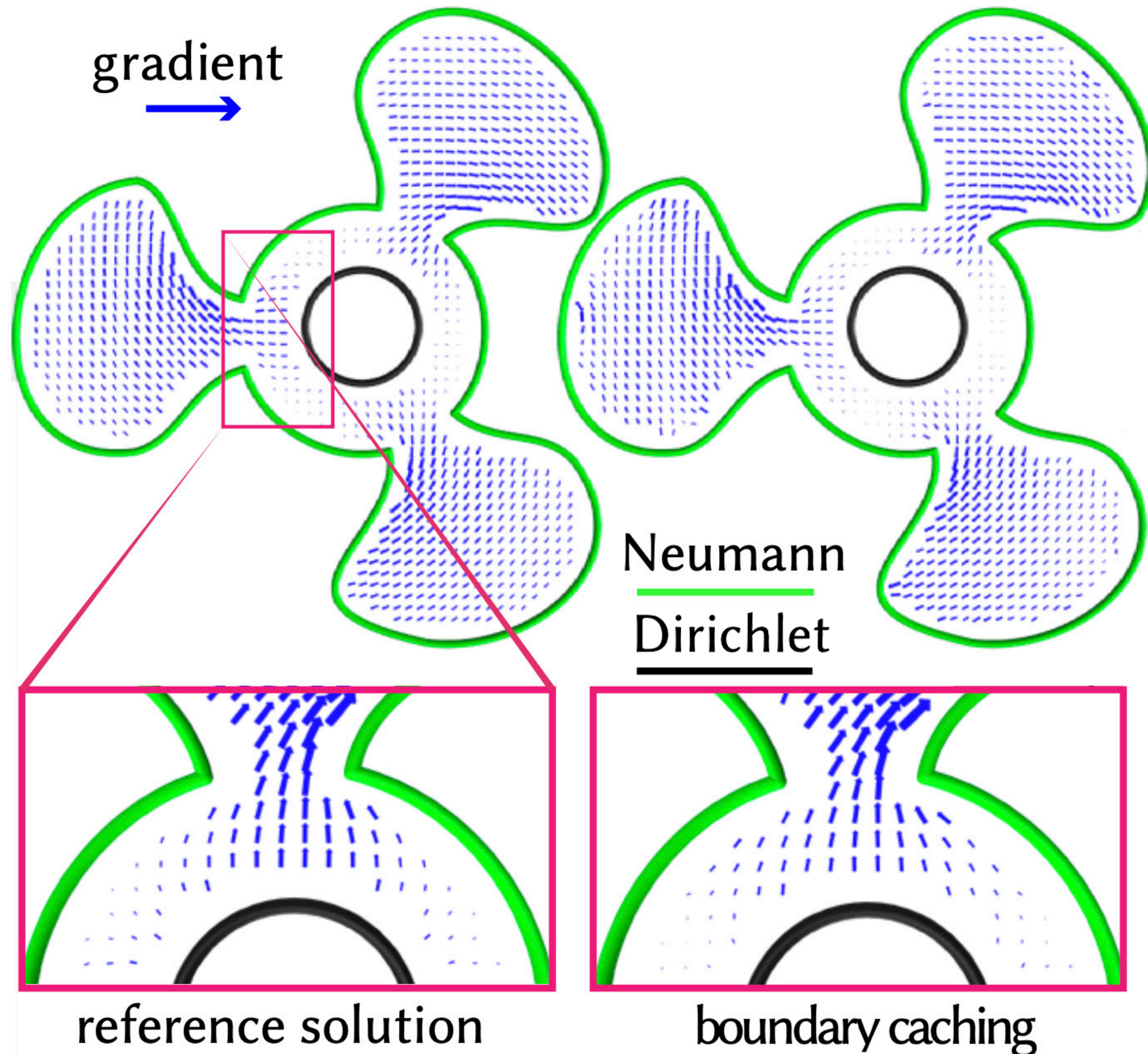


# Solution Estimates with BVC



# Gradient Estimates with BVC

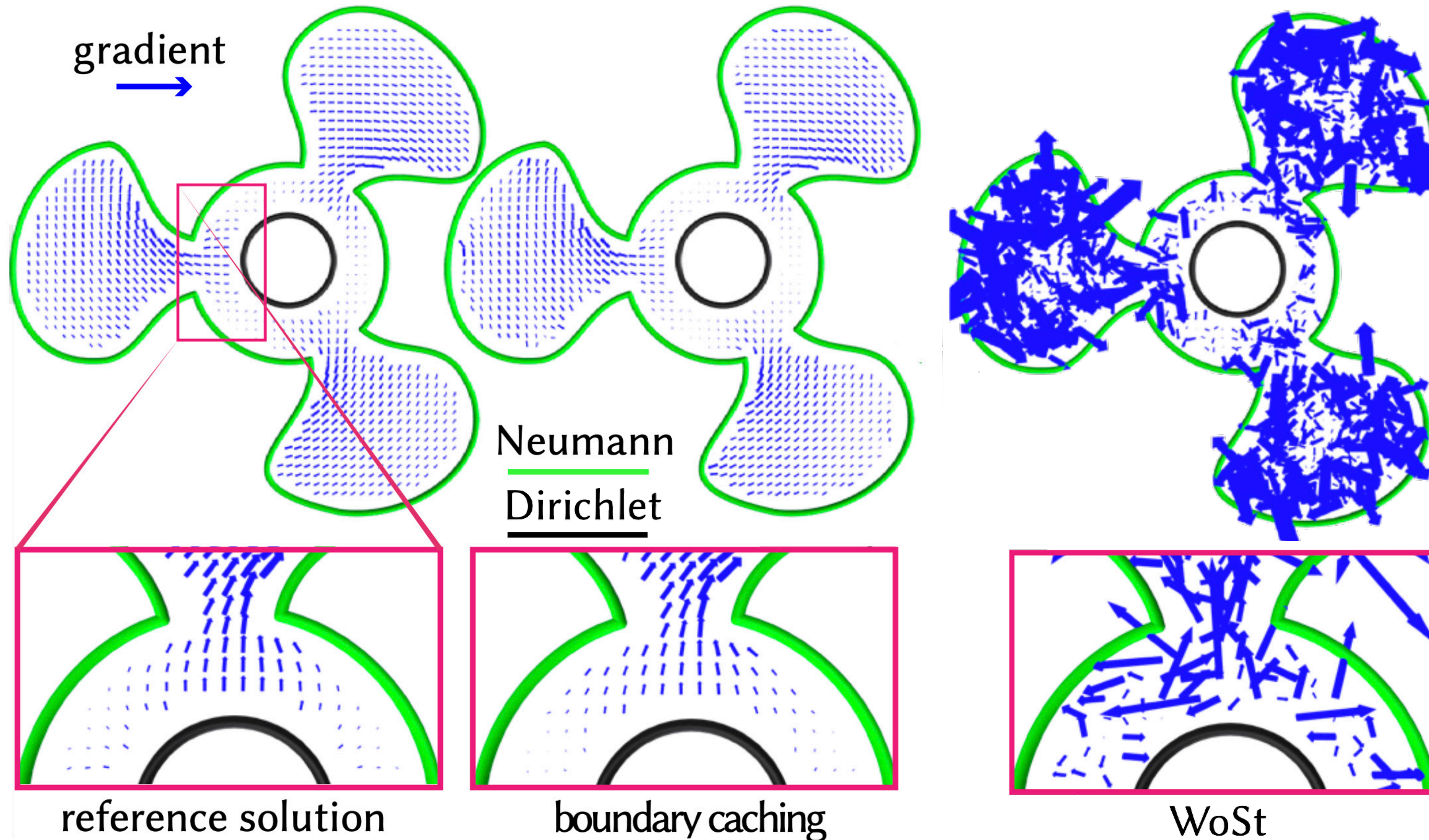
Can reuse **same** boundary cache for gradients!





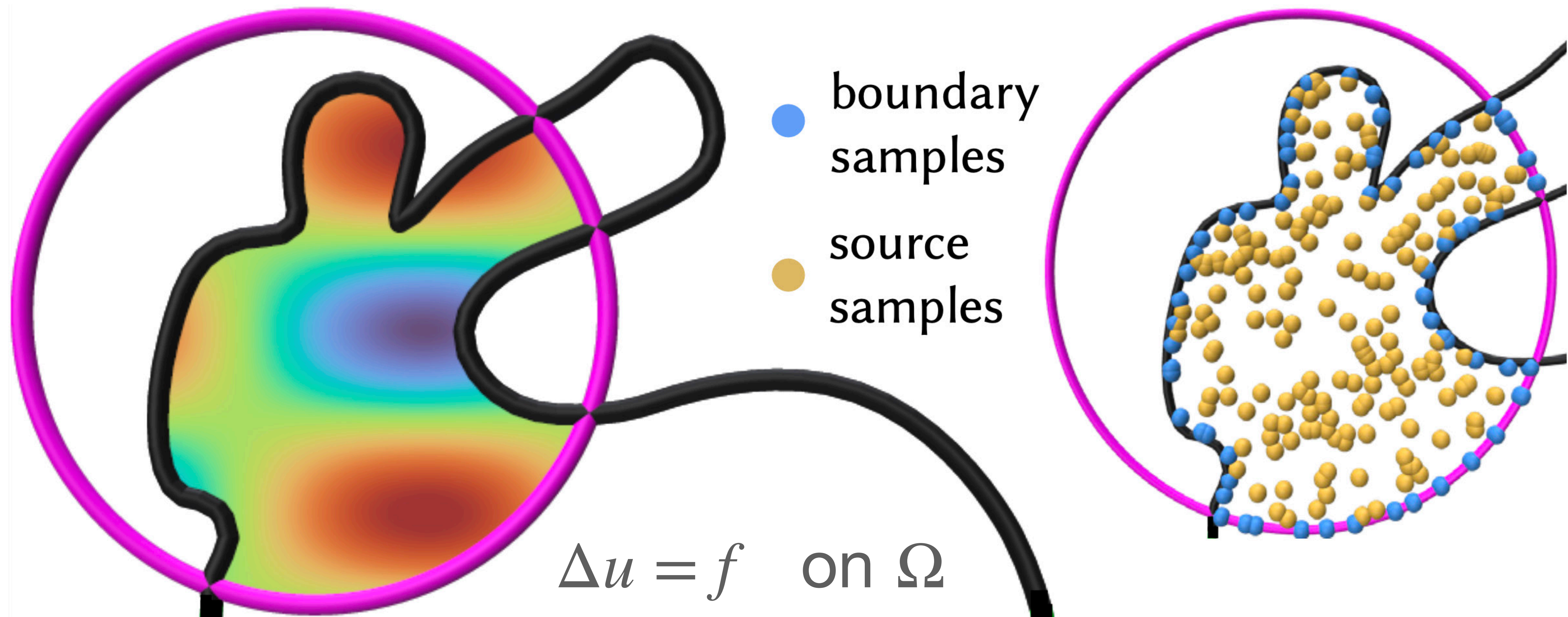
# Gradient Estimates with BVC

Can reuse **same** boundary cache for gradients!



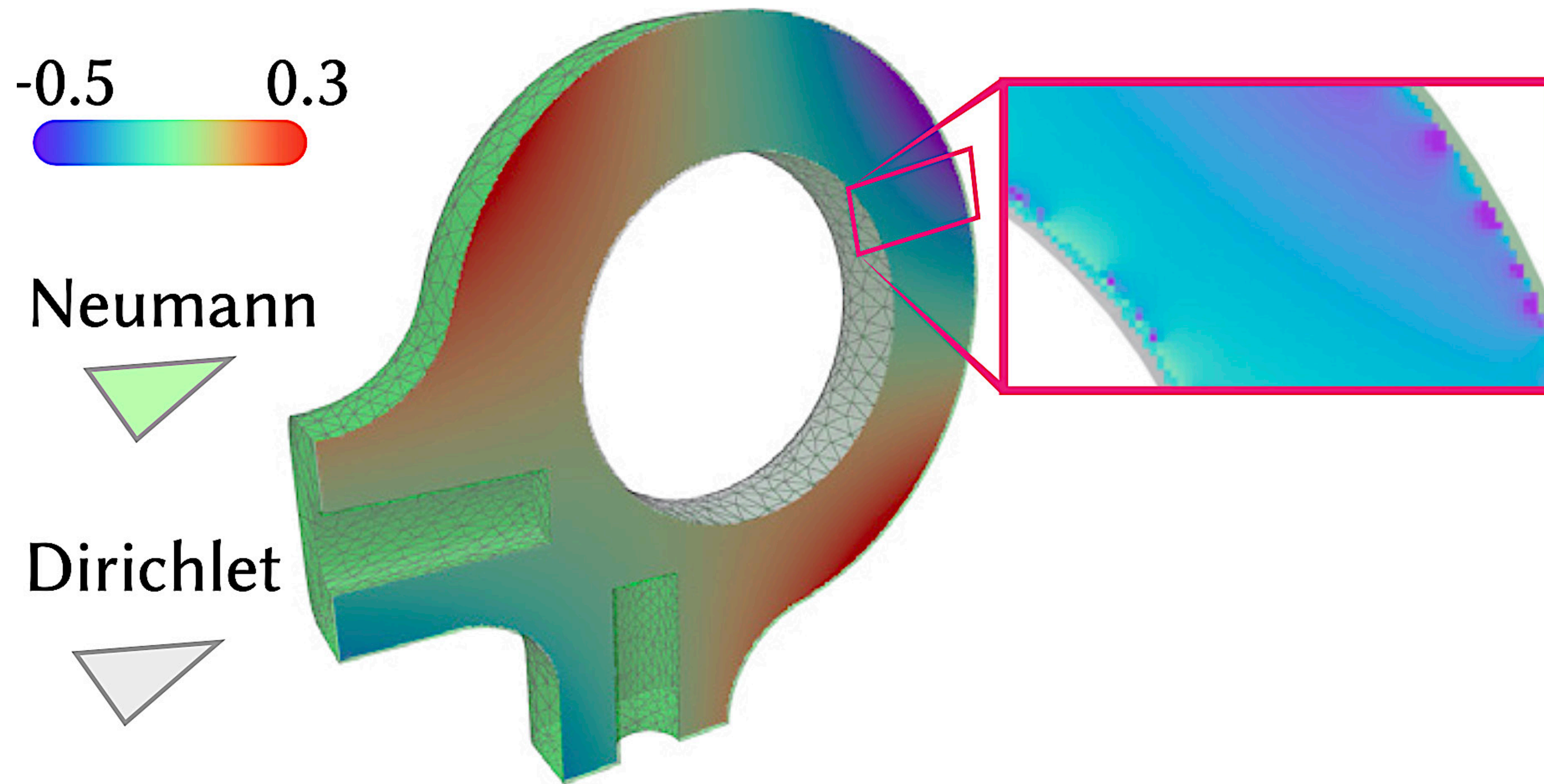
# Source Term

Generate cache samples for source values  $f$  **inside** domain:  
**no random walks needed**



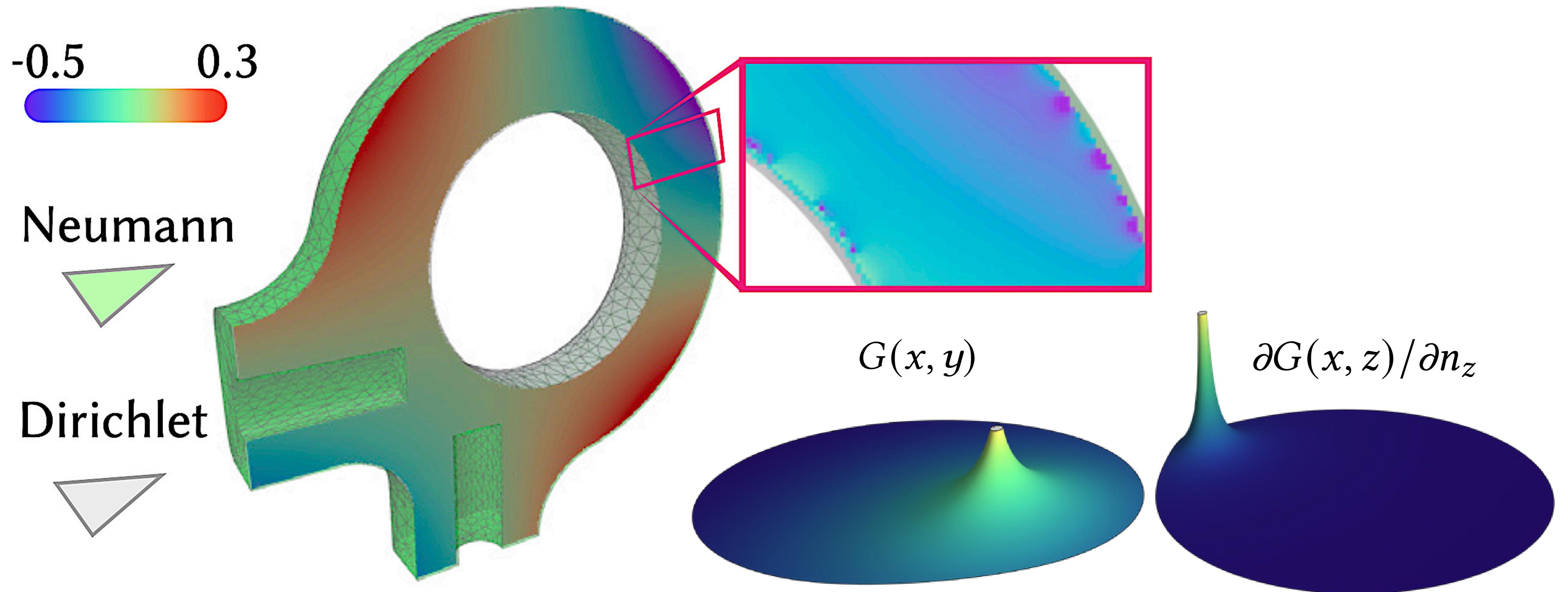
# Singularities

Artifacts near the boundary due to **lack of importance sampling**



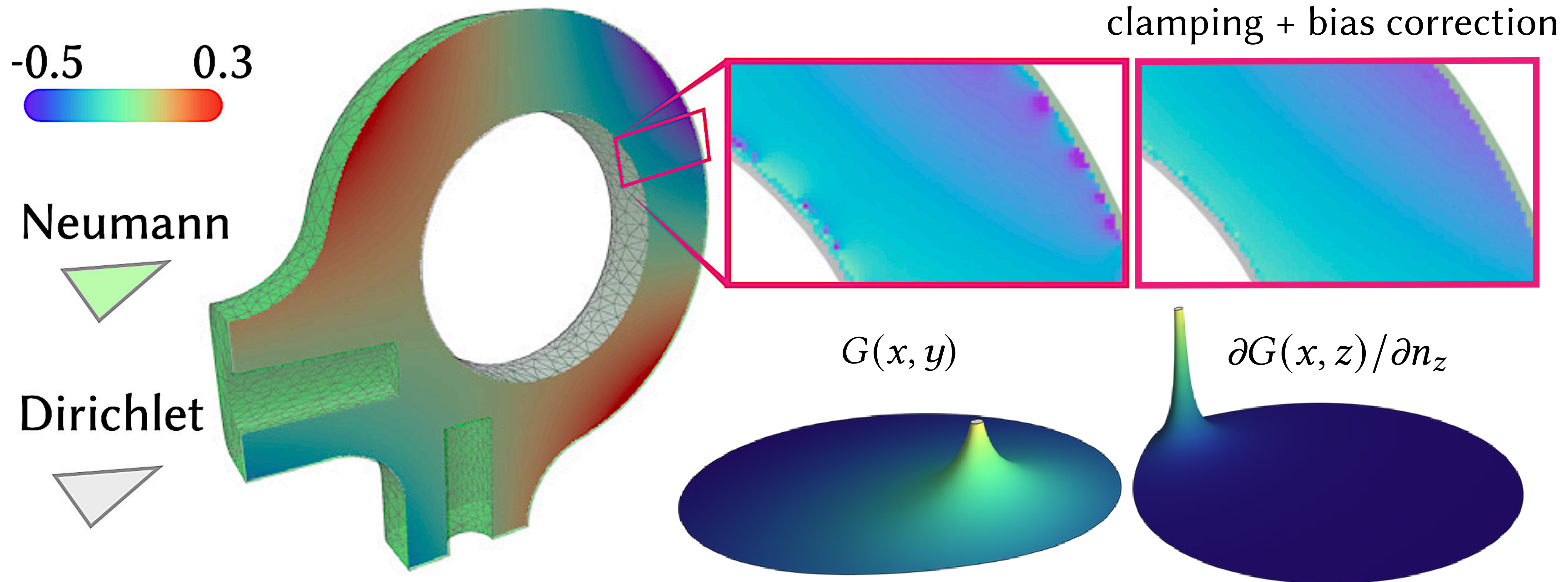
# Singularities

Artifacts near the boundary due to **lack of importance sampling**



# Singularities

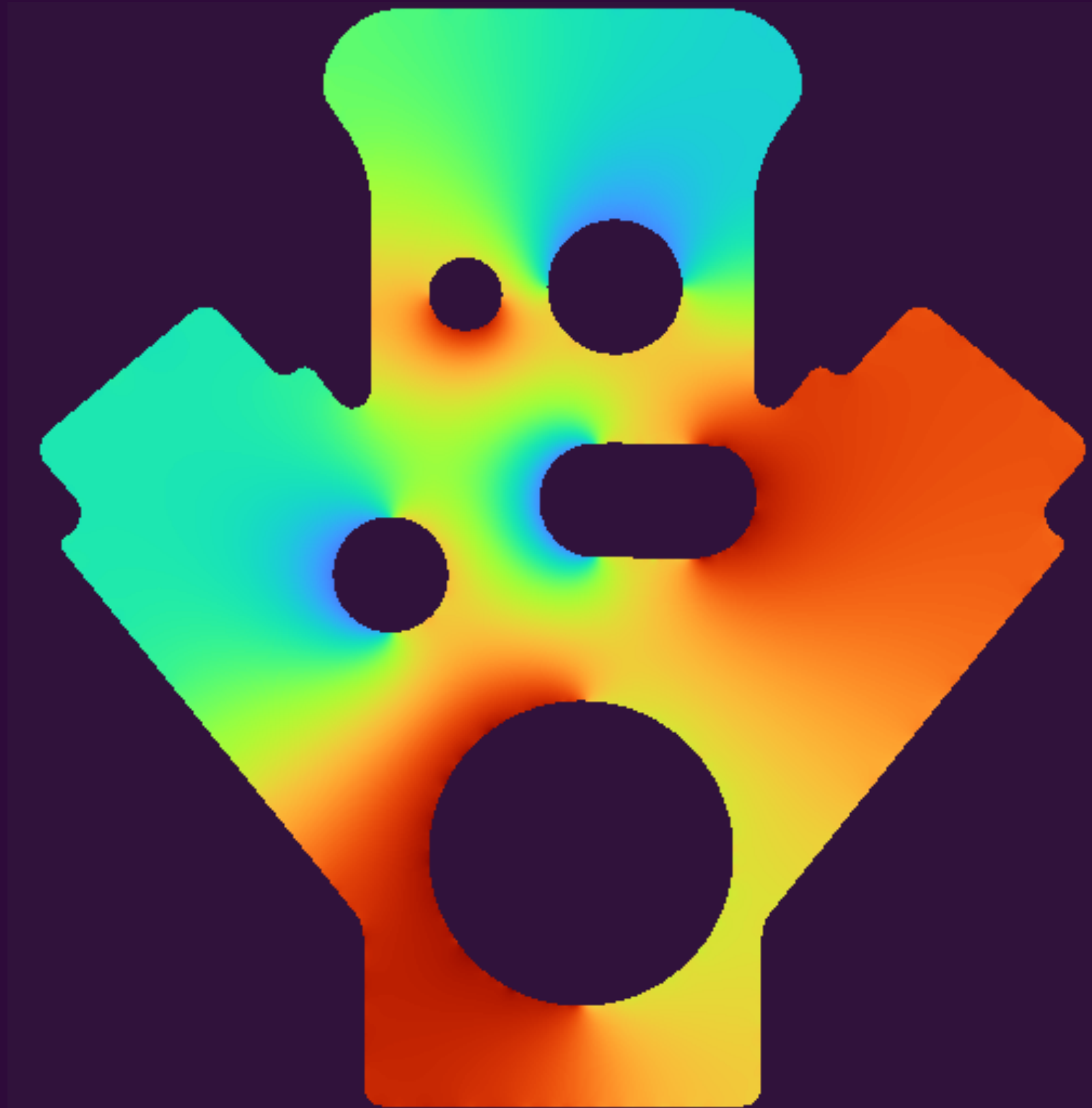
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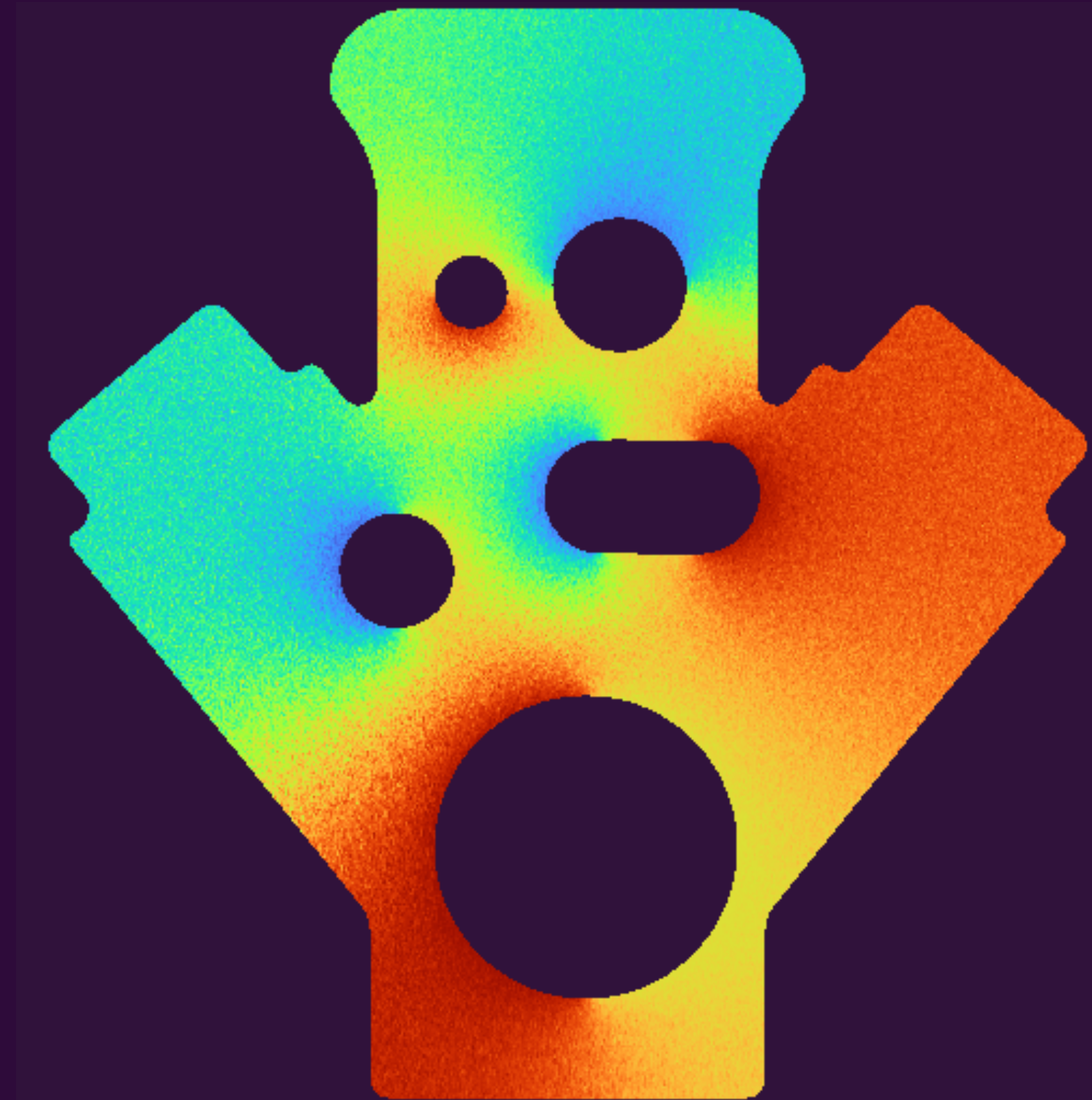


# VALIDATION & COMPARISONS

# Benefits of BVC



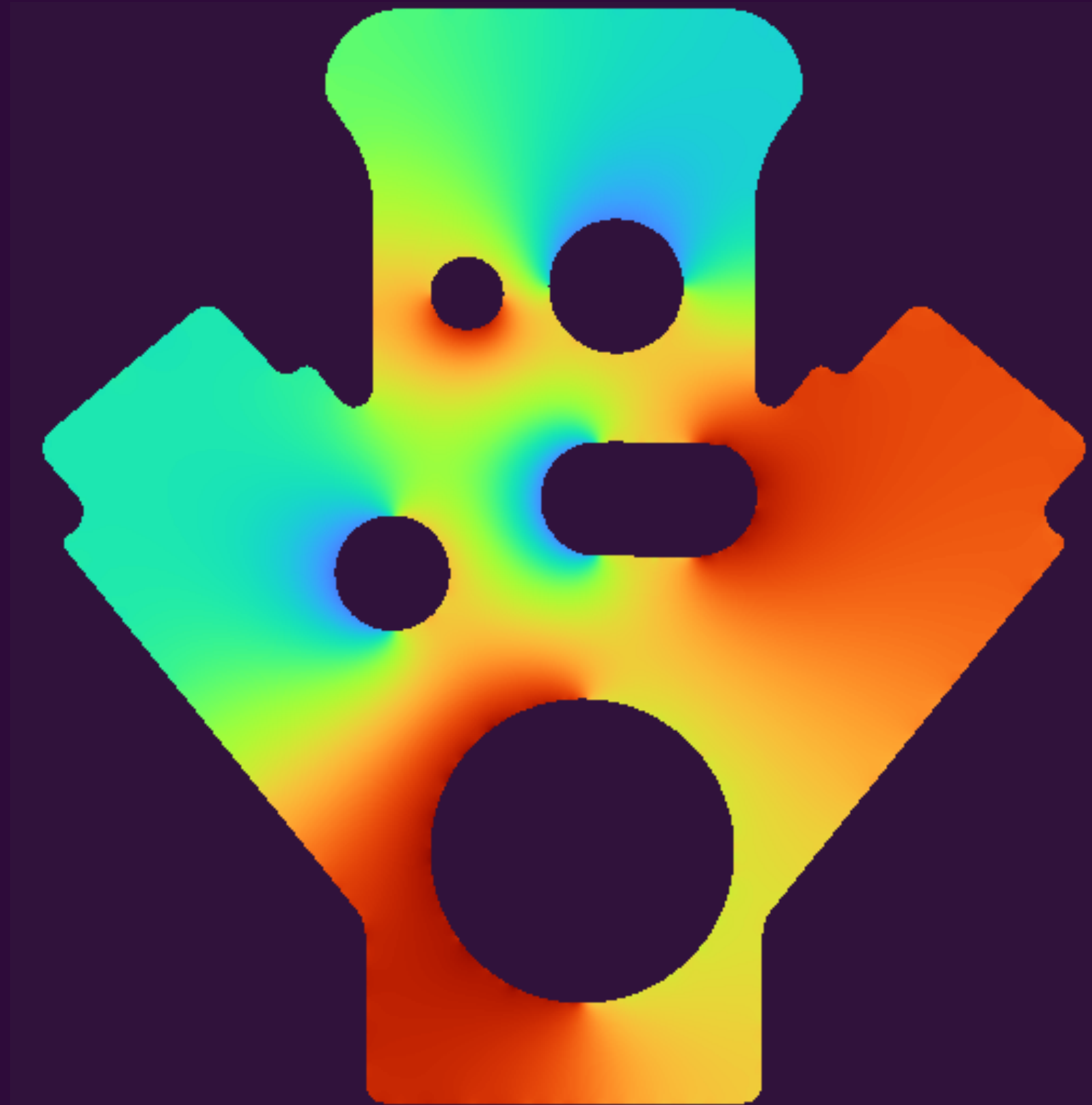
Boundary Value Caching



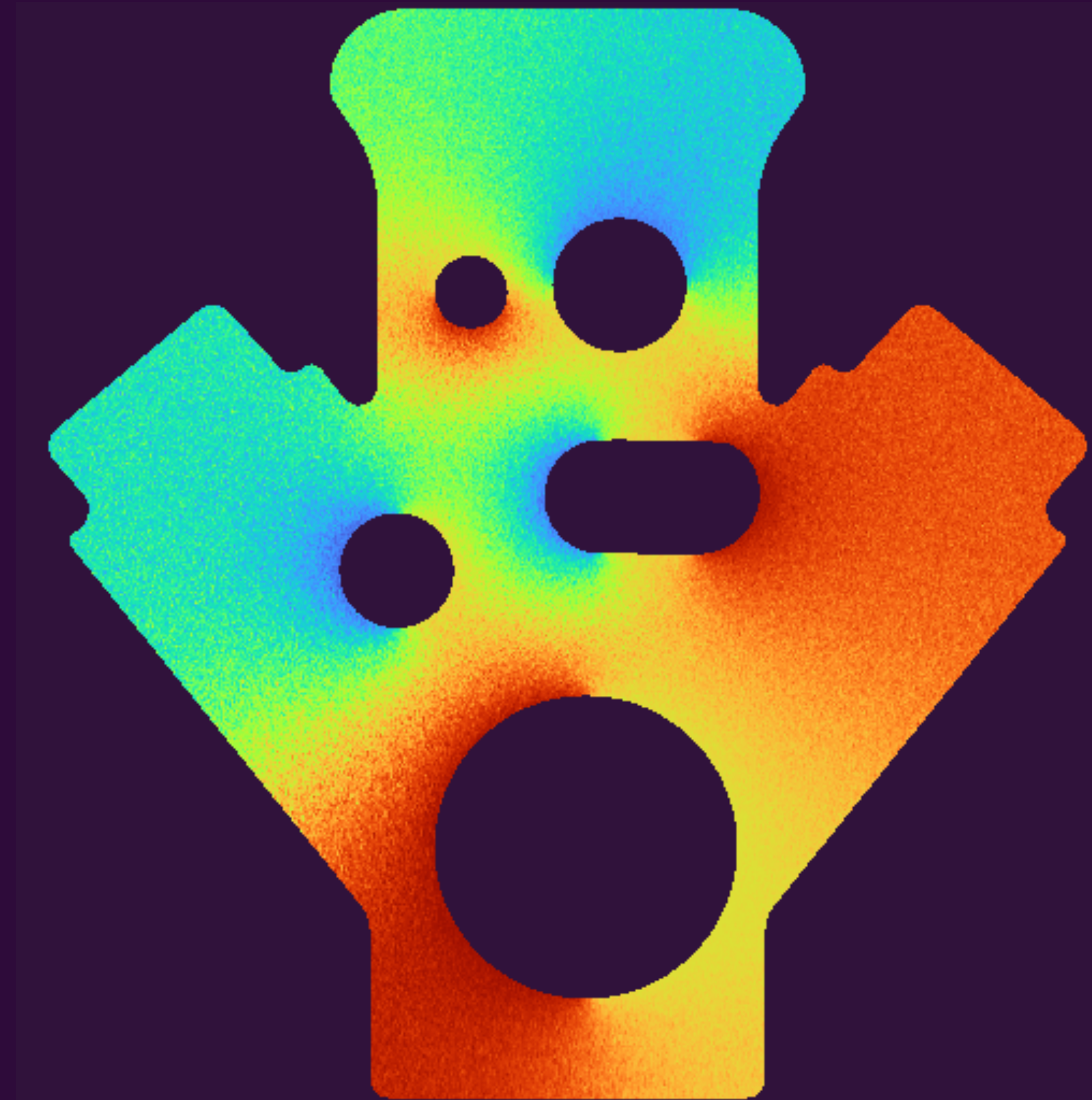
Walk on Stars



# Benefits of BVC



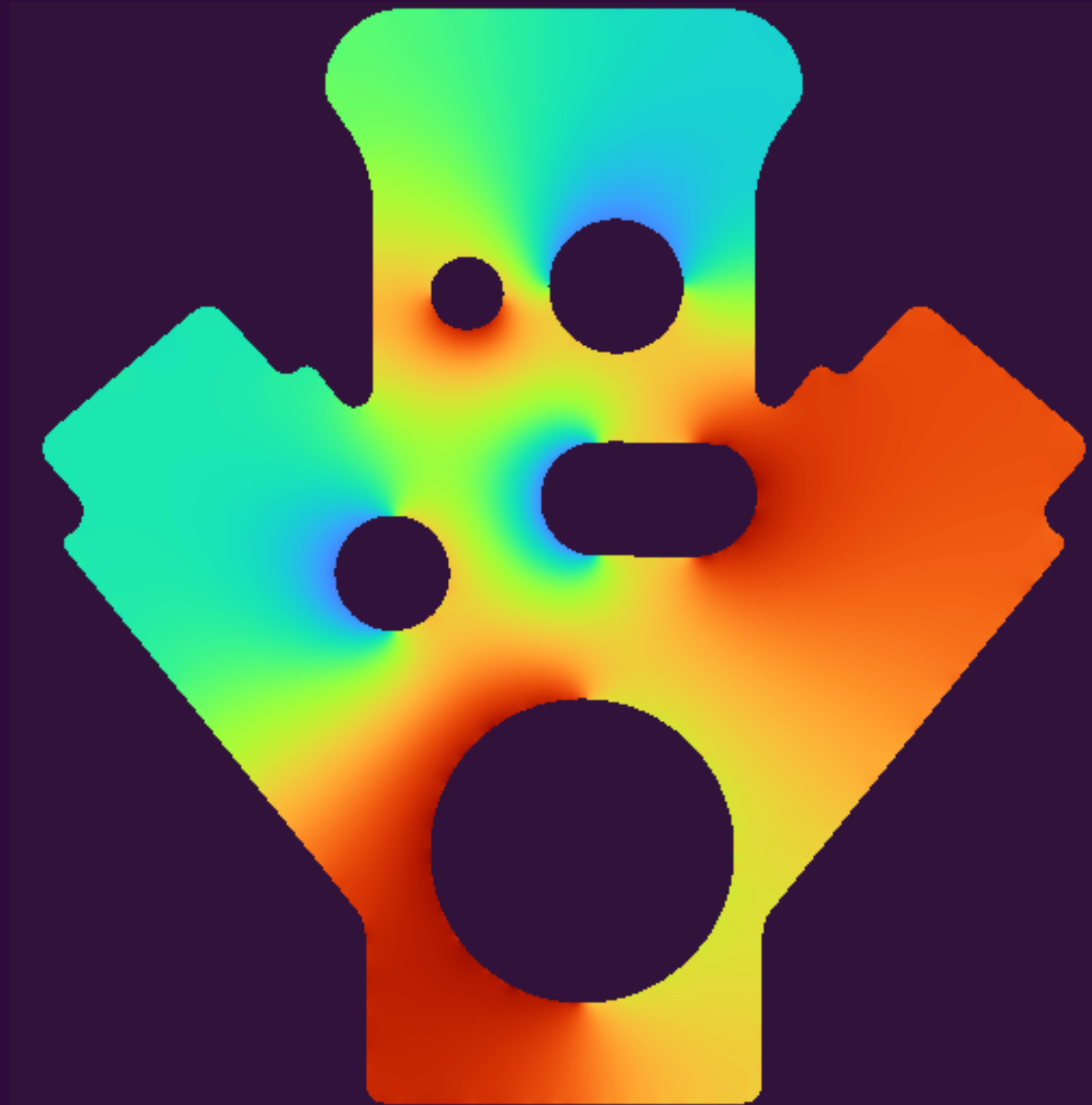
Boundary Value Caching



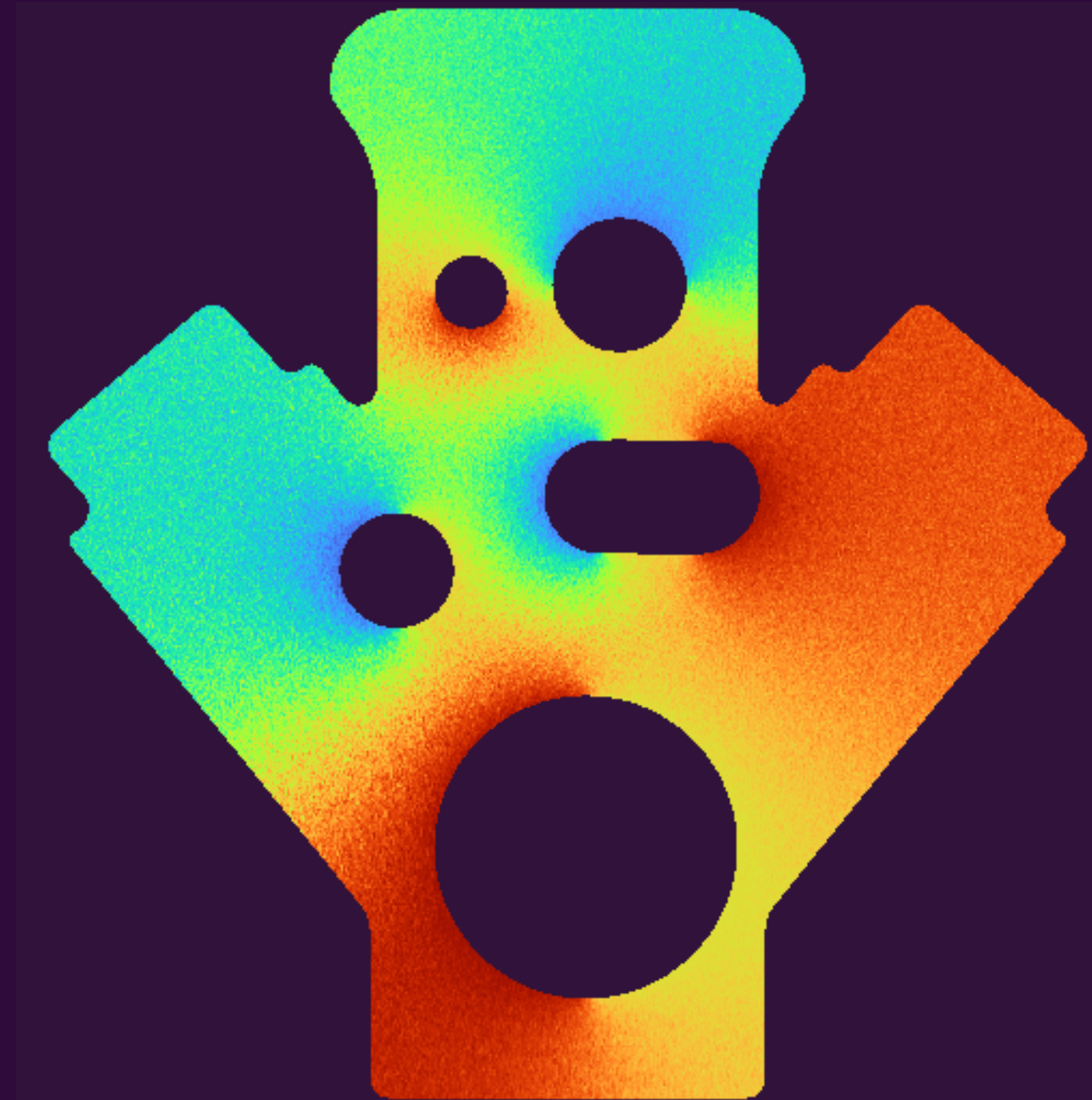
Walk on Stars

Improved run-time efficiency (sharing global information)

# Benefits of BVC



Boundary Value Caching

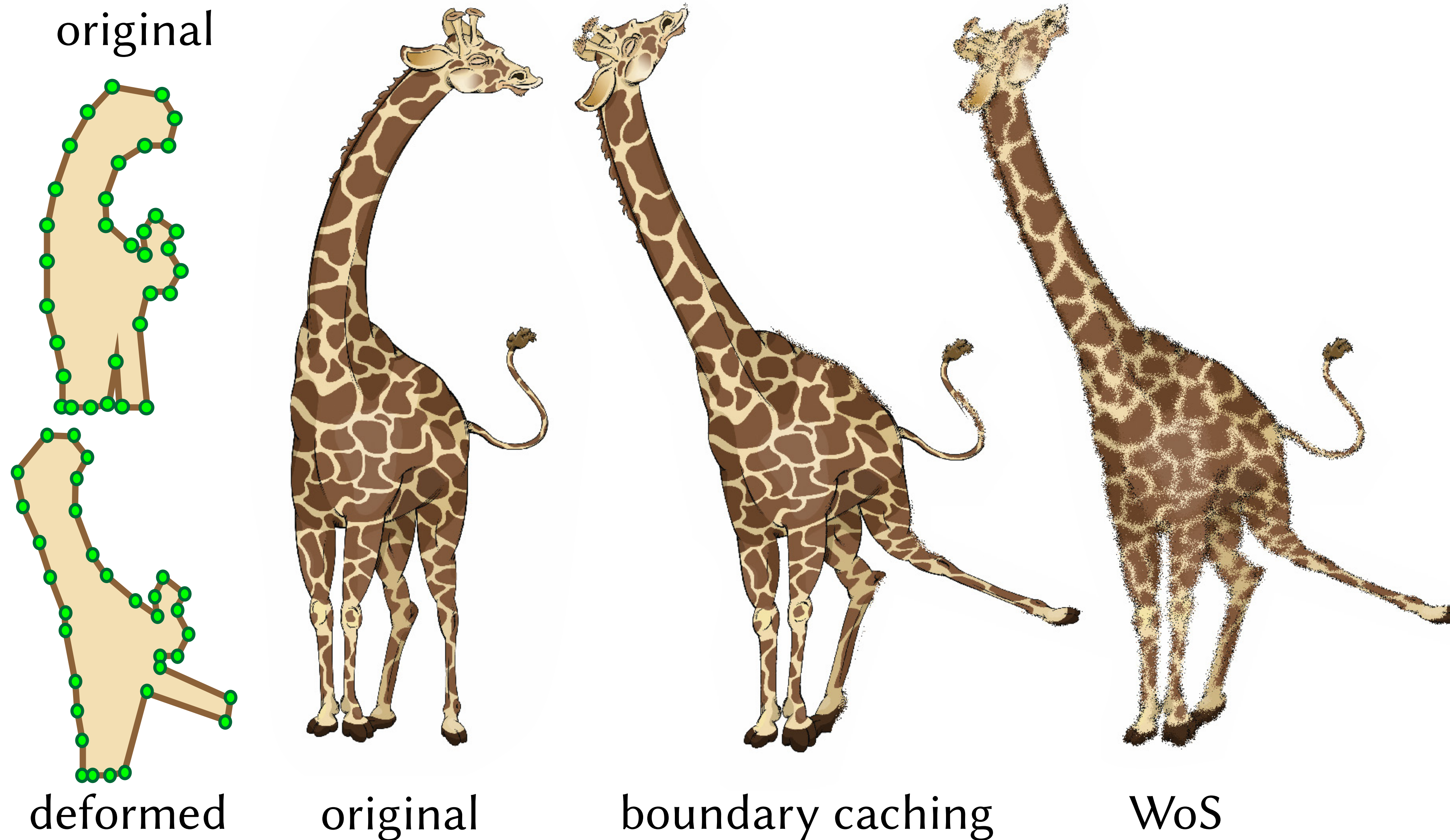


Walk on Stars

Improved run-time efficiency (sharing global information)

Suppressed noise (due to correlation)

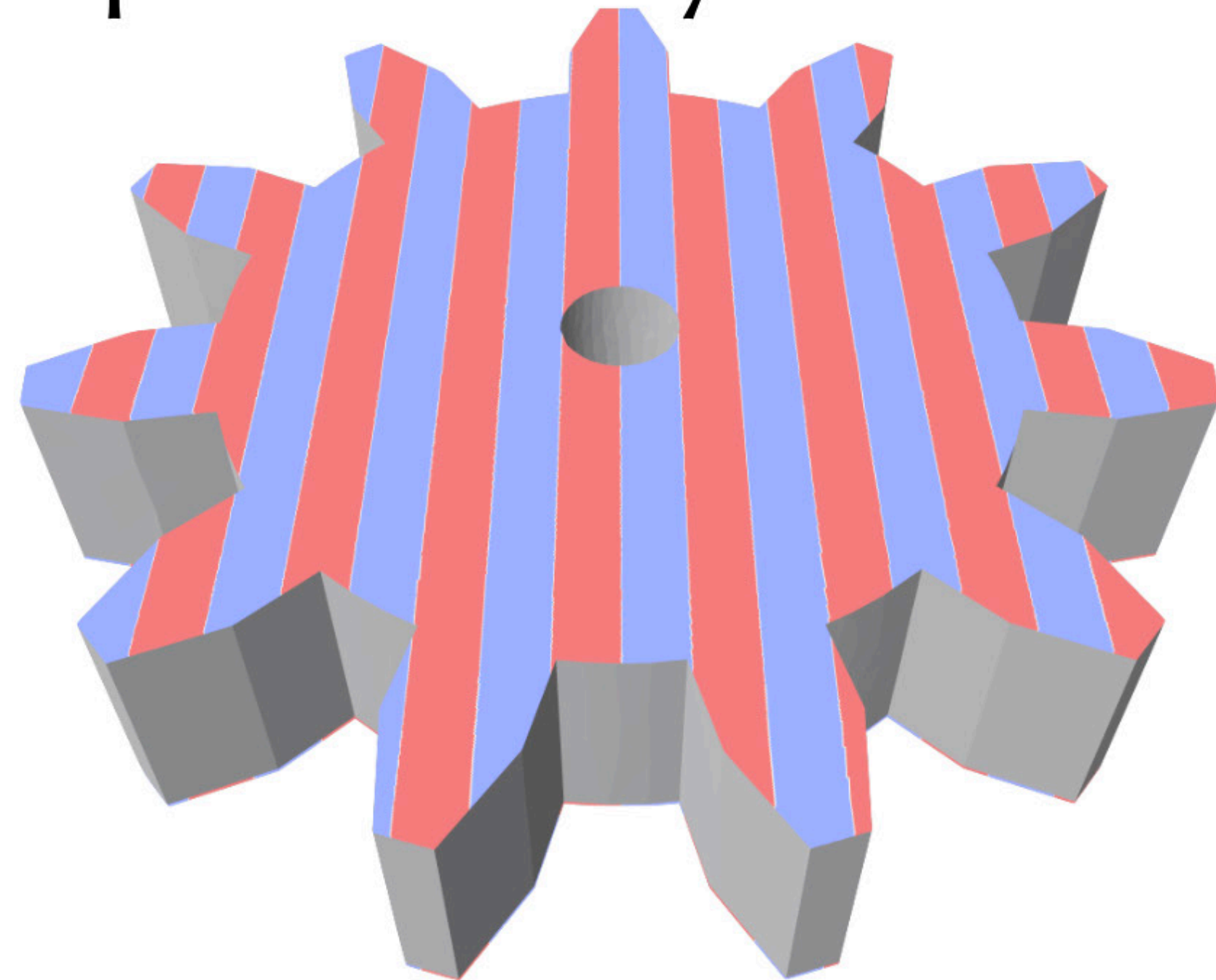
# Harmonic Interpolation of Texture Coordinates



# Comparison to Boundary Element Method

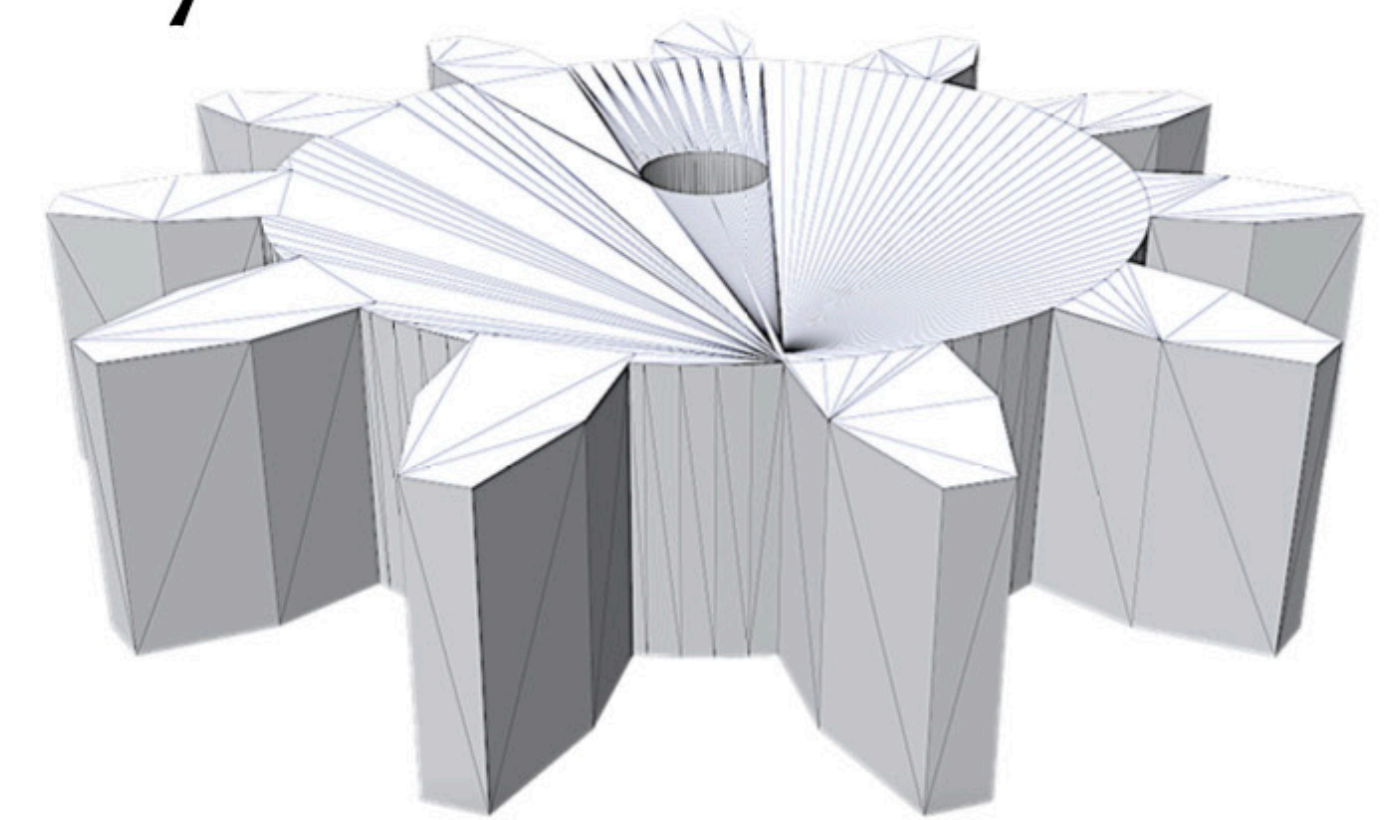
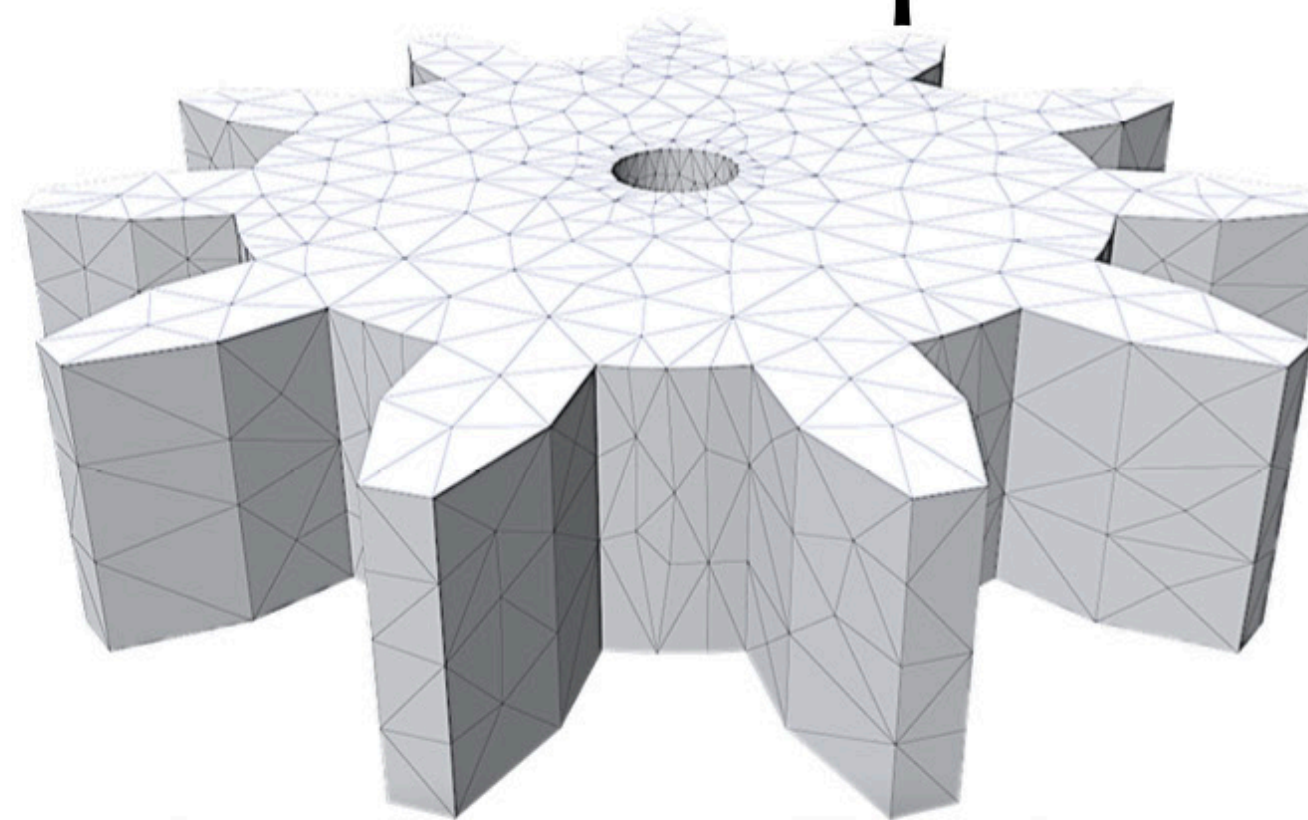
Like WoSt, BVC is **not** affected by quality of discretization

Input boundary conditions



-1  1 Dirichlet  
 0 Neumann

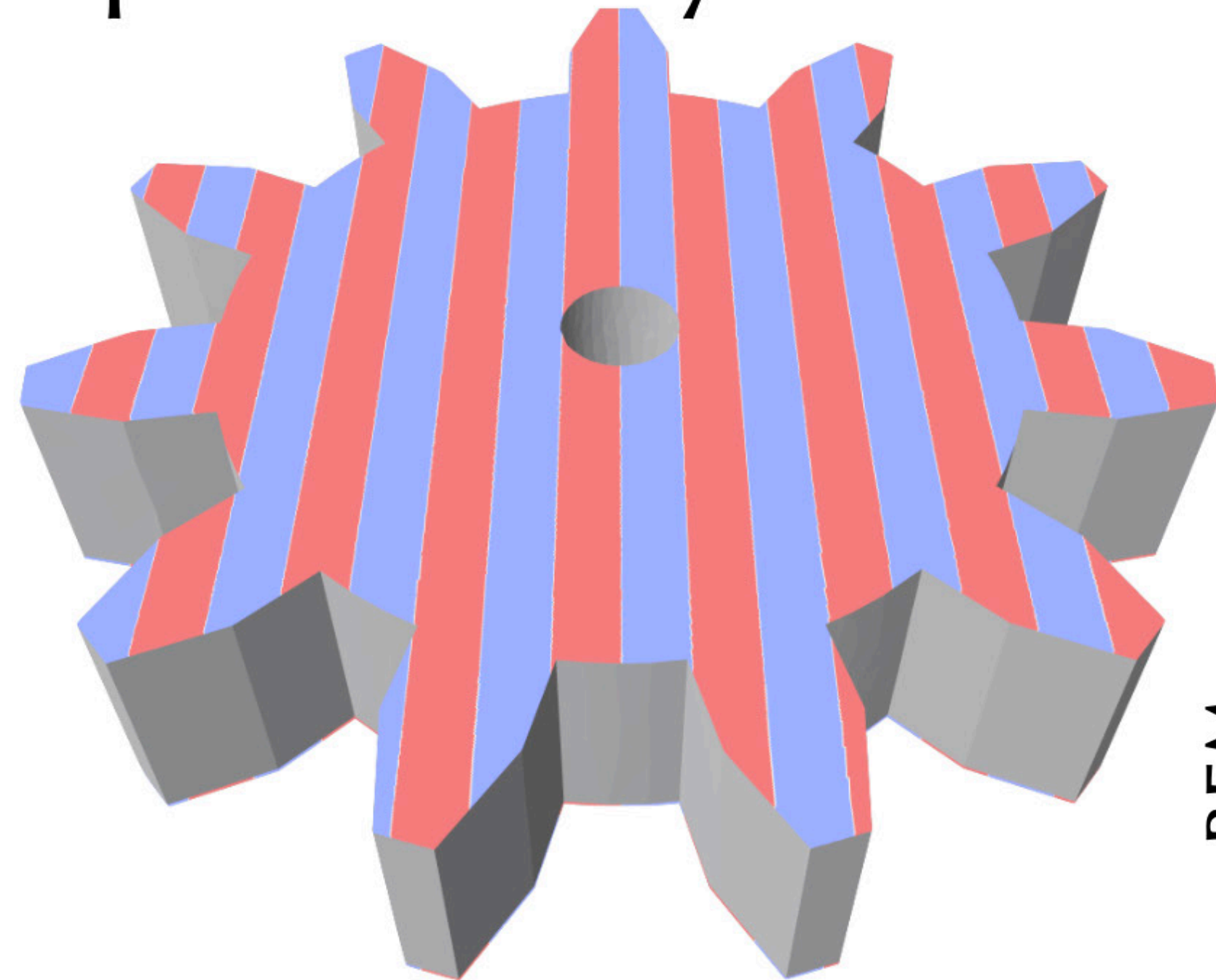
Input boundary mesh



# Comparison to Boundary Element Method

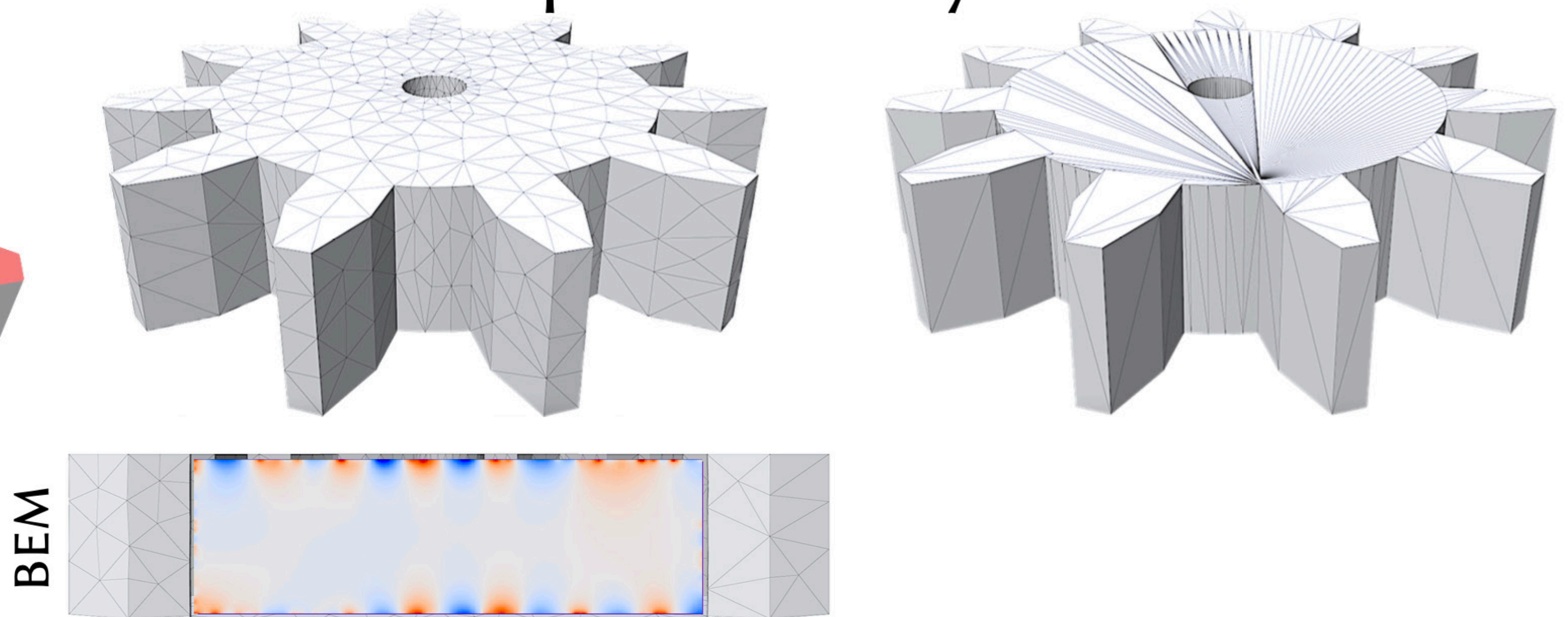
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Input boundary conditions



-1 1 Dirichlet  
0 Neumann

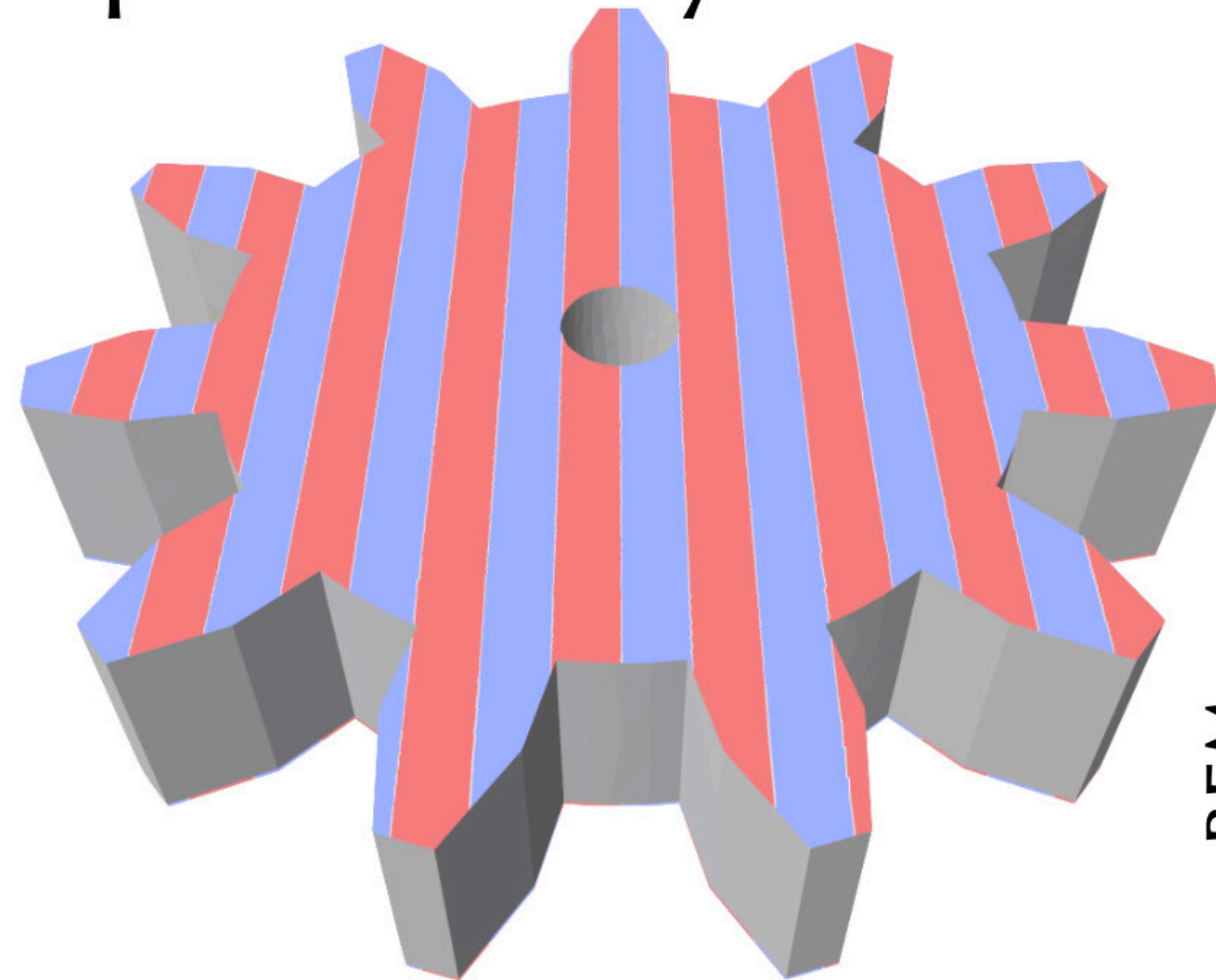
Input boundary mesh



# Comparison to Boundary Element Method

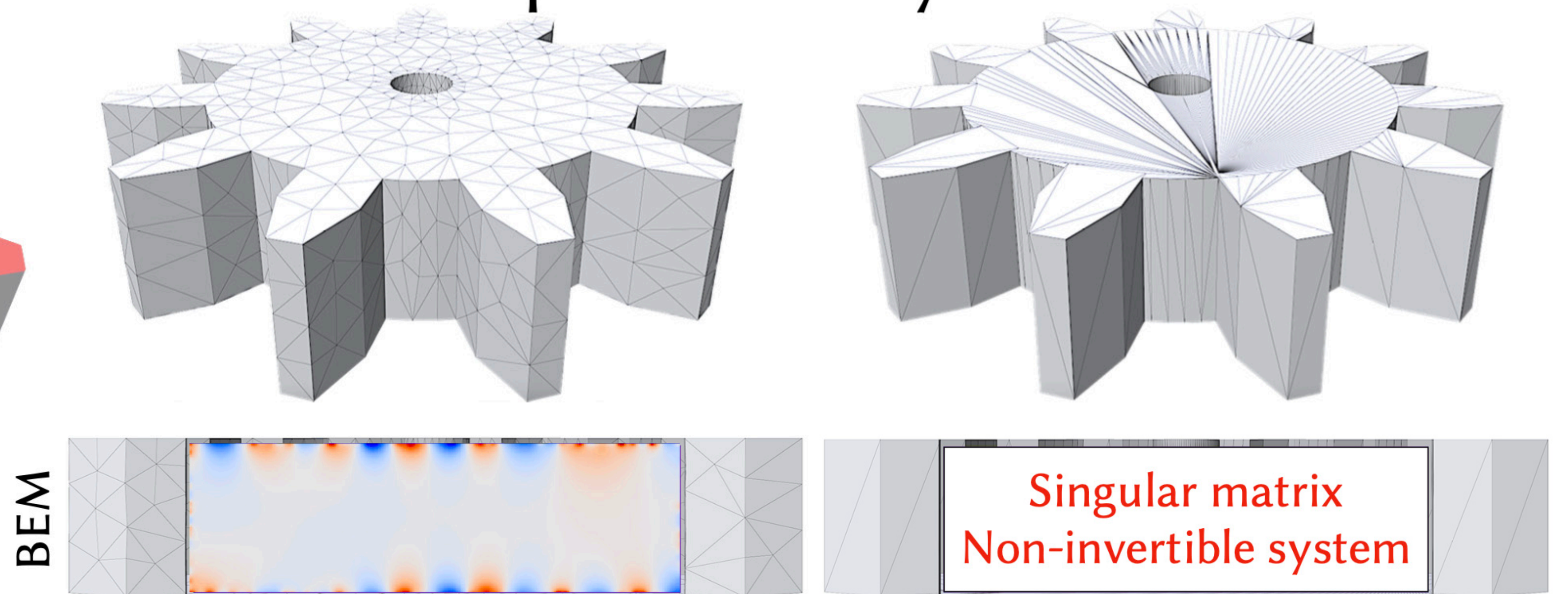
Like WoSt, BVC is **not** affected by quality of discretization

Input boundary conditions



-1  1 Dirichlet  
 0 Neumann

Input boundary mesh



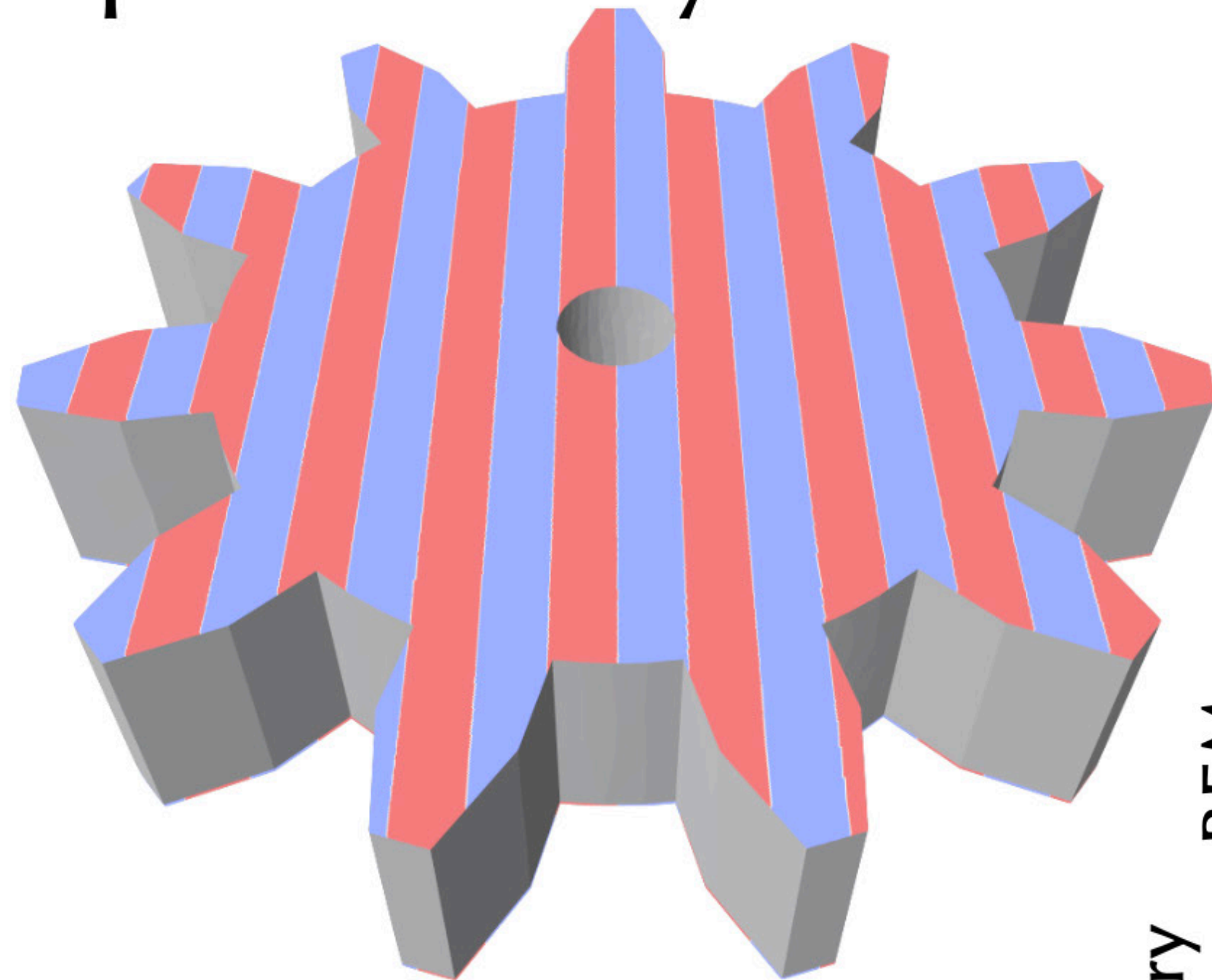
BEM



Singular matrix  
Non-invertible system

# Comparison to Boundary Element Method

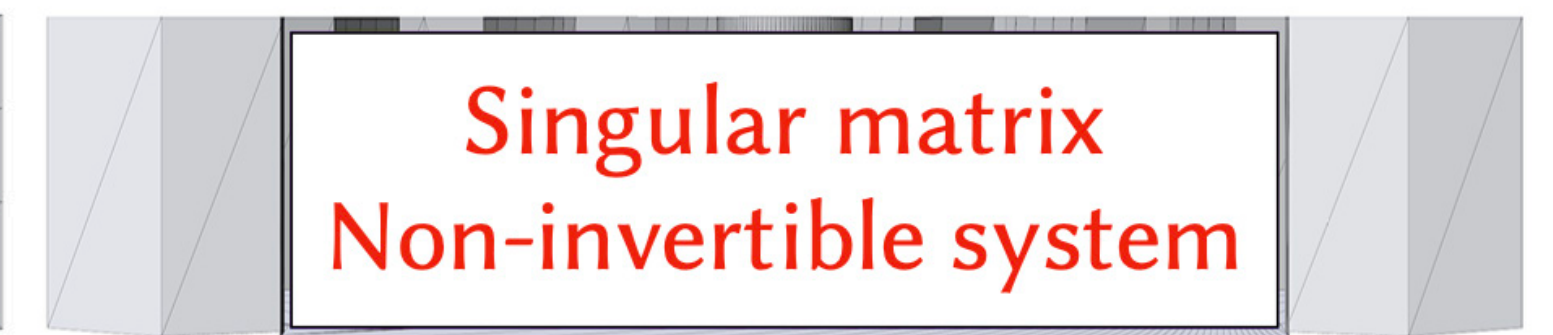
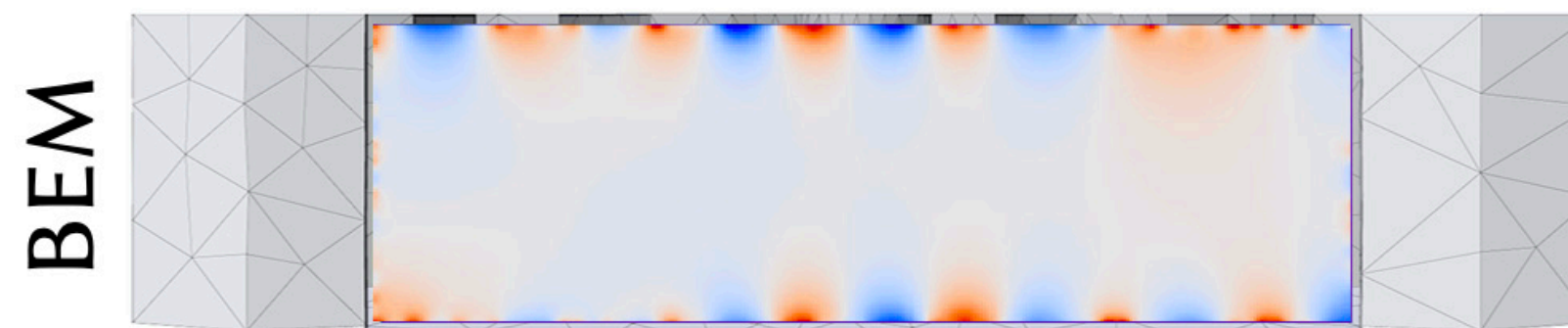
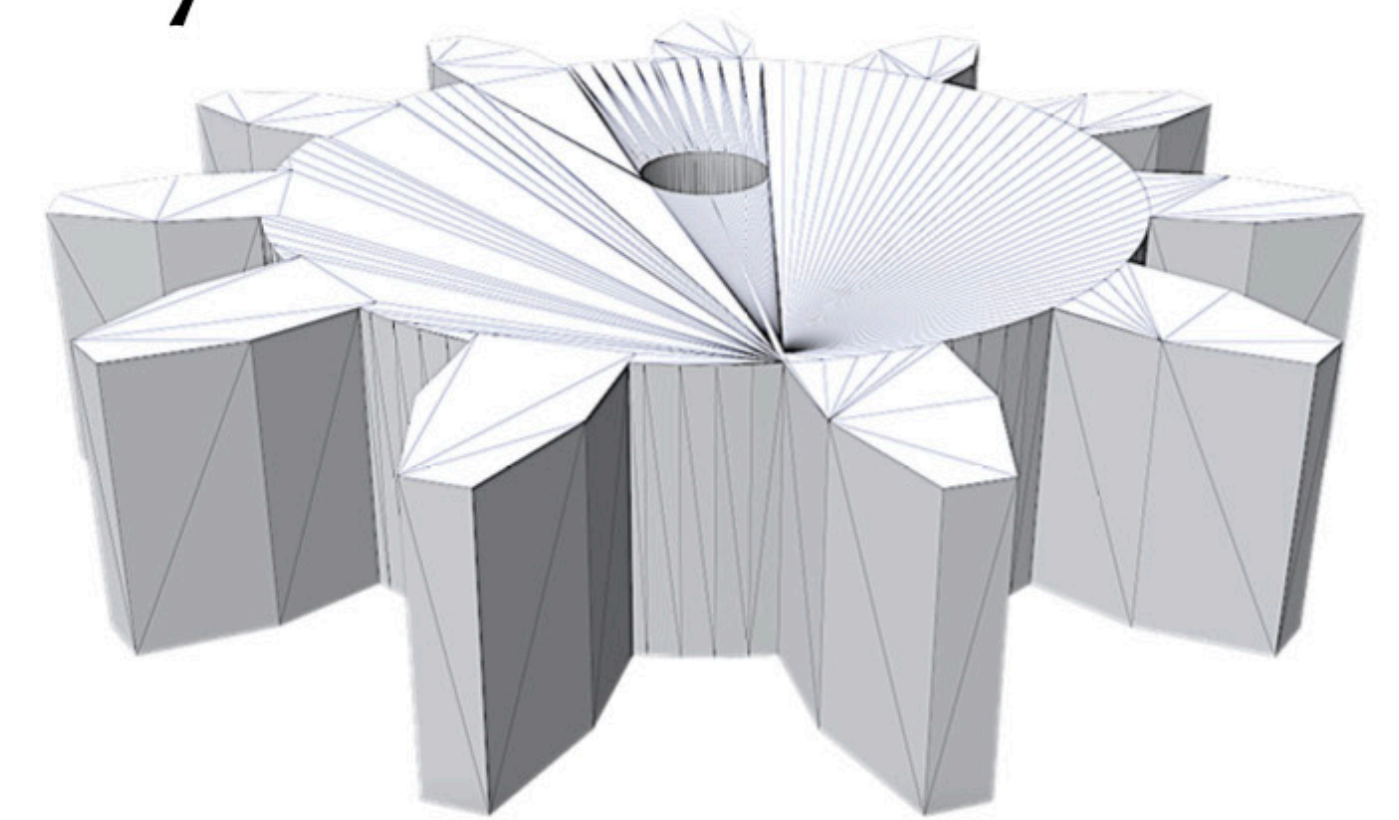
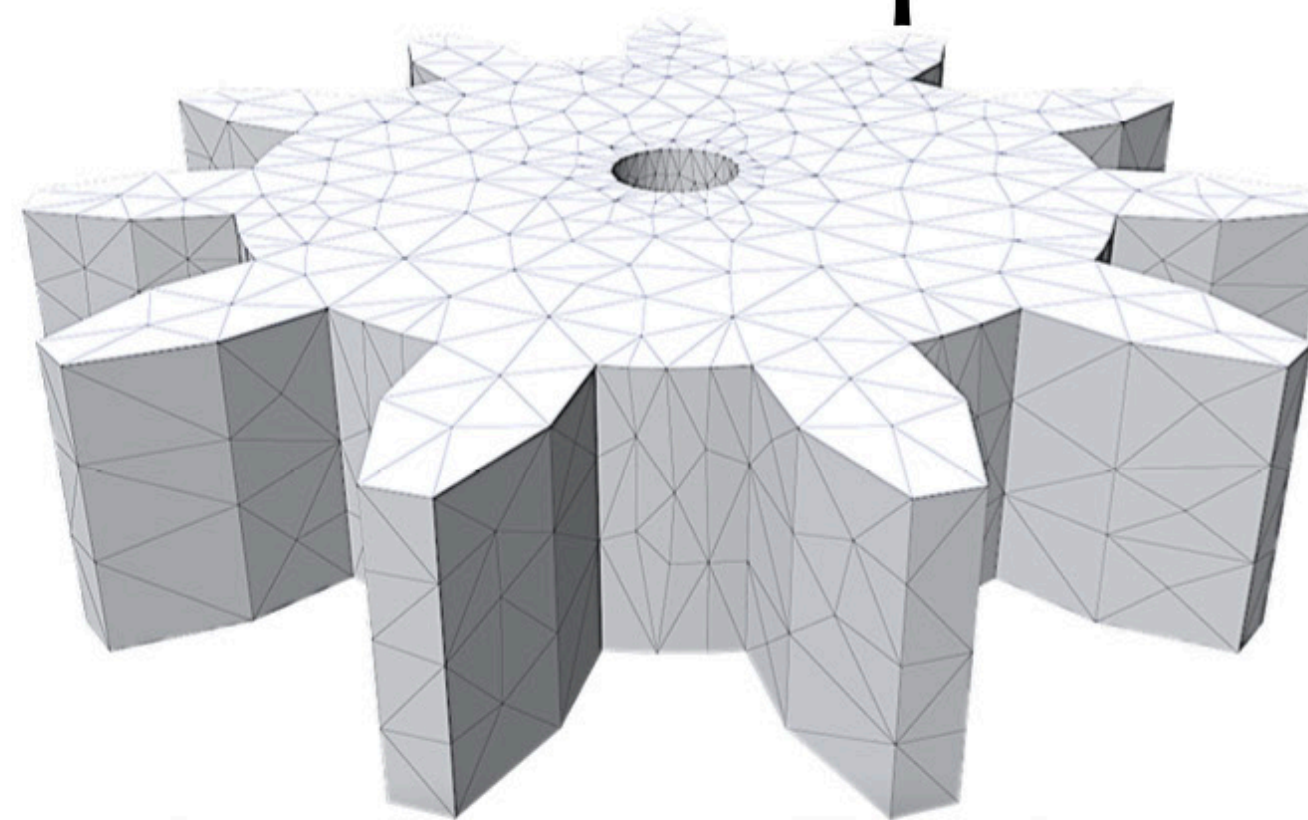
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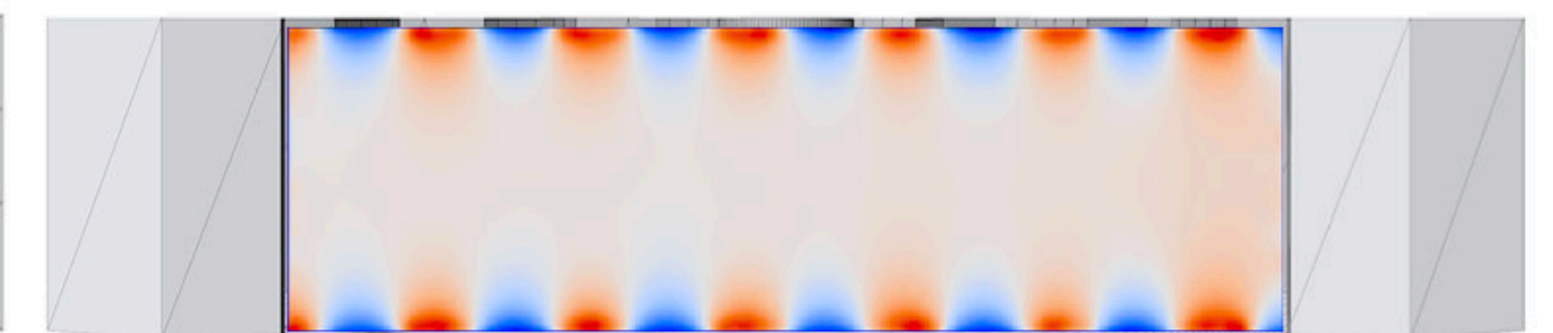
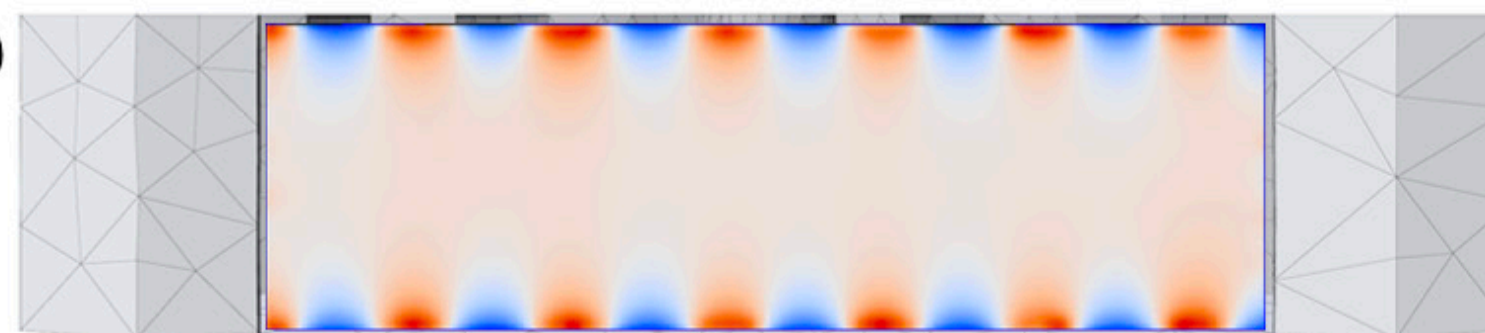


-1  1 Dirichlet  
 0 Neumann

Input boundary mesh

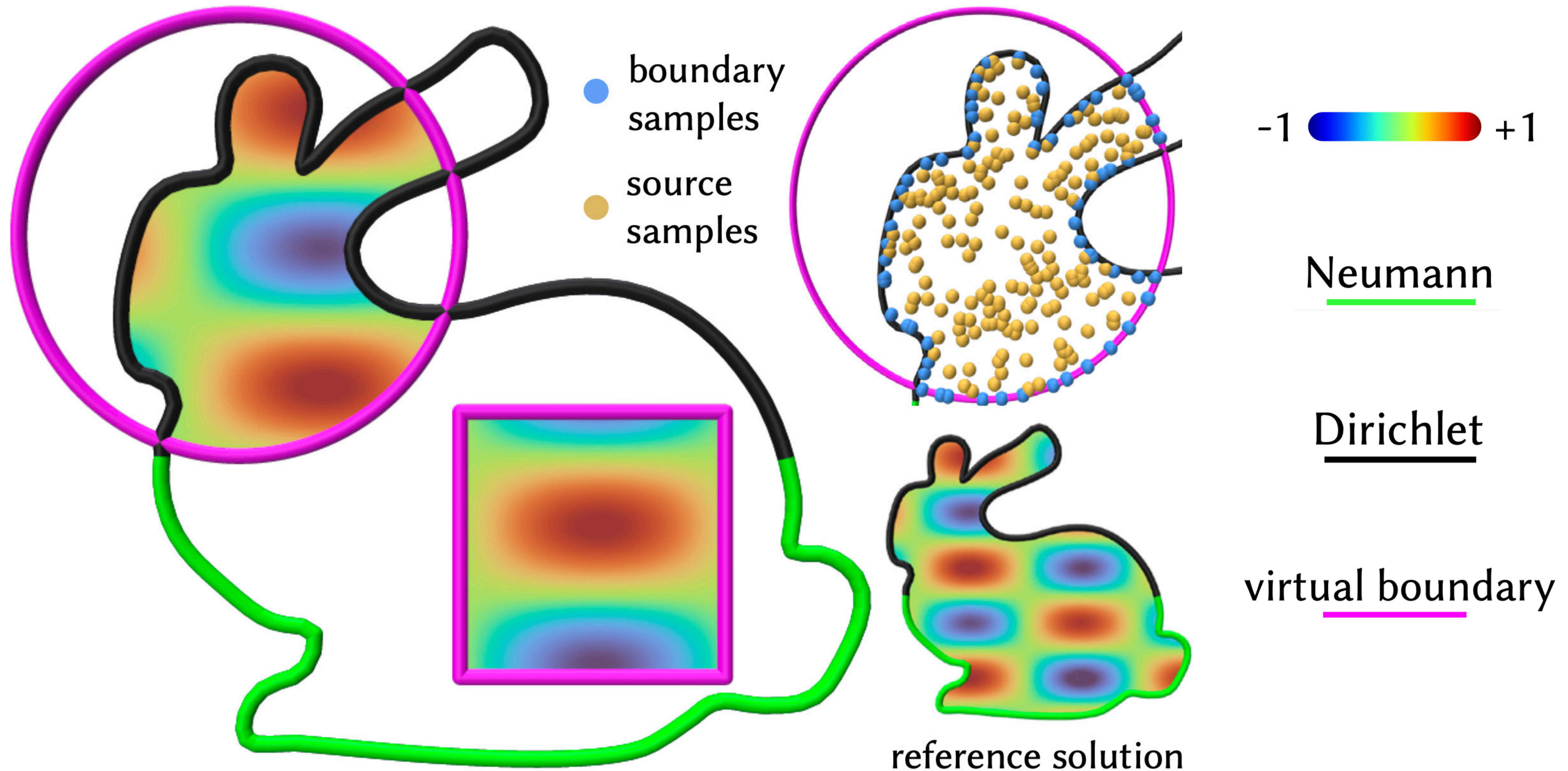


boundary  
caching



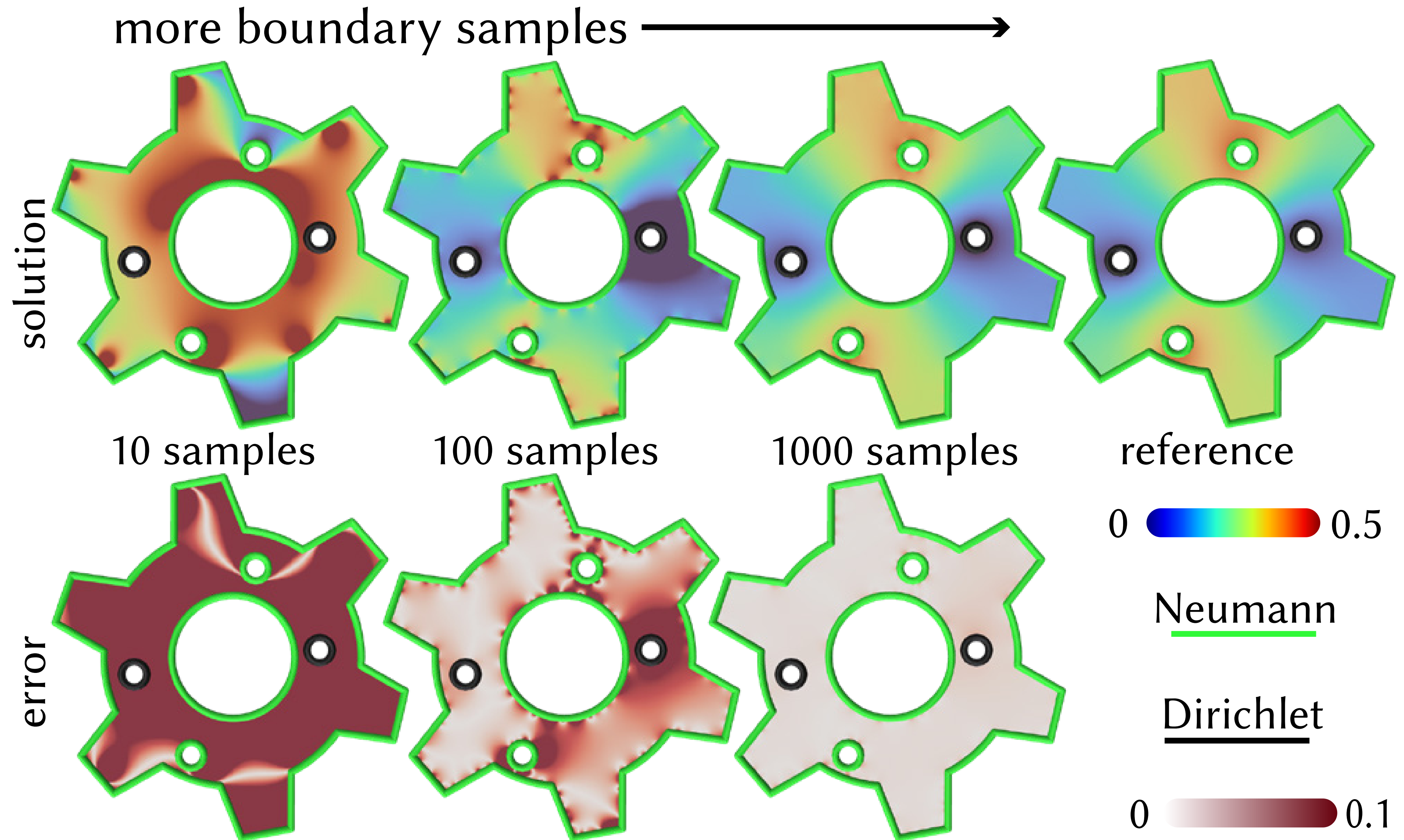
# Output Sensitivity with BVC

Can focus computation in **local regions of interest**



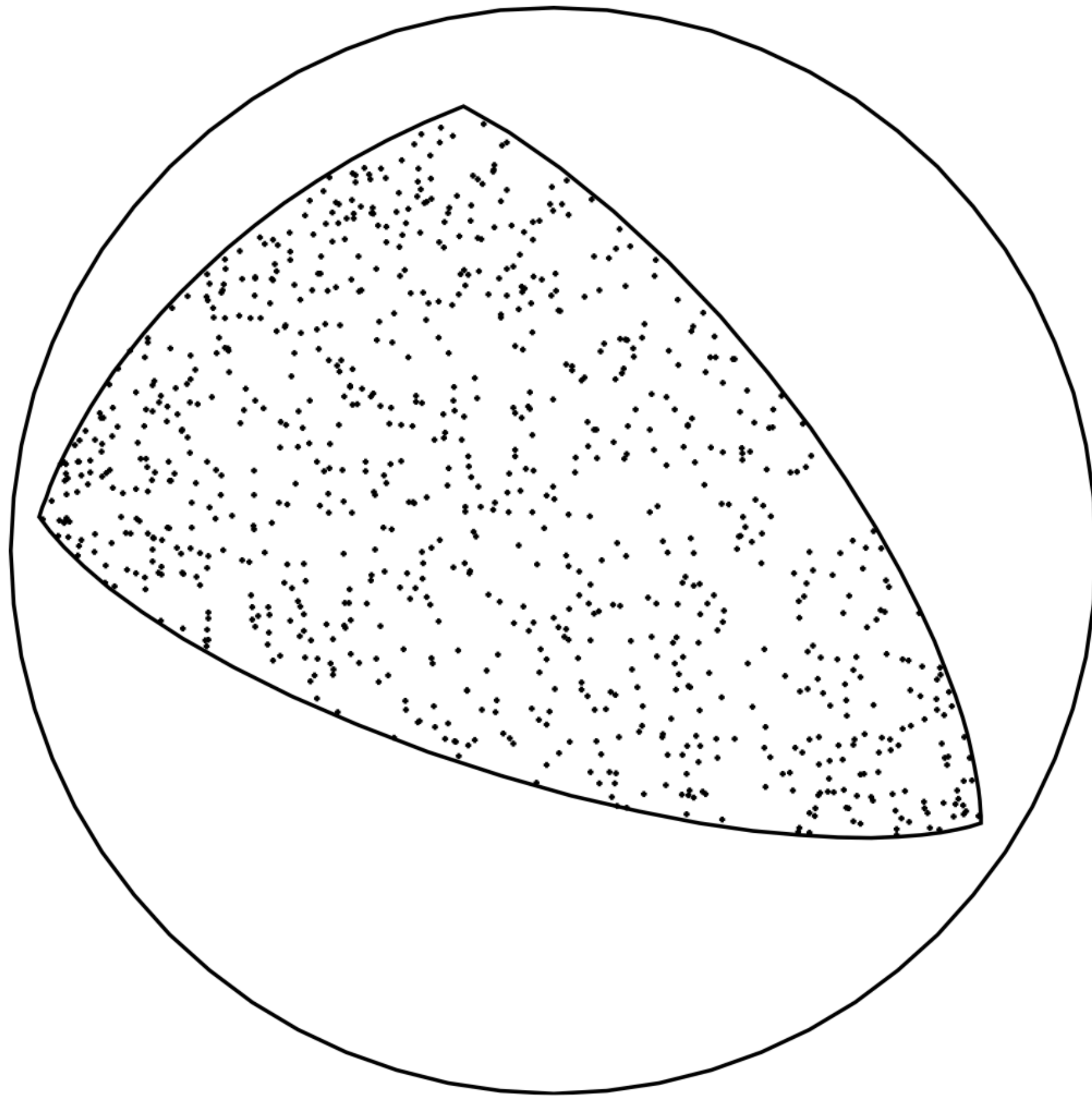


# Error and Convergence



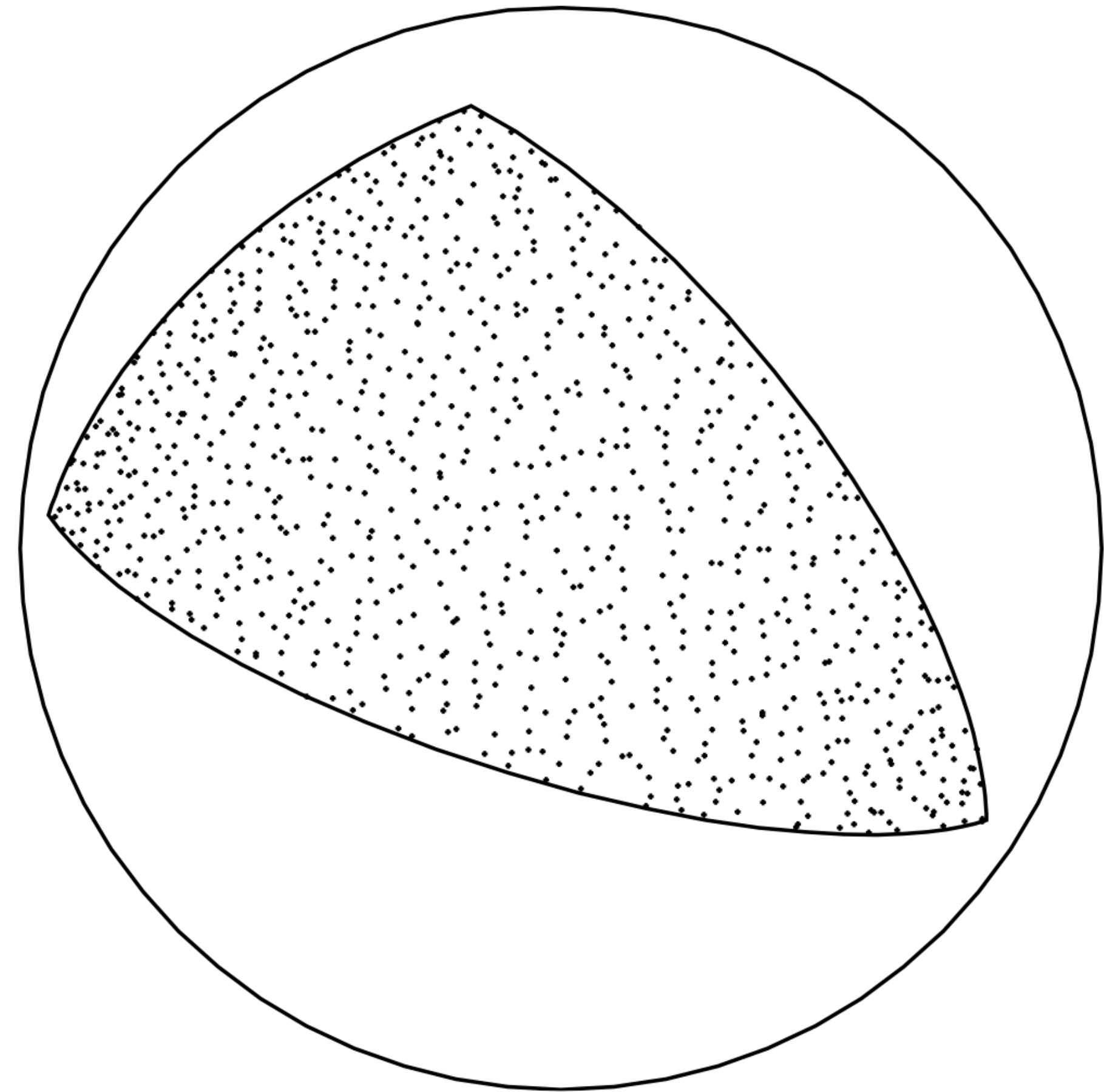
# Stratification

**uniform**



**“more clumpy”**

**stratified**



**“more even”**



# FUTURE WORK

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Any improvements to WoSt benefit BVC!

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Principled approach to estimate  $\frac{du}{dn}$  on  $\partial\Omega_D$

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Reuse information **during** a walk?

# Future Work

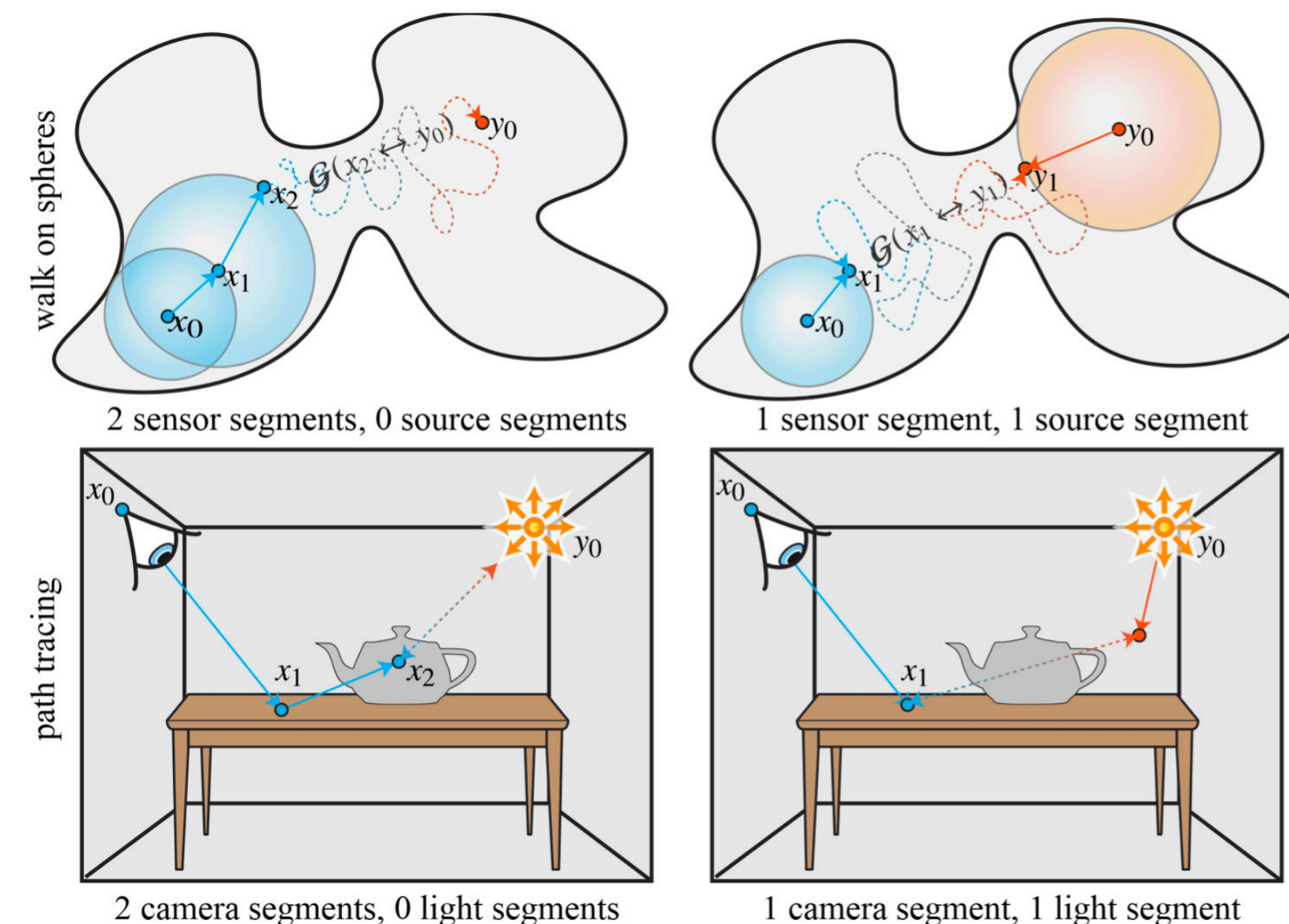
Any improvements to WoSt benefit BVC!

Principled approach to estimate  $\frac{du}{dn}$  on  $\partial\Omega_D$

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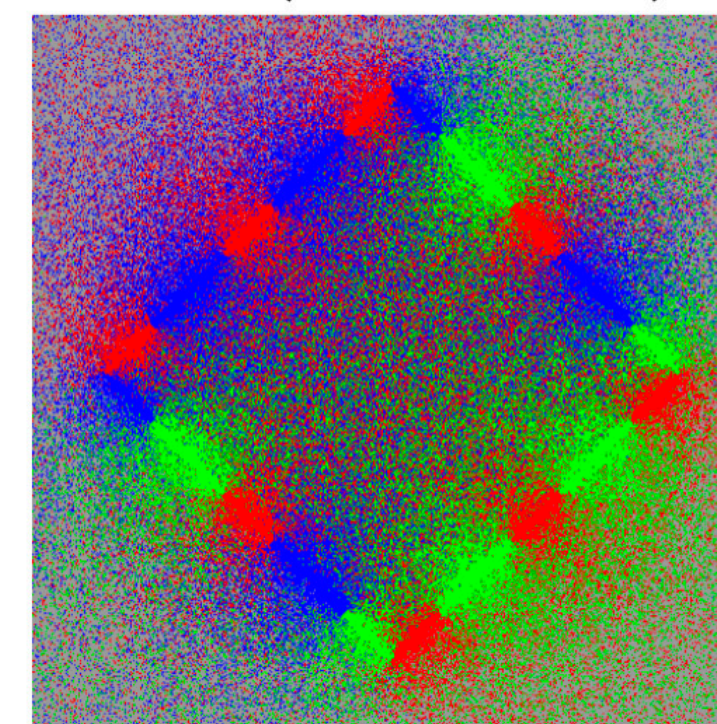
Reuse information **during** a walk?

Unified caching w BVC, MVC, Bidirectional WoS?

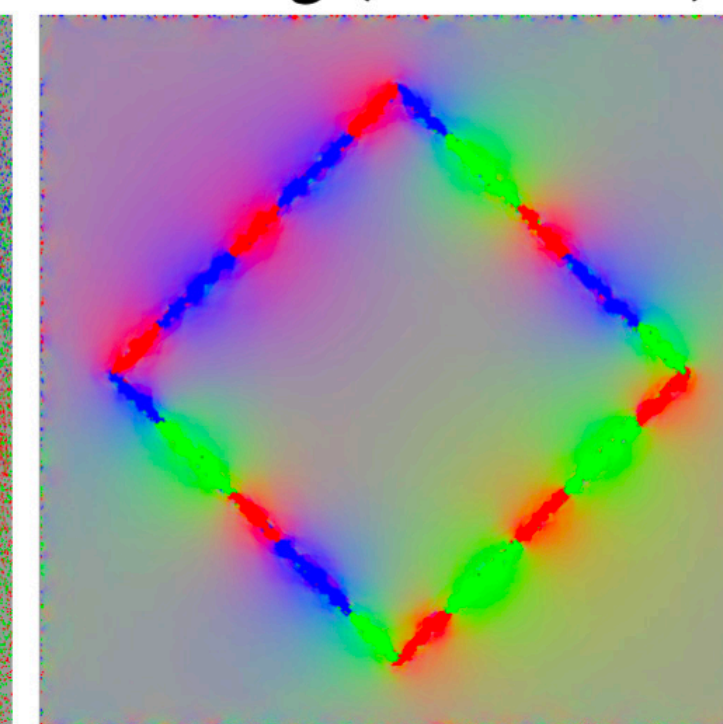


[Qi, Seyb, Bitterli, Jarosz, EGSR 2022]

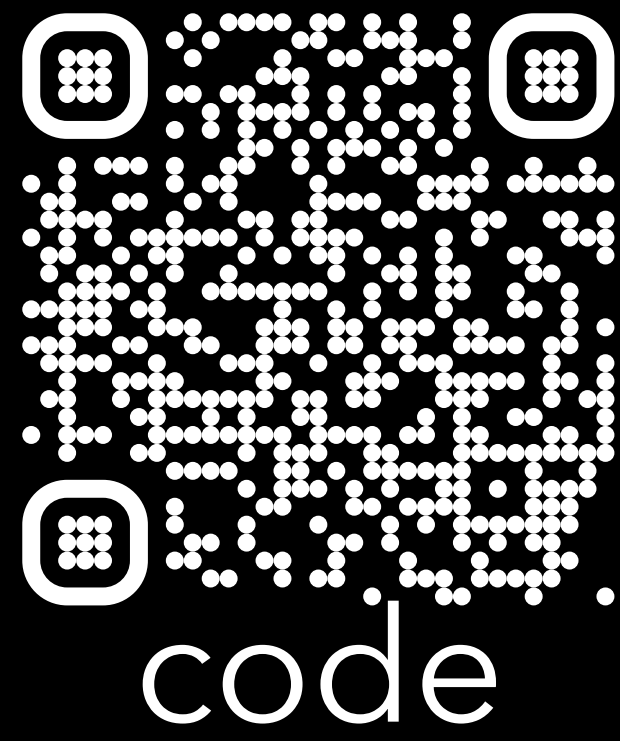
WoS (250K walks)



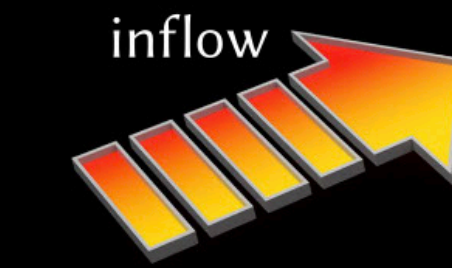
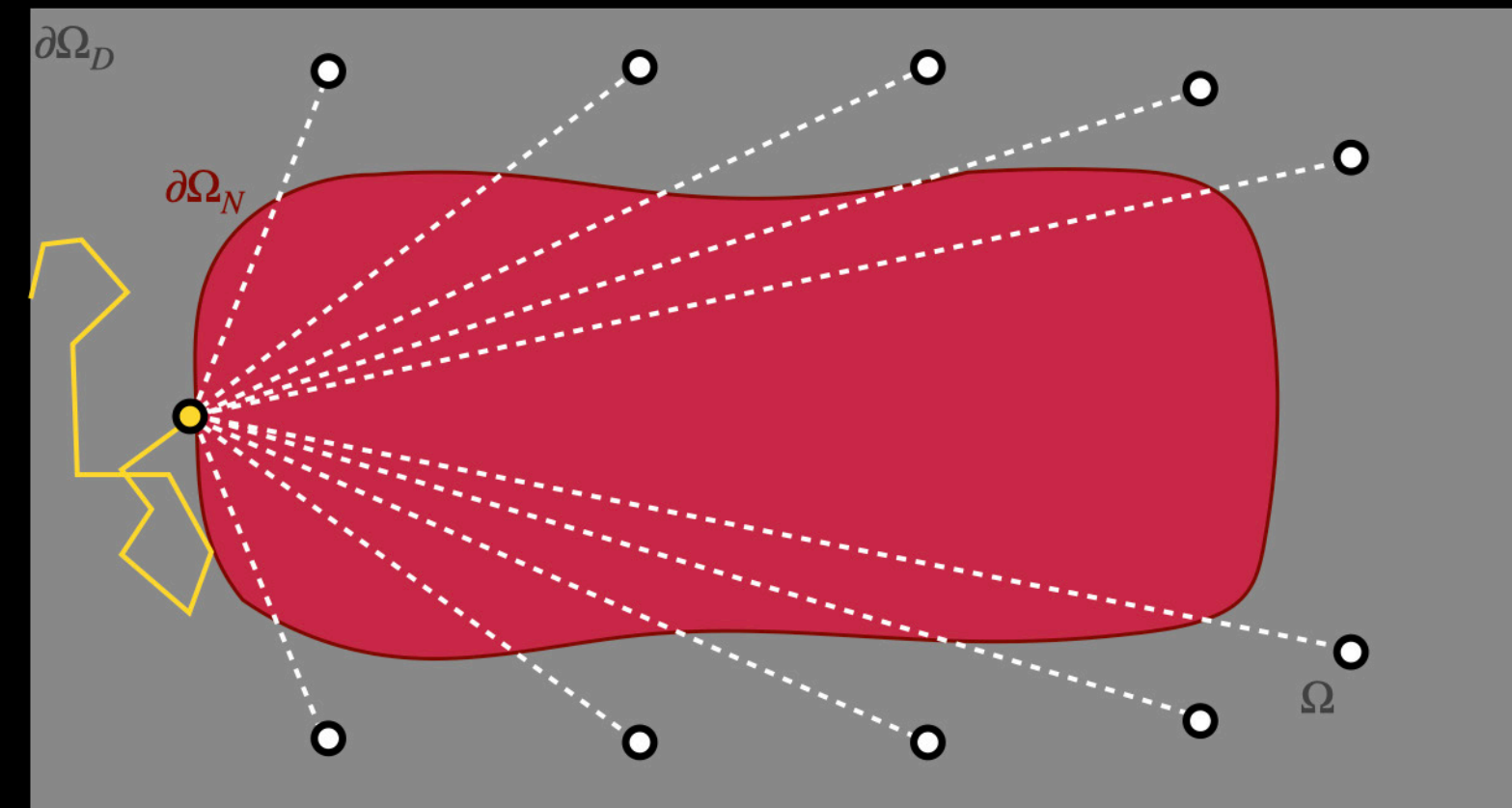
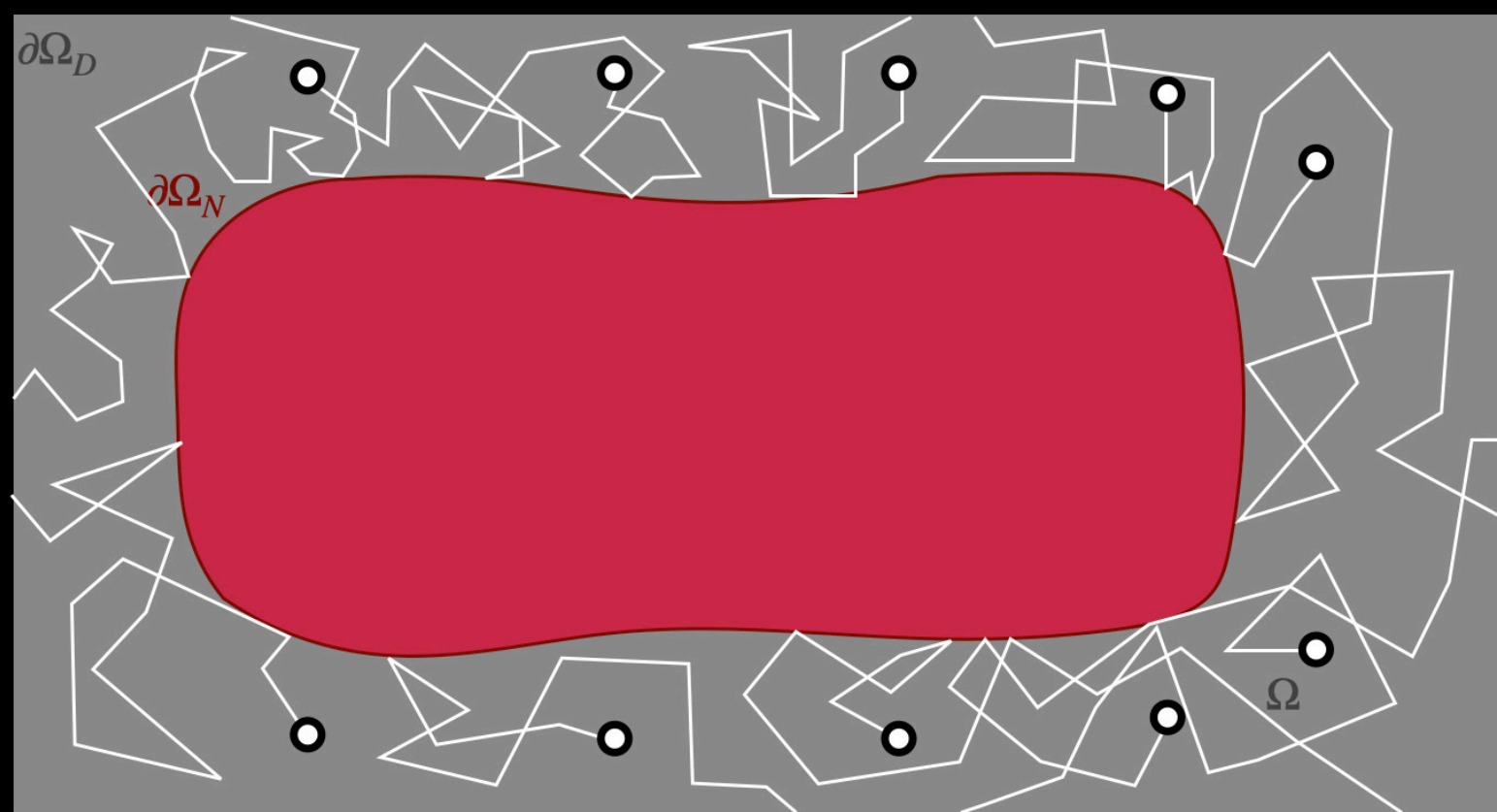
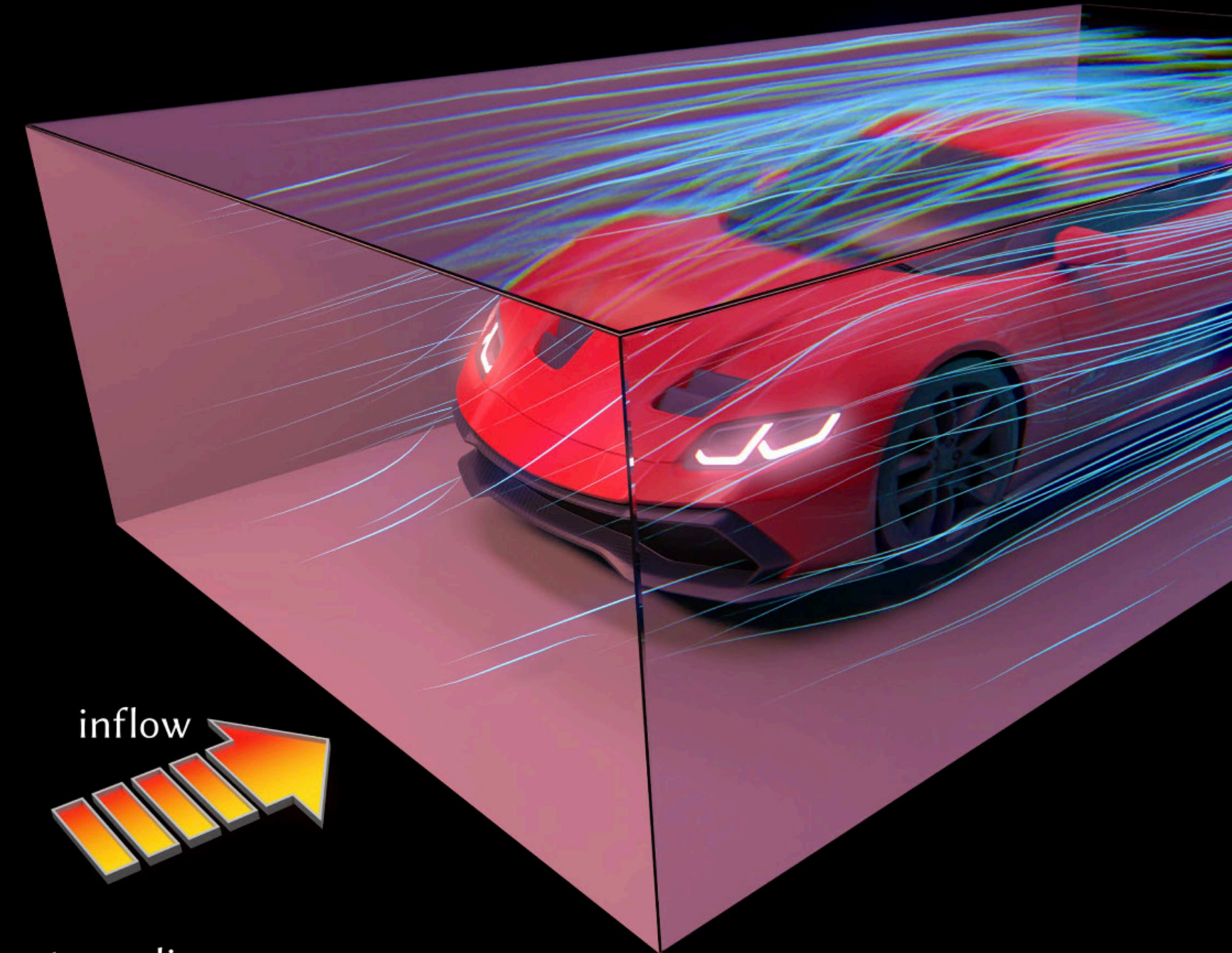
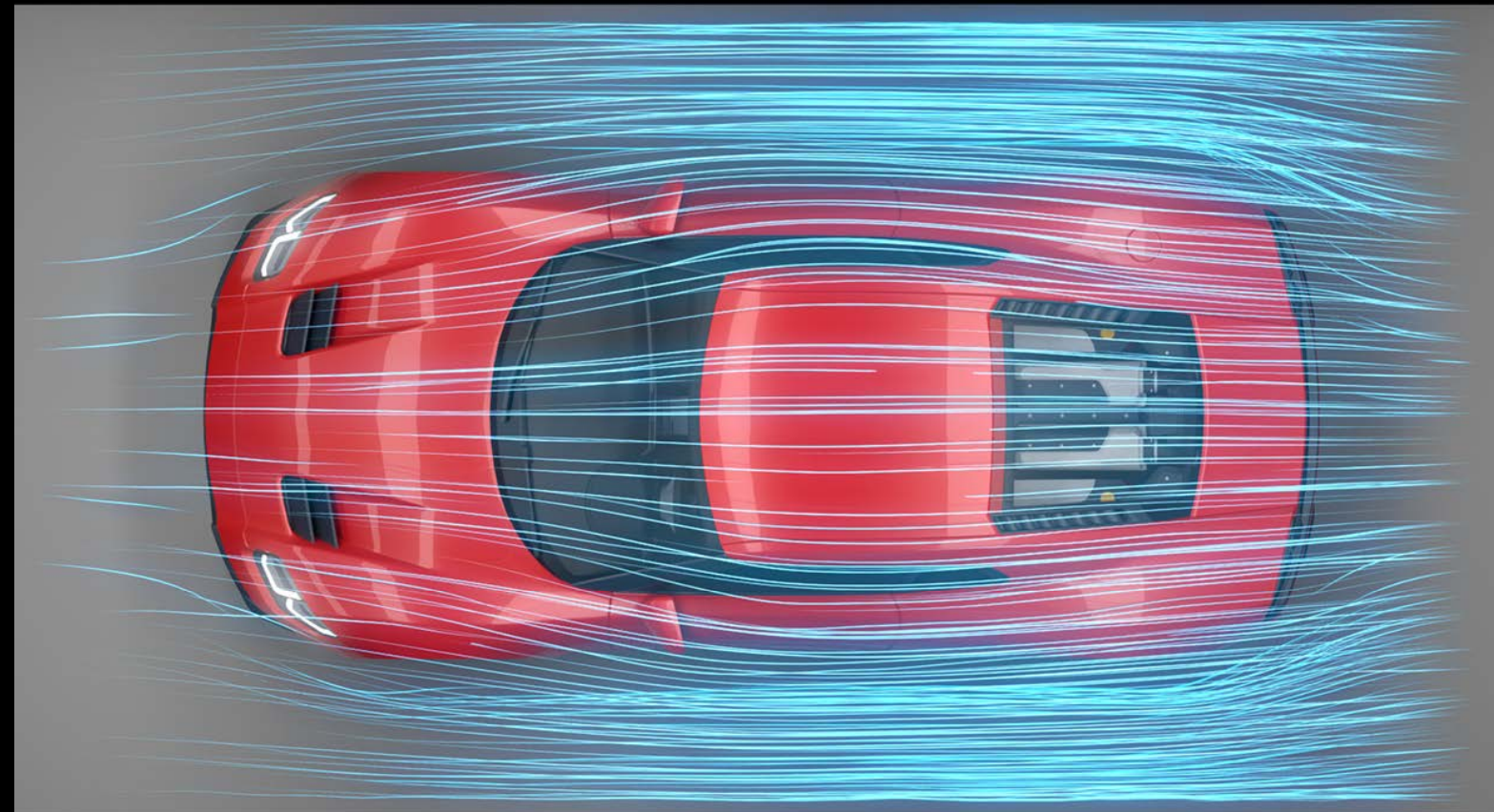
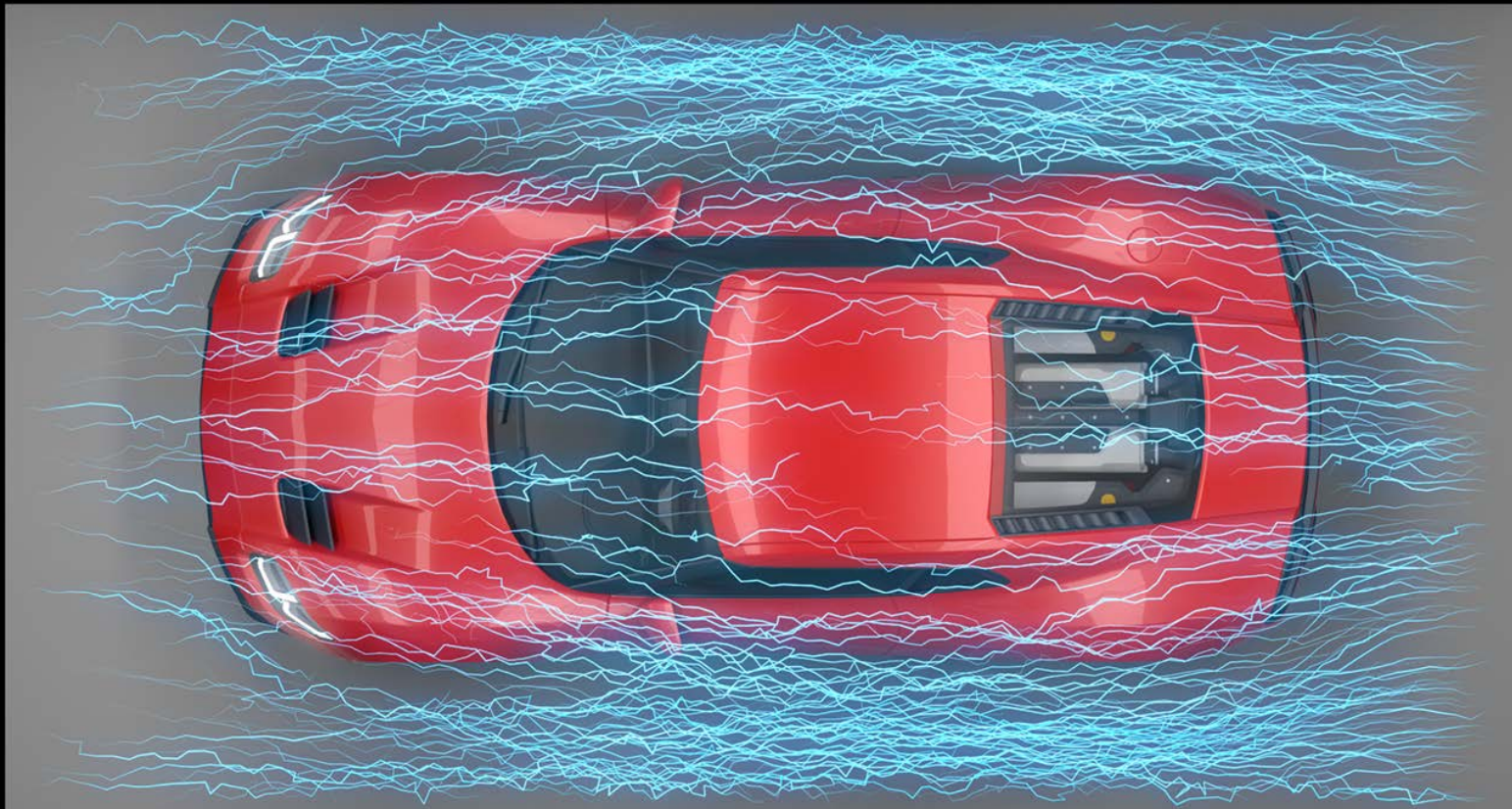
Caching (50K walks)



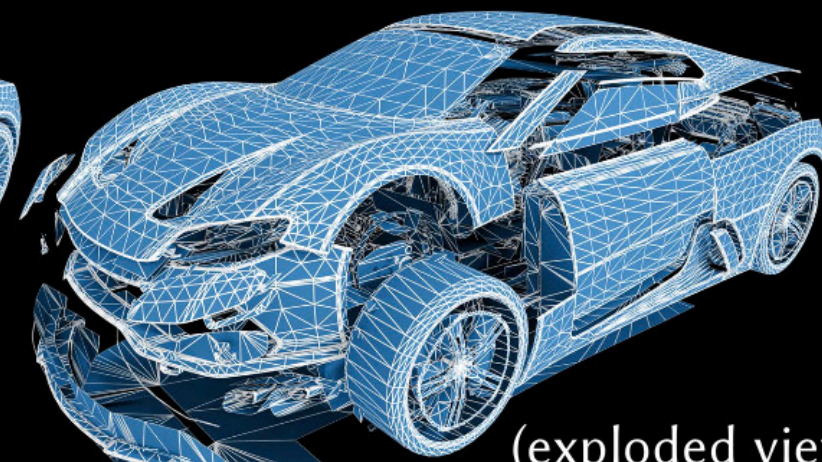
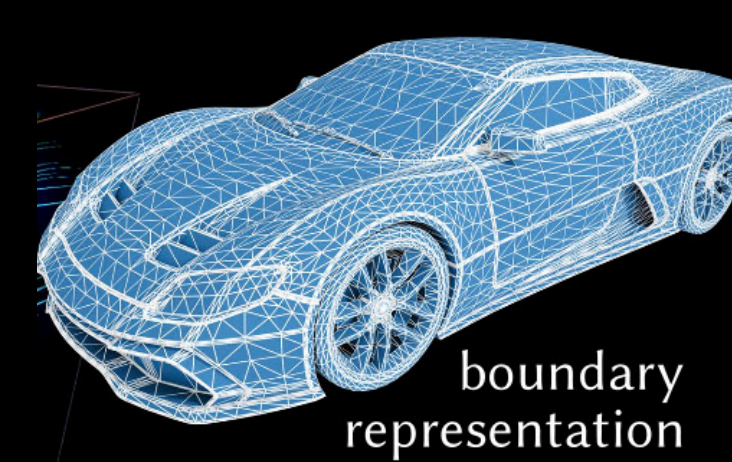
[Bakbouk & Peers, EGSR 2023]



Thank you!



streamline



pointwise

BVC